

Evaluating the MAX14827 with mbed User Guide

UG6248; Rev 0; 3/16

Description

The MAX14827 IO-Link device transceiver/industrial-sensor output driver can be configured and monitored either by setting logic-interface pins (pin-mode) or through an SPI interface (SPI mode). The MAX14827 EV kit is designed to operate as a stand-alone board (for pin-mode evaluation only) or in conjunction with an Arduino[®]-based form-factor ARM[®] mbed[®] board (for either pin-mode or SPI-mode evaluation). Maxim used the STM32 Nucleo-F103R board for GUI development and testing.

Installing the Software

Software for the MAX14827 EV kit can be downloaded from the MAX14827 EV kit Design Resources tab. This zip file contains 2 files: a .bin file, and an .exe file. Click on the .exe file to install the GUI on your PC.

To connect the PC to the mbed board, connect the USB cable from the mbed board to the PC, and copy and paste the .bin file to the mbed drive that appears. This programs the microcontroller on the mbed board.

Once the mbed board is connected and programmed, you can open the MAX14827 EV kit software installed on your PC.

Quick Start

Required Equipment

- Windows[®] 7 and later for PC with a USB Port
- MAX14827EVKIT
- STM32 Nucleo-F103R mbed board or other Arduino form-factor mbed platform
- 24V, 500mA Power Supply
- Oscilloscope

Note: Before connecting the mbed board to the PC, ensure that you have installed the appropriate mbed drivers.

- Download the driver for the mbed board from the mbed website.
- Follow the instructions on the mbed site for installing the drivers.
- Ensure that you have the latest firmware available by following the directions on this page.

Procedure

- 1. Ensure that you have installed the mbed drivers on your PC.
- 2. Ensure that the jumpers on the MAX14827 EV kit are configured as shown in **Table 1**.

JUMPER/S WITCH	SHUNT POSITION/ SETTING	FUNCTION
J1	Open	LED1IN is not pulled high.
J2	Open	UARTSEL is not pulled high.
J3	Open	LED2 is connected to IRQ/OC (not bypassed).
J4	2-3	VL is connected to V33 (VL = 3.3 V)
J5	Open	SDI/RX/NPN jumper is low.
J6	Open	CS/PP jumper is high.
J7	Open	CLK/TXEN/200MA is low.
J8	Open	TXEN is open.
SW1	Position 1 (Far Left)	Internal 5V regulator is used.
SW2	Off (Left)	SPI/ PIN is pulled low.

Table 1. Jumper Settings for mbed Connection

- 3. Connect the MAX14827EVKIT to the mbed platform.
- 4. Connect the positive terminal of the V24 supply source to the V24 test point (TP1). Connect the negative terminal of the V24 supply source to the GND test point (TP18).
- 5. Connect the USB cable from the PC to the mbed board.
- 6. Connect the oscilloscope probes to the C/Q (TP8), DO (TP14), and RX (TP7) test points.
- 7. Turn on the V24 power supply.
- 8. Open the MAX14827 EV kit software installed on your computer. A splash screen appears briefly as the program is started, then disappears.
- 9. Ensure that the GUI shows that both the mbed board and MAX14827 EV Kit board are detected (**Figure 1**).

MAX1 File	4827 EV Kit Options	Software IO Help	O-Link Device Transceiver EV	Kit		9 D			
Regis	ter Settings	5							
[Addresse	DAM	Decister	Volue	Description	Road All	Include Inter	upt Reaist	ter
	0x00	R	INTERRUPT REGISTER	0600000000	Interrupt Register	i Keau Aii	Include I/Os		
	0x01	R	STATUS_REGISTER	0b01000010	Status Register	Write modified			
	0x02	R/W	MODE_REGISTER	0600000000	Mode Register		_		
	0x03	R/W	CURRLIM_REGISTER	0b0000000	Current Limit Register	MAX14827 I/O Pin	s		
	0x04	R/W	CQConfig_REGISTER	0b0000001	C/Q Config Register	Name	Set Function	Read	Direction
	0x05	R/W	DIOConfig_REGISTER	0b0000001	DI / DO Config Register	SPI / PIN	SPI / PIN	1	IN
						UARTSEL	UARTSEL	0	IN
	Bit	Value	Settin	9	Description	Chip Mode	SPI and UART, Ind	ependent	
	B[7]	060	0: No Interrupt		Interrupt: Thermal Shutdown	TXEN	TXEN	0	IN
	B[6]	060	0: No Interrupt		Interrupt: IO-Link Wake-Up Condition	ТХ		0	IN
	B[5]	060	0: No Interrupt		Interrupt: DO-Driver Overload	RX	RX	1	OUT
	B[4]	060	0: No Interrupt		Interrupt: C/Q-Driver Overload	. u	L	1	OUT
	B[3]	060	0: No Interrupt		Interrupt: V24 Below 16V	LO	LO	0	IN
	B[2]	060	0: No Interrupt		Interrupt: V24 Below Undervoltage TH		~		
	B[1]	0b0	0: No Interrupt		Interrupt: DO Temperature Warning	LED1N	LED1N	0	IN
	B[0]	060	0: No Interrupt		Interrupt: C/Q Temperature Warning	CSB / PP	CS	N/A	IN
1	Note: To edi	t the value	of a R/W register, click on the	Value cell.		SDI/TX/NPN	SDI	N/A	OUT
						CLK / TXEN	CLK	N/A	IN
						SDO/RX/THSH	SDO	N/A	IN
							IRQ / OCB	1	OUT
							WU	1	OUT
									Read All
ice: I	/AX14827				EV Kit Software Version 1.00, FW Version 1.00		MAX	14827EV	KIT on mbed and Connected

Figure 1. MAX14827 EV kit startup screen.

10. Click on the SPI/PIN switch to move it to the left and put the device in pin-mode. Click on the Read All button in the MAX14827 IO Pins section to verify that the pin setting has been changed.

Note: In this mode the register block are greyed out and the inputs are controlled using the switches in the MAX14827 IO Pins section on the right.

- 11. Click on the LO switch and verify that DO switches are expected.
- 12. Click on the TXEN switch so that it moves to the right.
- 13. Click on the TX switch and verify that C/Q and RX move as expected.

Operating in Pin-Mode

To operate the MAX14827 EV kit in pin-mode, set the mode selection switch (SW2) to the OFF, or left, position. When connected to the mbed board, SPI/PIN switch in the MAX14827 IO Pins section must also be set to the left. In this position, the SPI/PIN input is pulled low.

When operating in pin-mode, the C/Q and DO output modes are changed simultaneously by setting the CS/PP, SDI/TX/NPN or SDO/RX/200MA pins high or low. The DO output cannot be disabled in pin-mode, but C/Q can be configured as either a driver output or receiver input by setting the TXEN pin.

Each input is configured with a switch on the GUI in the MAX14827 I/O Pins section (**Figure 2**). The function for each pin is listed next to the switch. Click on the switch to change the setting. When a switch is set to the left, the corresponding pin is set low and the Read box is '0'. When a switch is set to the right, the corresponding pin is set high and the Read box next to it is '1.' Note that outputs do not have switches, but do have Read boxes for quick visual validation.

See Tables 1-3 in the MAX14827 IC data sheet for detailed information on configuring and setting the C/Q and DO drivers and LED output in pin-mode.



Figure 2. MAX14827 I/O pins section for Pin-Mode Control on the GUI.

Operating in SPI Mode

To operate the MAX14827 EV kit in SPI mode, ensure that SW2 is in the OFF position and set the SPI/PIN switch in the MAX14827 IO Pins section to the right. This pulls the SPI/PIN input high and sets the device in SPI mode. Click on the Read All button in the MAX14827 I/O Pins section to ensure that the change is validated.

When operating the MAX14827 in SPI mode, the C/Q and DO outputs can be independently monitored and configured. See the MAX14827 data sheet for more detailed information about setting/reading the SPI registers and configuration bits.

After setting the device in SPI mode, it is a good idea to check the "Include Interrupt Register" check box in the upper right side of the GUI, and to click on the Read All button near the top of the Register list. Both C/Q and DO should be disabled when SPI mode is entered (after power up) and the register list should look as shown in **Figure 3**.

Address	R/W	Register	Value	Description	Read All	Include Interre	Include Interrupt Register				
x00	R	INTERRUPT_REGISTER	060000000	Interrupt Register		Include I/Os					
x01	R	STATUS_REGISTER	0b01000010	Status Register	Write modified						
x02	R/W	MODE_REGISTER	060000000	Mode Register							
x03	R/W	CURRLIM_REGISTER	060000000	Current Limit Register	MAX14827 I/O Pins						
x04	R/W	CQConfig_REGISTER	0b0000001	C/Q Config Register	Name	Set Function	Read	Direction			
x05	R/W	DIOConfig_REGISTER	0b0000001	DI / DO Config Register	SPI / PIN	SPI / PIN	1	IN			
					UARTSEL	UARTSEL	0	IN			
Bit	Value	Settin	g	Description	Chip Mode	SPI and UART, Inde	pendent				
3[7]	0b0	0: No Interrupt		Interrupt: Thermal Shutdown	TXEN	TXEN	0	IN			
8[6]	0b0	0: No Interrupt		Interrupt: IO-Link Wake-Up Conditi	on	ТХ	0	IN			
8[5]	0b0	0: No Interrupt		Interrupt: DO-Driver Overload	RX	BX	1	OUT			
8[4]	0b0	0: No Interrupt		Interrupt: C/Q-Driver Overload		10	1	OUT			
8[3]	0b0	0: No Interrupt		Interrupt: V24 Below 16V	10	10	0	IN			
8[2]	0b0	0: No Interrupt		Interrupt: V24 Below Undervoltage	тн						
8[1]	0b0	0: No Interrupt		Interrupt: DO Temperature Warnin	LED1N	LED1N	0	IN			
8[0]	0b0	0: No Interrupt		Interrupt: C/Q Temperature Warnin	g CSB/PP	CS	N/A	IN			
ote: To ed	it the value	of a RW register click on the	Value cell		SDI/TX/NPN	SDI	N/A	OUT			
		or a rear regional, and car are	Value con.		CLK / TXEN	CLK	N/A	IN			
					SDO/RX/THSH	SDO	N/A	IN			
						IRQ / OCB	1	OUT			
						M/L	4	OUT			

Figure 3. SPI Mode default configuration after power-up.

To set a bit (or bits) in the registers:

- 1. Click on the Register in the register list box at the top.
- 2. Click on the bit to set and select the setting from the drop-down menu.
- 3. Click on the Write Modified button to set the registers as desired.

The following example shows this process. In this example, the C/Q output is enabled and set to pushpull mode.

1. Click on the C/Q Config Register in the register list (**Figure 4**).

Addres	s R/W	Register	Value		Description	Read All	Inc	lude Interru	ipt Regis	ter
)x00	R	INTERRUPT_REGISTER	060000000	Interrup	ot Register		 Inc 	lude I/Os		
)x01	R	STATUS_REGISTER	0b01000010	Status	Register	Write modified				
)x02	R/W	MODE_REGISTER	0b0000000	Mode F	Register					
)x03	R/W	CURRLIM_REGISTER	0b0000000	Curren	t Limit Register	MAX14827 I/O Pins				
)x04	R/W	CQConfig_REGISTER	0b00000001	C/Q Co	nfig Register	Name	Set	Function	Read	Direction
)x05	R/W	DIOConfig_REGISTER	0b0000001	DI/DO	Config Register	SPI / PIN		SPI / PIN	1	IN
						UARTSEL	\bigcirc	JARTSEL	0	IN
Bit	Value	Setting			Description	Chip Mode	SPI and	UART, Inde	pendent	
3[7]	0b0	0: Disable 🗸 🗸			Rx Receiver Disable	TXEN	\bigcirc	TXEN	0	IN
3[6]	0b0	0: Disable 🗸			C/Q Weak Pull-Down	TX	$\tilde{\mathbf{O}}$	TX	0	IN
3[5]	0b0	0: Disable 🗸 🗸			C/Q Weak Pull-Up	RX		RX	1	OUT
8[4]	0b0	0: Disable 💌			C/Q and DO Outputs Tracking	U		LI	1	OUT
9[3]	0b0	0: Disable		-	C/Q NPN operation	LO	\bigcirc	LO	0	IN
3[2]	0b0	0: Disable		•	C/Q Push-Pull Mode		~			
8[1]	0b0	0: Disable		-	Drive C/Q to V24	LED1N		LED1N	0	IN
3[0]	0b1	1: Enable		-	C/Q Driver Tristate	CSB / PP		CS	N/A	IN
ote: To ec	dit the value	of a R/W register, click on the	Value cell.		-	SDI/TX/NPN		SDI	N/A	OUT
						CLK / TXEN		CLK	N/A	IN
						SD0/RX/THSH		SDO	N/A	IN
								RQ/OCB	1	OUT
								wu	1	OUT

Figure 4. Selecting the C/Q Register in the register list.

2. Click on the B[0] bit row to select the 0: Disable setting for the C/Q Driver Tristate bit (**Figure 5**). Setting this bit to 0 disables the tristate setting (enabling the driver output).

Address	R/W	Register	Value		Description	Read All	Include Interrupt Register				
0x00	R	INTERRUPT_REGISTER	060000000	Interrup	t Register		🗸 li	nclude I/Os			
0x01	R	STATUS_REGISTER	0b01000010	Status I	Register	Write modified					
0x02	R/W	MODE_REGISTER	0b0000000	Mode R	legister						
0x03	R/W	CURRLIM_REGISTER	0b0000000	Current	Limit Register	MAX14827 I/O Pins					
0x04	R/W	CQConfig_REGISTER	0b00000001	C/Q Co	nfig Register	Name	Set	Function	Read	Direction	
0x05	R/W	DIOConfig_REGISTER	0b0000001	DI/DO	Config Register	SPI / PIN		SPI / PIN	1	IN	
						UARTSEL	\bigcirc	UARTSEL	0	IN	
Bit	Value	Settin	g		Description	Chip Mode	SPI and	d UART, Inde	pendent		
3[7])b0	0: Disable			Rx Receiver Disable	TXEN	\bigcirc	TXEN	0	IN	
3[6]	0b0	0: Disable			C/Q Weak Pull-Down	ТХ		TX	0	IN	
3(5))60	0: Disable			C/Q Weak Pull-Up	RX		RX	1	OUT	
3[4]	060	0: Disable			C/Q and DO Outputs Tracking			11	1	OUT	
3[3]	060	0: Disable		-	C/Q NPN operation	10	\bigcirc	10	0	IN	
3[2]	060	0: Disable		-	C/Q Push-Pull Mode				-		
3[1]	0b0	0: Disable		-	Drive C/Q to V24	LED1N	\bigcirc	LED1N	0	IN	
3[0])b1	1: Enable		-	C/Q Driver Tristate	CSB / PP		CS	N/A	IN	
ote: To edi	the value	0: Disable			K	SDI / TX / NPN		SDI	N/A	OUT	
010. 10 00.		1: Enable				CLK / TXEN		CLK	N/A	IN	
						SDO / RX / THSH		SDO	N/A	IN	
								IRQ / OCB	1	OUT	
								WU	1	OUT	
										001	

Figure 5. Setting the C/Q Driver Tristate Bit in the C/Q Config Register.

3. Click on the B[2] bit row to select the 1: Enable setting for the C/Q Push-Pull Mode bit (**Figure 6**). Setting this bit enables push-pull mode for the C/Q driver.

Addres	s R/W	Register	Value		Description	Read All	_ √ I	Include Interrupt Register				
)x00	R	INTERRUPT_REGISTER	060000000	Interrup	ot Register		Include I/Os					
)x01	R	STATUS_REGISTER	0b01000010	Status I	Register	Write modified						
)x02	R/W	MODE_REGISTER	0b0000000	Mode R	Register							
)x03	R/W	CURRLIM_REGISTER	0b0000000	Current	t Limit Register	MAX14827 I/O Pins						
)x04	R/W	CQConfig_REGISTER	0600000000	C/Q Co	nfig Register	Name	Set	Function	Read	Direction		
)x05	R/W	DIOConfig_REGISTER	0b0000001	DI/DO	Config Register	SPI / PIN		SPI / PIN	1	IN		
						UARTSEL	\bigcirc	UARTSEL	0	IN		
Bit	Value	Settin	g		Description	Chip Mode	SPI an	d UART, Inde	pendent			
3[7]	0b0	0: Disable			Rx Receiver Disable	TXEN	\bigcirc	TXEN	0	IN		
8[6]	0b0	0: Disable			C/Q Weak Pull-Down	TX		TX	0	IN		
3[5]	0b0	0: Disable			C/Q Weak Pull-Up	PY		DY DY	1	OUT		
3[4]	0b0	0: Disable			C/Q and DO Outputs Tracking			11	1			
9[3]	0b0	0: Disable		-	C/Q NPN operation		\bigcirc	10	0	IN		
3[2]	0b0	0: Disable		-	C/Q Push-Pull Mode			20	•			
9[1]	0b0	0: Disable			Deve C/Q to V24	LED1N	\bigcirc	LED1N	0	IN		
3[0]	0b0	0: Disable		-	C/Q Driver Tristate	CSB / PP		CS	N/A	IN		
ote: To er	dit the value	of a RM register click on the			1	SDI/TX/NPN		SDI	N/A	OUT		
016. 10 61		or a row register, click on are	value cell.			CLK / TXEN		CLK	N/A	IN		
						SDO / RX / THSH		SDO	N/A	IN		
								IRO / OCB	1	OUT		
								WU	1	OUT		
								**0		001		

Figure 6. Setting the C/Q Push-Pull Mode Bit in the C/Q Config Register.

4. Click on the Write Modified button to write the register changes to the MAX14827 (**Figure 7** and **Figure 8**).

Addres	R/W	Register	Value		Description	Read All	ad All 🗹 Include Interrupt Register 🗸 Include I/Os					
0x00	R	INTERRUPT_REGISTER	0b0000000	Interrup	ot Register							
0x01	R	STATUS_REGISTER	0b01000010	Status	Register	Write modified	-					
0x02	R/W	MODE_REGISTER	0b0000000	Mode F	Register							
0x03	R/W	CURRLIM_REGISTER	0b0000000	Curren	t Limit Register	MAX14827 I/O Pins						
0x04	R/W	CQConfig_REGISTER	0b00000100	C/Q Co	nfig Register	Name	Set	Function	Read	Direction		
0x05	R/W	DIOConfig_REGISTER	0b0000001	DI/DO	Config Register	SPI/PIN (SPI / PIN	1	IN		
						UARTSEL	\bigcirc	UARTSEL	0	IN		
Bit	Value	Settin	g		Description	Chip Mode	SPI and					
B[7]	060	0: Disable			Rx Receiver Disable	TXEN	\sim	TXEN	0	IN		
B[6]	0b0	0: Disable			C/Q Weak Pull-Down	TX		TY	0	IN		
B[5]	0b0	0: Disable			C/Q Weak Pull-Up	RX		RX	1	OUT		
B[4]	0b0	0: Disable		-	C/Q and DO Outputs Tracking			11	1	OUT		
B[3]	0b0	0: Disable		-	C/Q NPN operation	10 (\frown	10	0	IN IN		
B[2]	0b1	1: Enable		•	C/Q Push-Pull Mode							
B[1]	0b0	0: Disable		-	Drive C/Q to V24	LED1N (\bigcirc	LED1N	0	IN		
B[0]	0b0	0: Disable		-	C/Q Driver Tristate	CSB / PP		CS	N/A	IN		
lote: To ed	it the value	of a R/W register click on the	Value cell		-	SDI/TX/NPN		SDI	N/A	OUT		
						CLK / TXEN		CLK	N/A	IN		
						SDO / RX / THSH		SDO	N/A	IN		
								IRQ / OCB	1	OUT		
								10/11	4	OUT		

Figure 7. Click on the Write Modified button to write the changes to the MAX14827.

Address	R/W	Register	Value		Description	Read All	🖌 🗸 In	Include Interrupt Register				
x00	R	INTERRUPT_REGISTER	0600000000	Interrup	pt Register		🗸 In	clude I/Os				
x01	R	STATUS_REGISTER	0b01000010	Status	Register	Write modified						
x02	R/W	MODE_REGISTER	0b0000000	Mode F	Register							
x05	NW	CORREIM_REGISTER	0000000000	Curren	t Limit Tregister	MAX14827 I/O Pins						
x04	R/W	CQConfig_REGISTER	0b00000100		onfig Register	Name	Set	Function	Read	Direction		
x05	NVV	DIOCOINIg_REGISTER	000000000	01100	Coning Register	SPI / PIN		SPI / PIN	1	IN		
						UARTSEL	\bigcirc	UARTSEL	0	IN		
Bit	Value	Setting			Description	Chip Mode	SPI and	UART, Inde	pendent			
8[7]	060	0: No Interrupt			Interrupt: Thermal Shutdown	TXEN	\sim	TXEN	0	IN		
8[6]	0b0	0: No Interrupt			Interrupt: IO-Link Wake-Up Condition	TX		тх	0	IN		
8[5]	0b0	0: No Interrupt			Interrupt: DO-Driver Overload	RX		RX	0	OUT		
8[4]	0b0	0: No Interrupt		Interrupt: C/Q-Driver Overload			11	0	OUT			
8[3]	0b0	0: No Interrupt			Interrupt: V24 Below 16V	LO		LO	0	IN		
8[2]	0b0	0: No Interrupt			Interrupt: V24 Below Undervoltage TH				_			
8[1]	0b0	0: No Interrupt			Interrupt: DO Temperature Warning	LED1N	\bigcirc	LED1N	0	IN		
8[0]	0b0	0: No Interrupt			Interrupt: C/Q Temperature Warning	CSB / PP		CS	N/A	IN		
ote: To edi	t the value	of a R/W register, click on the	Value cell.			SDI / TX / NPN		SDI	N/A	OUT		
						CLK / TXEN		CLK	N/A	IN		
						SDO / RX / THSH		SDO	N/A	IN		
								IRQ / OCB	1	OUT		
								wu	1	OUT		

Figure 8. C/Q Config Register has been changed and C/Q Driver Output is enabled.

Driving the Inputs with an External Source

When the MAX14827 EV kit is connected to the mbed board and the MAX14827 GUI is on, the mbed board is set to drive the inputs high or low, as set with the switch. It is possible, however, to drive an input with an external source when needed.

When a switch is set, the GUI writes to the corresponding pin and then reads it to verify that the input is set correctly. When the input reads back a different value than written, however, the GUI interprets this as the pin being controlled by an external source, and a message box with that note appears (**Figure 9**). The DIRECTION note in that pin row is also modified to note that the pin is being driven with an external source (**Figure 10**).

	3
TX Pin level doesn't match the requested setting. This is most likely caused by driving TX pin externally, which doesn't allow the GUI to drive the pin. This pin has been set to Tristate on mbed to accomodate your external signal. If you remove the signal, please change the setting for this pin in the GUI to set the pin back to be driven by mbed. The GUI will for now assume the setting that was read back.	
ОК	

Figure 9. Driving with an external signal message.



Figure 10. Driving signal with an external source indicator.

Ensure that the signal from the external source can source enough to drive the input with a OV-3.3V signal when the mbed is attempting to set the pin. If the external source is not strong enough, the GUI may not detect that an external source is present on the pin.

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