

USER GUIDE

Bluepyro-M3225



Version 1.0



Revision history

Version	Date	Note	Contributor(s)	Approver
1.0	15 April 2021	Initial version	Ho Manh Tai	Nguyen Hoang Hoan



Copyright © 2019 I-SYST, all rights reserved.

3514, 1re Rue, Saint-Hubert, QC., Canada J3Y 8Y5

This document may not be reproduced in any form without, express written consent from I-SYST.



Contents

1. Introduction	5
1.1 Required components	5
2. Installation	5
2.1. Install Android Studio	5
2.2. Create new virtual device	8
2.3. Import Android Project	9
2.4. Run the Bluepyro-M3225 Android App Project with new Virtual device	11
2.5. Run on real Android device	12
2. Bluepyro-M3225 Firmware development with Eclipse IDE	13
2.1. Download Bluepyro-M3225 Firmware	13
2.2 Import firmware projects to Eclipse	
2.3 Build Bluepyro-M3225 Firmware Projects	14
2.4 Connect Bluepyro-M3225 device	17
2.5 Debug Configurations	
2.6 Flashing Firmware	22



1. Introduction

This document shows step-by-step to install Android Studio to develop Android apps with Bluepyro-M3225

1.1 Required components

The following are needed for a full development environment Bluepyro-M3225:

- Android Studio
- Eclipse
- Download source code Android app and firmware at <u>I-SYST/BluePyro: BluePyro (github.com)</u>

2. Installation

2.1. Install Android Studio

Download and install Android Studio to develop Android apps using Bluepyro-M3225 at the following link: https://developer.android.com/studio/

Download Android Studio and SDK tools | Android Developers

Follow the link below to install Android Studio: https://developer.android.com/studio/install Install Android Studio | Android Developers







漜 Android Studio Setup Wizard

- 🗆 🗙







2.2. Create new virtual device

After finishing installation Android Studio, create a new Android virtual device in AVD Manager



📥 An	Iroid Virtual Device Manager					-	\times
	Your Virtual D	evices					
Туре				Target	CPU/ABI		
Co	Nexus 5X API 30	⊳	1080 × 1920: 420dpi	Android 11.0 (Google Play)		▶ ₽	
	Create Virtual Device					<u></u>	

2.3. Import Android Project

Download source code Android app at <u>https://github.com/I-SYST/BluePyro</u> Import Android project BluePyro







2.4. Run the Bluepyro-M3225 Android App Project with new Virtual







2.5. Run on real Android device

Now it's ready to run on your Android device to test with Bluepyro-M3225. Connect your Android device and run the project on your device. Test the Bluepyro-M3225 device with Bluepyro app on your device. Now you are freely to develop any android apps with Bluepyro-M3225.





2. Bluepyro-M3225 Firmware development with Eclipse IDE

Please read the installation guide "Eclipse IDE in firmware development with Iosonata" for Eclipse installation at Eclipse IDE in firmware development with IOsonata | I-SYST's Site.

In this section, we will show how to manually develop Bluepyro-M3225 Firmware by Eclipse.

2.1. Download Bluepyro-M3225 Firmware Download source code Bluepyro-M3225 firmware at:

https://github.com/I-SYST/BluePyro

2.2 Import firmware projects to Eclipse

Select Open Projects from File System in File menu Located the Bluepyro-M3225 Firmware directory.



Import Projects from File System or Archive		– 🗆 X
Import Projects from File System or Archive		
This wizard analyzes the content of your folder or archive file to find projects and impor	t them in the IDE.	
Import source: D:\i_syst\BluePyro-main\firmware	~	Directory Archive
type filter text		Select All
Folder	Import as	Deselect All
☑ firmware ☑ firmware\BluePyro ☑ firmware\dfu	Eclipse project Eclipse project Eclipse project	3 of 3 selected
Close newly imported projects upon completion Use <u>installed project configurators</u> to: Search for nested projects Detect and configure project natures Working sets		☐ Hide aiready open projects
Add project to working sets		New
working sets:	She	ow other specialized import wizards
?	< Back Next >	Finish Cancel

2.3 Build Bluepyro-M3225 Firmware Projects



eclipse-workspace - BluePyro/src/main.cp	p - Eclipse IDE —		×
<u>File Edit Source Refactor Navigate Se</u>	a <u>r</u> ch <u>P</u> roject <u>R</u> un <u>W</u> indow <u>H</u> elp		
🐔 💽 🔳 💽 Run	✓ E HelloWorld.elf		
📸 ▼ 😂 ▼ 🔂 ▼ 🞯 ▼ 🔅 ▼ 🔿 ▼ 💡	נייק אין	۹ ا	8 6
Project Ex 🛛 🗖 🚺 blue_pyro	.h 🗈 board.h 🗈 main.cpp ⊠	- 6	a 🐺
□ 2 V 34 > □ 35 #inc. 36 #inc. 36 > □ BluePyro 37 #inc. > □ BluePyro. 37 #inc. > □ blue_pyro.h 38 #inc. > □ blue_pyro.h 38 #inc. > □ board.h 44 #inc. > □ board.h 43 #inc. > □ bobag 44 #inc. > □ bebug 50 #inc. > □ Debug 50 #inc. 55 #inc. 55 #inc. 56 #inc. 55 #inc. <tr< td=""><td><pre>*/ Lude <string.h> Lude (string.h) Lude (atomic) Lude (atomic) Lude "app_util_platform.h" Lude "nrf_sdh.h" Lude "nrf_sdh.h" Lude "idelay.h" Lude "idelay.h" Lude "idelay.h" Lude "ble_service.h" Lude "ble_service.h" Lude "ble_service.h" Lude "ble_service.h" Lude "coredev/upincfg.h" Lude "coredev/upincfg.h" Lude "coredev/ipincfg.h" Lude "interrupt.h" Lude "interrupt.h" Lude "blue_pyro.h" Lude "blue_pyro.h"</string.h></pre></td><td>◆ → ↓ ↓</td><td></td></tr<>	<pre>*/ Lude <string.h> Lude (string.h) Lude (atomic) Lude (atomic) Lude "app_util_platform.h" Lude "nrf_sdh.h" Lude "nrf_sdh.h" Lude "idelay.h" Lude "idelay.h" Lude "idelay.h" Lude "ble_service.h" Lude "ble_service.h" Lude "ble_service.h" Lude "ble_service.h" Lude "coredev/upincfg.h" Lude "coredev/upincfg.h" Lude "coredev/ipincfg.h" Lude "interrupt.h" Lude "interrupt.h" Lude "blue_pyro.h" Lude "blue_pyro.h"</string.h></pre>	◆ → ↓ ↓	
10:04:00 ** make all Invoking: (arm-none-ea text 78247 Finished bu	*** Build of configuration Debug for project BluePyro **** GNU ARM Cross Print Size abi-sizeformat=berkeley "BluePyro.elf" data bss dec hex filename 2228 6344 86619 15323 BluePyro.elf wilding: BluePyro.siz		~
/BluePyro/src/main.cpp		>	

You may need to add some more libraries

Right click on Bluepyro Project, select Project Properties \rightarrow C/C++ General \rightarrow Paths and Symbols \rightarrow Includes tab. Click Add button: Add directory path, select File system



Properties for BluePyro	_	
type filter text	Paths and Symbols	← - ⇒ %
type filter text > Resource Builders < C/C++ Build Build Variables Environment Logging Settings Tool Chain Editor < C/C++ General > Code Analysis Documentation File Types Formatter Indexer Language Mappings Paths and Symbols Preprocessor Include Pat Profiling Categories Linux Tools Path > MCU Project Natures Project References Run/Debug Settings Task Repository Task Tags > Validation WikiText	Paths and Symbols Configuration: Debug [Active] Includes # Symbols Includes # Symbols Include directories Include directories Assembly Include directories GNU C Include directories Include directories Include directories Assembly Include directories GNU C Include directories J.J./JOsonata/ARM/Nordic/nRF52/nRF52832/lib/incl GNU C++ Include directories J.J./JOsonata/ARM/CMSIS/Core/Include J.J./JOsonata/ARM/CMSIS/Core/Include J.J./JOsonata/ARM/CMSIS/Core/Include J.J./Jexternal/nRF5_SDK/components/libraries/atomic J.J./external/nRF5_SDK/components/libraries/ratomic J.J./external/nRF5_SDK/components/libraries/ratomic J.J./external/nRF5_SDK/components/libraries/log/srcc J.J./external/nRF5_SDK/components/libraries/log/srcc </th <th>Configurations erences Add Edit Delete Export Move Up Move Down</th>	Configurations erences Add Edit Delete Export Move Up Move Down
	🖓 Import Settings 🛞 Export Settings	
< >	Restore <u>D</u> efaults	Apply
?	Apply and Close	Cancel



Add directory path	×
Directory:	aior\arm-none-eabi\include
 Add to all configurations Add to all languages □	Variables Workspace File system OK Cancel

Right click on Bluepyro-M3225 Firmware project, select Build Project . Now you can build and manually develop Bluepyro-M3225 Firmware by yourself.

2.4 Connect Bluepyro-M3225 device



Prepare Bluepyro-M3225 development kit as the figure above include Bluepyro-M3225 board, IDAP-Link.



Connect Bluepyro-M3225 to computer.







2.5 Debug Configurations

In order to debug the Bluepyro-M3225 firmware, we have to set the Debug Configurations as following:

In the Main tab, select C/C++ Application by clicking Search Project. Select BluePyro.elf file.



Debug Configurations			— П X
Configurations	ſ		
Create, manage, and run configurations		Program Selection — L X	
		Choose a program to run:	
	New Diver]
	Name: BluePyrc	Binaries:	
type filter text	📄 Main 🕉 De	D BluePyro.elf] ————————————————————————————————————
C/C++ Application	Project:		
C/C++ Container Launcher	BluePyro		Browse
C/C++ Postmortem Debugger	C/C++ Applicat		
CTC/C++ Remote Application	Debug\BluePyr		
C GDB Hardware Debugging			Variables Search Project Browse
> C GDB OpenOCD Debugging	Build (if requir		
BleAdvertiser Debugging	Build Configu		~
C Blinky Debug	O Enable auto		Disable auto build
C BluePyro Debug	Use worksp		ifigure Workspace Settings
C GDB PyOCD Debugging		Qualifier:	
GDB QEMU Debugging		3 armle - /BluePyro/Debug/BluePyro.elf	
GDB SEGGER J-Link Debugging			
Launch Group			
		UK Cancel	
Filter matched 18 of 21 items			Revert Apply
(?)			Debug Close
Debug Configurations			— 🗆 X
Create, manage, and run configurations			1 second second
			2
🗋 🖻 🍋 🗎 🗶 🖻 🏹 🗸	Name: BluePyro	Debug	
type filter text	📄 Main 🕸 De	bugger 🕨 Startup 🧤 Source 🔲 Common	
> C/C++ Application	Project:		
C C/C++ Attach to Application	BluePyro		Browse
C/C++ Postmortem Debugger	C/C++ Applicati	on:	
C/C++ Remote Application	Debug\BluePyr	o.elf	
GDB Hardware Debugging			Variables Search Project Browse
> C GDB OpenOCD Debugging	Build (if require	ed) before launching	
C BleAdvertiser Debug	Build Configu	ration: Select Automatically	
C Blinky Debug	Carbles	huild	O Dirable sute build
C BluePyro Debug	Use workspa	ace settings	Configure Workspace Settings
C GDB PyOCD Debugging			
GDB QEMU Debugging			
C GDB SEGGER J-Link Debugging GDB SEGGER J-Link Debugging			

In the Debugger tab, set the Executable by browsing to the OpenOCD executable file.

aunch Group

Filter matched 18 of 21 items

?

Revert Apply

Debug Close



Set the Config Option:

-f "interface/cmsis-dap.cfg"

-f	"target/	/nrf52.	.cfg"
----	----------	---------	-------

Debug Configurations				- 🗆	×
Create, manage, and run configurations				2	\$
type filter text > C //C++ Application C //C++ Attach to Application C //C++ Container Launcher C //C++ Postmortem Debugger C //C++ Remote Application Cii //C++ Unit C GDB Hardware Debugging C GDB OpenOCD Debugging C BleAdvertiser Debug C BleAdvertiser Debug C BleAdvertiser Debug C BluePyro Debug C BlystHeater Debug C GDB SEGGER J-Link Debugging C GDB SEGGER J-Link Debugging C GDB SEGGER J-Link Debugging	Name: BluePyro D Main & Debu OpenCD Setup Start OpenOC Executable: GDB port: Telnet port: Config options: Allocate cons GDB Client Setup Executable: Other options: Commands:	ebug igger Startup Source Common Common Control Control Common Control	Browse	Variables	
Filter matched 18 of 21 items			Revert	Арр	у
0			Debug	CI	ose

Then click Debug button.

eclipse-workspace - BluePyro/src/main.c	p - Eclipse IDE	– o ×
File Edit Source Refactor Navigate	search Project Run Window Help 	* - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 -
	District Districtions Share affirm The District M	* * * *
	Borning Construction of the conclusion of the construction of the construction of the conclusion of th	
Project Explorer 13 Project Explorer 13 Project Explorer 13 Project Explorer 14 Proje	<pre>Bindy.c Blackdentiscr.pp The happ.nt53cpp The Tool D main.cpp 12 // Adjust it for other toolchains. // Adjust it for other</pre>	
	(44) dut <u>0</u> function (/32) (45) dut <u>i</u> comp (/32) (46) dut <u>i</u> mask (/4)	
	(ar) dm_1_function (/32) (d8) dm_2_nosk (/4) (d8) dm_2_nosk (/4) (31) dm_3_comp (/32) (33) dm_3_comp (/32) (34) dm_3_comp (/32) (35) dm_3_function (/22)	
	Writable Smart Insert 81	>

After you start the debugger, it will stop at main(). Now you can debug the firmware by clicking the



step button (F5, F6) to trace your source code line by line.

2.6 Flashing Firmware

Click Run button to run the firmware on your device.

Note:

Make sure that the softdevice is flashed first. Using Use IDAPnRFProg to flash NRF softdevice using IDAP-Link. Download here <u>IDAP-Link/M - Browse /Windows at SourceForge.net</u>

Run IDAPnRFProg by following command line:

\$.\IDAPnRFProg.exe .\external\nRF5_SDK\components\softdevice\s132\
hex\s132 nrf52 7.2.0 softdevice.hex