### **USB Dual-Port Power Switch and Current Monitor**

#### **Features**

- · Dual-Port Power Switches:
  - 2.9V to 5.5V source voltage range
  - 3.0A continuous current per  $V_{BUS}$  port with 40  $m\Omega$  On resistance per switch
  - Independent port power switch enable pins
  - DUAL fault ALERT# active drain output pins
  - Constant Current or Trip mode current limiting behaviors
  - Undervoltage and overvoltage lockout
  - Back-drive, back-voltage protection
  - Auto-recovery fault handling with low test current
  - BOOST# logic output to increase DC-DC converter output under large load conditions
  - A\_DET# open-drain outputs for device attach detection per port
- SMBus 2.0/I<sup>2</sup>C Mode Features:
  - Eight programmable current limits assignable to each power switch
  - Other SMBus addresses available upon request
  - Block read and block write
- Self-contained current monitoring (no external sense resistor required)
- Fully programmable per-port charge rationing and behaviors
- Per-port BC1.2 V<sub>BUS</sub> Discharge Function
- · Wide Operating Temperature Range:
  - -40°C to +105°C
- · UL recognized and EN/IEC 60950-1 (CB) certified.
- · Passes Automotive AEC-Q100 Reliability Testing

#### **Description**

The UCS2112 is a dual USB port power switch configuration which can provide 3.0A continuous current (3.4A maximum) per  $V_{BUS}$  port with precision overcurrent limiting (OCL), port power switch enables, auto-recovery fault handling, undervoltage and overvoltage lockout, back-drive protection and back-voltage protection, and dynamic thermal management.

The UCS2112 is well suited for both stand-alone and applications having SMBus/I<sup>2</sup>C communications.

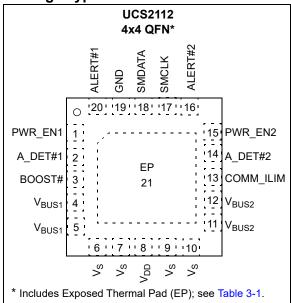
For applications with SMBus, the UCS2112 provides per-port current monitoring and eight programmable current limits per switch, ranging from 0.53A to 3.0A continuous current (3.4A maximum). Per-port charge rationing is also provided ranging from 3.8 mAh to 246.3 Ah.

In Stand-alone mode, the UCS2112 provides eight current limits for both switches, ranging from 0.53A + 0.53A to 3A + 3A total continuous current (see Table 1-1).

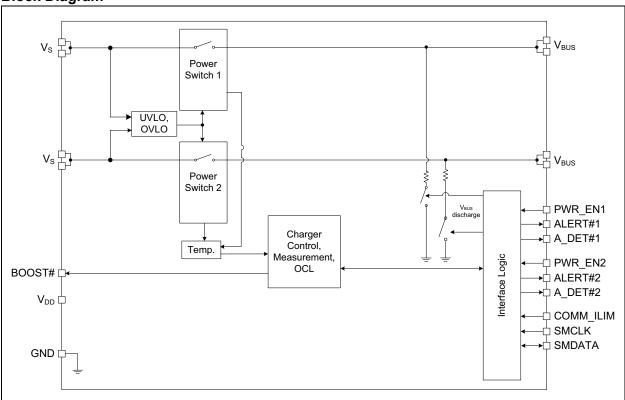
Both power switches include an independent  $V_{BUS}$  discharge function and constant current mode current limiting for BC1.2 applications.

The UCS2112 is available in a 4x4 mm 20-pin QFN package.

#### Package Type



### **Block Diagram**



## 1.0 ELECTRICAL CHARACTERISTICS

#### **Absolute Maximum Ratings †**

| Voltage on V <sub>DD</sub> , V <sub>S</sub> , and V <sub>BUS</sub> pins | 0.3 to +6V                    |
|---|-------------------------------|
| Pull-Up Voltage (V <sub>PULLUP</sub> )                                  | 0.3 to V <sub>DD</sub> + 0.3  |
| Port Power Switch Current   | Internally limited            |
| Voltage on any Other Pin to Ground                                      | 0.3 to V <sub>DD</sub> + 0.3V |
| Current on any Other Pin  | ±10 mA                        |
| Package Power Dissipation   | See Table 1-1                 |
| Operating Ambient Temperature Range                                     | 40°C to +105°C                |
| Storage Temperature Range   | 55°C to +150°C                |

**† Notice:** Stresses above those listed under "Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

TABLE 1-1: POWER DISSIPATION SUMMARY

| Board              | Package              | θЈС    | $\theta_{JA}$ | De-Rating Factor above +25°C | T <sub>A</sub> < +25°C<br>Power Rating | T <sub>A</sub> = +70°C<br>Power Rating | T <sub>A</sub> = +85°C<br>Power Rating |
|--------------------|----------------------|--------|---------------|------------------------------|--|--|--|
| High K<br>(Note 1) | 20-pin QFN<br>4x4 mm | 6 °C/W | 41 °C/W       | 24.4 mW/°C                   | 2193 mW                                | 1095 mW                                | 729 mW                                 |
| Low K<br>(Note 1)  | 20-pin QFN<br>4x4 mm | 6 °C/W | 60 °C/W       | 16.67 mW/°C                  | 1498 mW                                | 748 mW                                 | 498 mW                                 |

Note 1: A High K board uses a thermal via design with the thermal landing soldered to the PCB ground plane with 0.3 mm (12 mil) diameter vias in a 3x3 matrix (9 total) at 0.5 mm (20 mil) pitch. The board is multi-layer with 1-ounce internal power and ground planes and 2-ounce copper traces on top and bottom. A Low K board is a two-layer board without thermal via design with 2-ounce copper traces on the top and bottom.

#### TABLE 1-2: ELECTRICAL SPECIFICATIONS

**Electrical Characteristics:** Unless otherwise specified,  $V_{DD}$  = 4.5V to 5.5V,  $V_{S}$  = 2.9V to 5.5V,  $V_{PULLUP}$  = 3V to 5.5V,  $V_{A}$  = -40°C to 105°C. All typical values at  $V_{DD}$  =  $V_{S}$  = 5V,  $V_{A}$  = 27°C.

| Characteristic   | Symbol              | Min. | Тур. | Max. | Unit | Conditions  |
|--|---------------------|------|------|------|------|---|
| Power and Interrupts - DC  |                     |      |      |      |      |   |
| Supply Voltage   | $V_{DD}$            | 4.5  | 5    | 5.5  | V    |   |
| Supply Current in Active (I <sub>DD_ACT</sub> + I <sub>S1_ACT</sub> + I <sub>S2_ACT</sub> )            | I <sub>ACTIVE</sub> | _    | 850  | _    | μA   | Average current I <sub>BUS</sub> = 0 mA               |
| Supply Current in Sleep<br>(I <sub>DD_SLEEP</sub> + I <sub>S1_SLEEP</sub> +<br>I <sub>S2_SLEEP</sub> ) | I <sub>SLEEP</sub>  | _    | 6    | 20   | μА   | Average current V <sub>PULLUP</sub> ≤ V <sub>DD</sub> |
| Supply Current in Detect (I <sub>DD_DET</sub> + I <sub>S1_DET</sub> + I <sub>S2_DET</sub> )            | IDETECT             | _    | 200  | _    | μА   | Average current No portable device attached (Note 1)  |

- **Note 1:** This parameter is characterized, not 100% tested.
  - 2: This parameter is ensured by design and not 100% tested.
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TABLE 1-2: ELECTRICAL SPECIFICATIONS (CONTINUED)

**Electrical Characteristics:** Unless otherwise specified,  $V_{DD}$  = 4.5V to 5.5V,  $V_S$  = 2.9V to 5.5V,  $V_{PULLUP}$  = 3V to 5.5V,  $V_A$  = -40°C to 105°C. All typical values at  $V_{DD}$  =  $V_S$  = 5V,  $V_A$  = 27°C.

| Characteristic                       | Symbol                  | Min.    | Тур.    | Max.    | Unit    | Conditions  |
|--------------------------------------|-------------------------|---------|---------|---------|---------|---|
| Power-on Reset                       | -                       |         | _       |         |         |   |
| V <sub>DD</sub> Low Threshold        | V <sub>DD_TH</sub>      | _       | 4       | _       | V       | V <sub>DD</sub> voltage increasing  |
| V <sub>DD</sub> Low Hysteresis       | V <sub>DD_TH_HYST</sub> | _       | 500     | 600     | mV      | V <sub>DD</sub> voltage decreasing (Note 1)                                       |
| I/O Pins - SMCLK, SMDATA             |                         | RT#, A_ | DET#, B | OOST# - | DC Para | ameters   |
| Output Low Voltage                   | V <sub>OL</sub>         | _       | _       | 0.4     | V       | I <sub>SINK_IO</sub> = 8 mA<br>SMDATA, ALERT#, A_DET#,<br>BOOST#                  |
| Input High Voltage                   | V <sub>IH</sub>         | 2.0     | _       | _       | V       | PWR_EN, SMDATA, SMCLK   |
| Input Low Voltage                    | V <sub>IL</sub>         | _       | _       | 0.8     | V       | PWR_EN, SMDATA, SMCLK   |
| Leakage Current                      | I <sub>LEAK</sub>       | _       | _       | ±5      | μА      | Powered or unpowered $V_{PULLUP} \le V_{DD}$ $T_A < 85^{\circ}C \text{ (Note 1)}$ |
| Interrupt Pins - AC Parame           | ters                    |         |         |         |         |   |
| ALERT# Pin Blanking Time             | t <sub>BLANK</sub>      | _       | 25      |         | ms      | Blanking time, coming out of Reset  |
| ALERT# Pin Interrupt<br>Masking Time | <sup>t</sup> mask       |         | 5       | l       | ms      |   |
| BOOST# Pin Minimum<br>Assertion Time | t <sub>BOOST_MAT</sub>  |         | 1       |         | S       |   |
| BOOST# Pin Assertion<br>Current      | I <sub>BOOST</sub>      | _       | 1.9     | _       | Α       |   |
| SMBus/I <sup>2</sup> C Timing        |                         |         |         |         |         |   |
| Input Capacitance                    | C <sub>IN</sub>         | _       | 5       | _       | pF      |   |
| Clock Frequency                      | f <sub>SMB</sub>        | 10      | _       | 400     | kHz     |   |
| Spike Suppression                    | t <sub>SP</sub>         | _       | _       | 50      | ns      |   |
| Bus Free Time Stop to Start          | t <sub>BUF</sub>        | 1.3     | _       | _       | μs      |   |
| Start Setup Time                     | t <sub>SU:STA</sub>     | 0.6     | _       | _       | μs      |   |
| Start Hold Time                      | t <sub>HD:STA</sub>     | 0.6     | _       | _       | μs      |   |
| Stop Setup Time                      | t <sub>su:sto</sub>     | 0.6     | _       | _       | μs      |   |
| Data Hold Time                       | t <sub>HD:DAT</sub>     | 0       | _       | _       | μs      | When transmitting to the master   |
| Data Hold Time                       | t <sub>HD:DAT</sub>     | 0.3     | _       | _       | μs      | When receiving from the master  |
| Data Setup Time                      | t <sub>SU:DAT</sub>     | 0.6     | _       | _       | μs      |   |
| Clock Low Period                     | t <sub>LOW</sub>        | 1.3     | _       | _       | μs      |   |
| Clock High Period                    | t <sub>HIGH</sub>       | 0.6     | _       | _       | μs      |   |
| Clock / Data Fall Time               | t <sub>FALL</sub>       | _       | _       | 300     | ns      | Min = 20+0.1C <sub>LOAD</sub> ns<br>(Note 1)                                      |
| Clock / Data Rise Time               | t <sub>RISE</sub>       | _       | _       | 300     | ns      | Min = 20+0.1C <sub>LOAD</sub> ns<br>(Note 1)                                      |

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<sup>3:</sup> The current measurement full scale range maximum value is 3.4A. However, the UCS2112 cannot report values above  $I_{LIM}$  (if  $I_{BUS\_R2MIN} \le I_{LIM}$ ) or above  $I_{BUS\_R2MIN}$  (if  $I_{BUS\_R2MIN} > I_{LIM}$  and  $I_{LIM} \le 1.6A$ ).

TABLE 1-2: ELECTRICAL SPECIFICATIONS (CONTINUED)

**Electrical Characteristics:** Unless otherwise specified,  $V_{DD}$  = 4.5V to 5.5V,  $V_{S}$  = 2.9V to 5.5V,  $V_{PULLUP}$  = 3V to 5.5V,  $V_{A}$  = -40°C to 105°C. All typical values at  $V_{DD}$  =  $V_{S}$  = 5V,  $V_{A}$  = 27°C.

| Characteristic                       | Symbol                   | Min.   | Тур.      | Max.     | Unit | Conditions   |
|--------------------------------------|--------------------------|--------|-----------|----------|------|--|
| Capacitive Load                      | C <sub>LOAD</sub>        | _      | _         | 400      | pF   | Per bus line (Note 1)  |
| Timeout                              | t <sub>TIMEOUT</sub>     | 25     | _         | 35       | ms   | Disabled by default (Note 1)   |
| Idle Reset                           | t <sub>IDLE_RESET</sub>  | 350    | _         | _        | μs   | Disabled by default (Note 1)   |
| Port Power Switch                    |                          |        |           |          | l.   |  |
|                                      | Port Po                  | wer Sw | itch – Do | C Parame | ter  |  |
| Overvoltage Lockout                  | V <sub>S_OV</sub>        | _      | 6         |          | V    | Note 2   |
| V <sub>S</sub> Low Threshold         | V <sub>S_UVLO</sub>      | -      | 2.5       | _        | V    | Note 2   |
| V <sub>S</sub> Low Hysteresis        | V <sub>S_UVLO_HYST</sub> | _      | 100       | _        | mV   | Note 2   |
| On Resistance                        | R <sub>ON_PSW</sub>      | _      | 40        | 60       | mΩ   | 4.75V < V <sub>S</sub> < 5.25V   |
| V <sub>S</sub> Leakage Current       | I <sub>LEAK_VS</sub>     |        | _         | 5        | μA   | Sleep state into V <sub>S</sub> pin on one channel (Note 1)  |
| Back-Voltage Protection<br>Threshold | V <sub>BV_TH</sub>       | _      | 150       | _        | mV   | $V_{BUS} > V_{S}$<br>$V_{S} > V_{S\_UVLO}$   |
| Back-drive Current                   | I <sub>BD_1</sub>        | 1      | 0         | 3        | μА   | $V_{DD}$ < $V_{DD\_TH}$ ,<br>Leakage current from $V_{BUS}$ pins<br>to the $V_{DD}$ and the $V_{S}$ pins<br>(Note 1)                                     |
|                                      | I <sub>BD_2</sub>        | _      | 0         | 2        | μА   | $V_{DD} > V_{DD\_TH}$ ,<br>Leakage current from $V_{BUS}$ pins<br>to the $V_{DD}$ (in Detect State) or<br>the $V_{S}$ pins (in Active State)<br>(Note 1) |
| Selectable Current Limits            | I <sub>LIM1</sub>        | _      | 530       | _        | mA   | $I_{LIM}$ Resistor = 0 or 47 kΩ (530 mA setting)   |
|                                      | I <sub>LIM2</sub>        | l      | 960       |          | mA   | $I_{LIM}$ Resistor = 10 kΩ or 56 kΩ (960 mA setting)   |
|                                      | I <sub>LIM3</sub>        | l      | 1070      | -        | mA   | $I_{\text{LIM}}$ Resistor = 12 kΩ or 68 kΩ (1070 mA setting)   |
|                                      | I <sub>LIM4</sub>        | l      | 1280      | 1        | mA   | $I_{\text{LIM}}$ Resistor = 15 kΩ or 82 kΩ (1280 mA setting)   |
|                                      | I <sub>LIM5</sub>        | 1      | 1600      |          | mA   | $I_{LIM}$ Resistor = 18 kΩ or 100 kΩ (1600 mA setting)   |
|                                      | I <sub>LIM6</sub>        | _      | 2130      | _        | mA   | $I_{LIM}$ Resistor = 22 kΩ or 120 kΩ (2130 mA setting)   |
|                                      | I <sub>LIM7</sub>        | 2500   | 2670      | 2900     | mA   | $I_{LIM}$ Resistor = 27 kΩ or 150 kΩ (2670 mA setting)   |
|                                      | I <sub>LIM8</sub>        | 3000   | 3200      | 3400     | mA   | $I_{LIM}$ Resistor = 33 kΩ or $V_{DD}$ (3200 mA setting)   |
| Pin Wake Time                        | t <sub>PIN_WAKE</sub>    | _      | 3         | _        | ms   |  |
| SMBus Wake Time                      | t <sub>SMB_WAKE</sub>    | _      | 4         | _        | ms   |  |

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| Characteristic                    | Symbol                      | Min.    | Тур.     | Max.   | Unit  | Conditions  |
|-----------------------------------|-----------------------------|---------|----------|--------|-------|---|
| Idle Sleep Time                   | t <sub>IDLE_SLEEP</sub>     | _       | 200      | _      | ms    |   |
| Thermal Regulation Limit          | T <sub>REG</sub>            | _       | 110      |        | °C    | Die Temperature at which current limit will be reduced  |
| Thermal Regulation<br>Hysteresis  | T <sub>REG_HYST</sub>       | _       | 10       | _      | °C    | Hysteresis for t <sub>REG</sub> functionality.<br>Temperature must drop by this<br>value before I <sub>LIM</sub> value restored<br>to normal operation  |
| Thermal Shutdown<br>Threshold     | T <sub>TSD</sub>            | _       | 135      |        | °C    | Die Temperature at which port power switch will turn off  |
| Thermal Shutdown<br>Hysteresis    | T <sub>TSD_HYST</sub>       | _       | 35       | 1      | °C    | After shutdown due to T <sub>TSD</sub> being reached, die temperature drop required before port power switch can be turned on again                     |
| Auto-Recovery Test Current        | I <sub>TEST</sub>           | _       | 190      | _      | mA    | Portable device attached,<br>V <sub>BUS</sub> = 0V, Die temp < T <sub>TSD</sub>   |
| Auto-Recovery Test Voltage        | V <sub>TEST</sub>           | _       | 750      |        | mV    | Portable device attached,<br>V <sub>BUS</sub> = 0V before application,<br>Die temp < T <sub>TSD</sub><br>Programmable, 250 - 1000 mV,<br>default listed |
| Discharge Impedance               | R <sub>DISCHARGE</sub>      | _       | 100      |        | W     |   |
|                                   | Port Pov                    | ver Swi | tch – AC | Parame | ters  |   |
| Turn-On Delay                     | t <sub>ON_</sub> PSW        | _       | 200      | _      | ms    | Depends on the V <sub>BUS</sub> Discharge setting. Programmable 100 – 400 ms, default listed  |
| Turn-Off Time                     | t <sub>OFF_PSW_INA</sub>    | _       | 0.75     | _      | ms    | PWR_EN inactive toggle to switch off time $C_{BUS} = 120 \ \mu F$   |
| Turn-Off Time                     | t <sub>OFF_PSW_ERR</sub>    | _       | 1        | _      | ms    | Over-current Error, V <sub>BUS</sub> Min<br>Error, or Discharge Error to<br>switch off<br>C <sub>BUS</sub> = 120 µF                                     |
| Turn-Off Time                     | t <sub>OFF_PSW_ERR1</sub>   | _       | 100      | 1      | ns    | TSD or Back-drive Error to switch off C <sub>BUS</sub> = 120 µF   |
| V <sub>BUS</sub> Output Rise Time | t <sub>R_BUS</sub>          | _       | 1.1      | _      | ms    | Measured from 10% to 90% of $V_{BUS}$ , $C_{LOAD}$ = 220 $\mu F$ $I_{LIM}$ = 1.0A   |
| Soft Turn-On Rate                 | $\Delta I_{BUS}/\Delta_{t}$ | _       | 100      | _      | mA/μs |   |
| Temperature Update Time           | t <sub>DC_TEMP</sub>        | _       | 200      | _      | ms    |   |

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|   | T                        | 1        |          |          | - , .A   | T  |
|---|--------------------------|----------|----------|----------|----------|--|
| Characteristic                                | Symbol                   | Min.     | Тур.     | Max.     | Unit     | Conditions   |
| Short-Circuit Response Time                   | t <sub>SHORT_LIM</sub>   |          | 1.5      | _        | μs       | Time from detection of short to current limit applied. No C <sub>BUS</sub> applied   |
| Short-Circuit Detection Time                  | t <sub>SHORT</sub>       | _        | 6        | _        | ms       | Time from detection of short to port power switch disconnect and ALERT# pin assertion.                                       |
| Latched Mode Cycle Time                       | t <sub>UL</sub>          | _        | 7        | _        | ms       | From PWR_EN edge transition from inactive to active to begin error recovery  |
| Auto-Recovery Mode Cycle<br>Time              | tcycle                   |          | 25       |          | ms       | Time delay before error condition check Programmable 15-50 ms, default listed  |
| Auto-Recovery Delay                           | t <sub>TST</sub>         |          | 20       | _        | ms       | Portable device attached, V <sub>BUS</sub> must be ≥ V <sub>TEST</sub> after this time Programmable 10-25 ms, default listed |
| Discharge Time                                | <sup>†</sup> DISCHARGE   | _        | 200      | _        | ms       | Amount of time discharge resistor applied Programmable 100-400 ms, default listed  |
| Port  | Power Switch (           | peratio  | n With T | rip Mode | Current  | Limiting   |
| Region 2 Current<br>Keep-out                  | I <sub>BUS_R2MIN_1</sub> | _        | _        | 0.1      | Α        | Note 2   |
| Minimum V <sub>BUS</sub><br>Allowed at Output | V <sub>BUS_MIN_1</sub>   | 2.0      | _        | _        | V        | Note 2   |
| Port Power S                                  | Switch Operatio          | n With C | onstant  | Current  | Limiting | (Variable Slope)   |
| Region 2 Current<br>Keep-out                  | I <sub>BUS_R2MIN</sub>   | _        | _        | 2.13     | Α        | Note 2   |
| Minimum V <sub>BUS</sub><br>Allowed at Output | V <sub>BUS_MIN</sub>     | 2.0      | _        | _        | V        | Note 2   |
|   | Cu                       | rrent Me | asurem   | ent - DC |          |  |
| Current Measurement Range                     | I <sub>BUS_M</sub>       | 0        |          | 3400     | mA       | Range (Note 2 and Note 3)  |
| Reported Current<br>Measurement Resolution    | ΔI <sub>BUS_M</sub>      | _        | 13.3     | _        | mA       | 1 LSB  |
| Current Measurement                           |                          | _        | ±2       | _        | %        | 200 mA < I <sub>BUS</sub> < I <sub>LIM</sub>   |
| Accuracy                                      |                          | _        | ±2       | _        | LSB      | I <sub>BUS</sub> < 200 mA  |

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| 1 02201  |  | • .                |          | <i>DD</i> 0 | . , , |   |  |  |
|--|--|--------------------|----------|-------------|-------|---|--|--|
| Characteristic                                 | Symbol   | Min.               | Тур.     | Max.        | Unit  | Conditions  |  |  |
| Current Measurement – AC                       |  |                    |          |             |       |   |  |  |
| Sampling Rate                                  | _  |                    | 1.1      |             | ms    | Note 2  |  |  |
| Conversion Time both channels                  | t <sub>CONV</sub>                              | _                  | 2.2      | _           | ms    | All registers updated in digital (Note 2)                   |  |  |
|  | C  | harge R            | ationing | – DC        |       |   |  |  |
| Accumulated Current Measurement Accuracy       | _  | _                  | ±4.5     | _           | %     |   |  |  |
|  | C  | harge R            | ationing | J – AC      |       |   |  |  |
| Current Measurement<br>Update Time             | t <sub>PCYCLE</sub>                            | _                  | 1        | _           | s     |   |  |  |
| Attach / Removal Detecti                       | on   |                    |          |             |       |   |  |  |
|  |  | V <sub>BUS</sub> B | ypass –  | DC          |       |   |  |  |
| On Resistance                                  | R <sub>ON_BYP</sub>                            | _                  | 45       | _           | Ω     |   |  |  |
| Leakage Current                                | I <sub>LEAK_BYP</sub>                          | _                  | _        | 3           | μΑ    | Switch off T <sub>A</sub> < +85°C (Note 1)                  |  |  |
| Current Limit                                  | I <sub>DET_CHG</sub> /<br>I <sub>BUS_BYP</sub> | _                  | 500      | _           | μA    | $V_{DD}$ = 5V and $V_{BUS}$ > 4.75V                         |  |  |
| V <sub>BUS</sub> Charge Time for<br>Attachment | t <sub>DET_CHARGE</sub>                        | _                  | 800      | _           | ms    | C <sub>BUS</sub> = 500 μF maximum                           |  |  |
|  | Attac  | h/Remov            | val Dete | ction - D   | С     |   |  |  |
| Attach Detection<br>Threshold                  | I <sub>DET_QUAL</sub>                          | _                  | 800      | _           | μA    | Programmable 200-1000 μA, default listed                    |  |  |
| Primary Removal<br>Detection Threshold         | I <sub>REM_QUAL_ACT</sub>                      | _                  | 700      | _           | μA    | Programmable 100-900 μA, default listed. Active power state |  |  |
|  | I <sub>REM_QUAL_DET</sub>                      | _                  | 800      | _           | μA    | Programmable, default listed. Detect power state            |  |  |
|  | Attac  | h/Remov            | val Dete | ction – A   | С     |   |  |  |
| Attach Detection Time                          | t <sub>DET_QUAL</sub>                          | _                  | 100      | _           | ms    | Time from Attach to A_DET# assert.                          |  |  |
| Removal Detection Time                         | t <sub>REM_QUAL</sub>                          |                    | 1000     |             | ms    |   |  |  |
|  |  |                    |          |             |       |   |  |  |

Note 1: This parameter is characterized, not 100% tested.

<sup>2:</sup> This parameter is ensured by design and not 100% tested.

<sup>3:</sup> The current measurement full scale range maximum value is 3.4A. However, the UCS2112 cannot report values above  $I_{LIM}$  (if  $I_{BUS\_R2MIN} \le I_{LIM}$ ) or above  $I_{BUS\_R2MIN}$  (if  $I_{BUS\_R2MIN} > I_{LIM}$  and  $I_{LIM} \le 1.6A$ ).

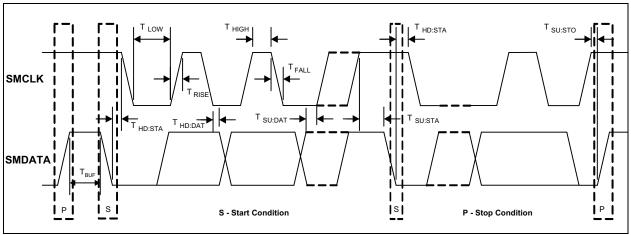


FIGURE 1-1: SMBus Timing.

TABLE 1-3: TEMPERATURE SPECIFICATIONS

| Parameters                                   | Sym.               | Min. | Тур. | Max. | Units | Conditions |  |  |
|--|--------------------|------|------|------|-------|------------|--|--|
| Temperature Ranges                           | Femperature Ranges |      |      |      |       |            |  |  |
| Operating Temperature Range                  | T <sub>A</sub>     | -40  | _    | +105 | °C    |            |  |  |
| Operating Junction Temperature               | T <sub>J</sub>     | -40  | _    | +125 | °C    |            |  |  |
| Storage Temperature Range                    | T <sub>A</sub>     | -55  | _    | +150 | °C    |            |  |  |
| Thermal Package Resistances - see Table 1-1. |                    |      |      |      |       |            |  |  |

#### 1.1 ESD and Transient Performance

TABLE 1-4: ESD RATINGS

| ESD Specification                                   | Rating or Value |
|---|-----------------|
| Human Body Model (JEDEC JESD22-A114) – All pins     | 8 kV            |
| Charged Device Model (JEDEC JESD22-C101) – All pins | 500V            |

### 1.1.1 HUMAN BODY MODEL (HBM) PERFORMANCE

HBM testing verifies the ability to withstand ESD strikes like those that occur during handling and manufacturing and is done without power applied to the IC. To pass the test, the device must have no change in operation or performance due to the event.

## 1.1.2 CHARGED DEVICE MODEL (CDM) PERFORMANCE

CDM testing verifies the ability to withstand ESD strikes like those that occur during handling and assembly with pick and place style machinery and is done without power applied to the IC. To pass the test, the device must have no change in operation or performance due to the event.



NOTES:

#### 2.0 TYPICAL PERFORMANCE CURVES

**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

**Note:** Unless otherwise indicated,  $V_{DD} = V_S = 5V$ ,  $T_A = +27$ °C.

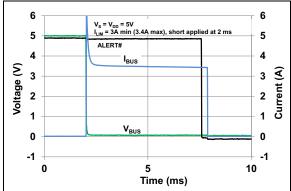


FIGURE 2-1: Short Applied After Power-Up.

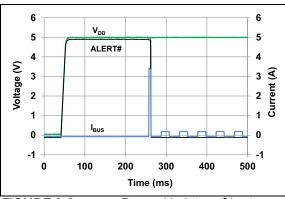


FIGURE 2-2: Power-Up Into a Short.

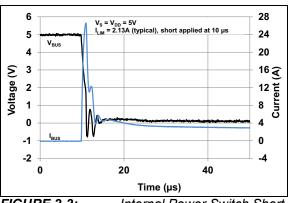


FIGURE 2-3: Internal Power Switch Short Response.

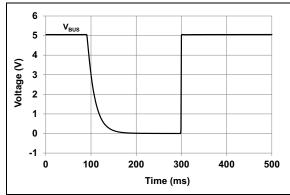


FIGURE 2-4: V<sub>BUS</sub> Discharge Behavior.

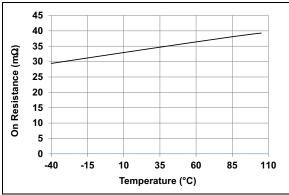
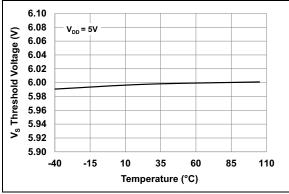
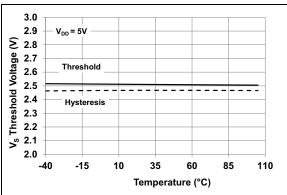


FIGURE 2-5: Power Switch On Resistance vs. Temperature.

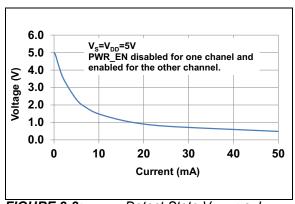
**Note:** Unless otherwise indicated,  $V_{DD} = V_S = 5V$ ,  $T_A = +27$ °C.



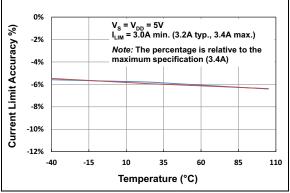
**FIGURE 2-6:**  $V_S$  Overvoltage Threshold vs. Temperature.



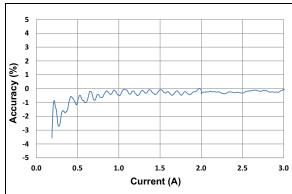
**FIGURE 2-7:**  $V_S$  Undervoltage Threshold vs. Temperature.



**FIGURE 2-8:** Detect State  $V_{BUS}$  vs.  $I_{BUS}$ .



**FIGURE 2-9:** Trip Current Limit Operation vs. Temperature.



**FIGURE 2-10:** I<sub>BUS</sub> Measurement Accuracy.

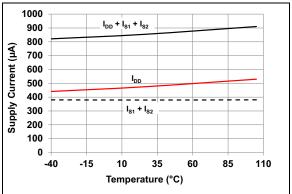


FIGURE 2-11: Active State Current vs.
Temperature (both channels on,
PWR\_EN1 = PWR\_EN2 = 1).

**Note:** Unless otherwise indicated,  $V_{DD} = V_S = 5V$ ,  $T_A = +27$ °C.

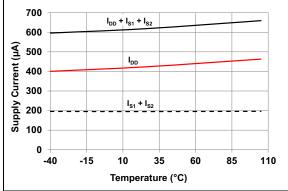
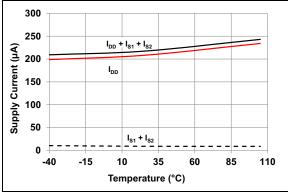


FIGURE 2-12: Active State Current vs. Temperature (only one channel on, PWR\_EN1 = 1, PWR\_EN2 = 0).



**FIGURE 2-13:** Detect State Current vs. Temperature.

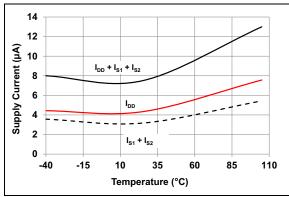


FIGURE 2-14: Sleep State Current vs. Temperature.

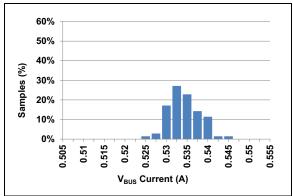
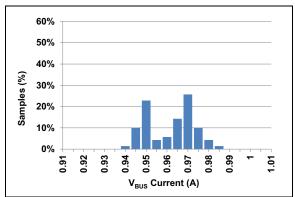
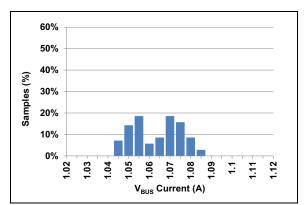


FIGURE 2-15: ILIM1 Trip Current Distribution.



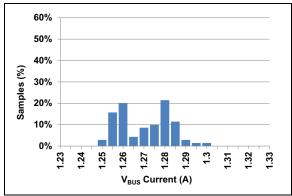
**FIGURE 2-16:** ILIM2 Trip Current Distribution<sup>(1)</sup>.



**FIGURE 2-17:** ILIM3 Trip Current Distribution<sup>(1)</sup>.

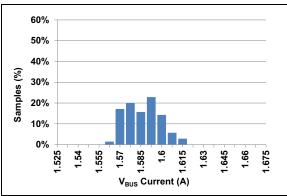
Note 1: The histogram aspect is caused by a mixture of two normal distributions, corresponding to the two  $V_{BUS}$  channels.

**Note:** Unless otherwise indicated,  $V_{DD} = V_S = 5V$ ,  $T_A = +27$ °C.



**FIGURE 2-18:** Distribution<sup>(1)</sup>.

ILIM4 Trip Current



**FIGURE 2-19:** Distribution<sup>(1)</sup>.

ILIM5 Trip Current

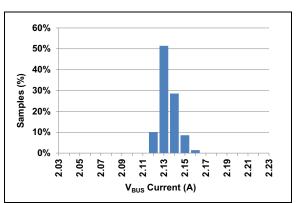
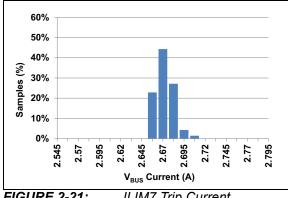


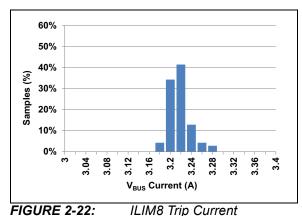
FIGURE 2-20: Distribution.

ILIM6 Trip Current



**FIGURE 2-21:** Distribution.

ILIM7 Trip Current



Distribution.

ILIM8 Trip Current

Note 1: The histogram aspect is caused by a mixture of two normal distributions, corresponding to the two V<sub>BUS</sub> channels.

### 3.0 PIN DESCRIPTION

Descriptions of the pins are listed in Table 3-1.

TABLE 3-1: PIN FUNCTION TABLE

| UCS2112<br>4x4 QFN | Symbol            | Function  | Pin Type        | Connection Type if Pin Not Used  |
|--------------------|-------------------|---|-----------------|--|
| 1                  | PWR_EN1           | Port power switch enable #1   | DI              | Connect to ground or V <sub>DD</sub> (depending on the polarity decoded via COMM_ILIM pin) |
| 2                  | A_DET#1           | Open-drain output for Attach Detection on V <sub>BUS1</sub> (requires pull-up resistor) | OD              | Connect to ground  |
| 3                  | BOOST#            | Logic output for DC-DC converter voltage increase (requires pull-up resistor)           | OD              | Connect to ground  |
| 4, 5               | V <sub>BUS1</sub> | Port power switch #1 output (requires both pins tied together)                          | High Power, AIO | Leave open   |
| 6, 7               | V <sub>S</sub>    | Voltage input to port power switch V <sub>BUS1</sub> (requires both pins tied together) | High Power, AIO | Connect to ground  |
| 8                  | $V_{DD}$          | Common supply voltage   | Power           | N/A  |
| 9, 10              | V <sub>S</sub>    | Voltage input to port power switch V <sub>BUS2</sub> (requires both pins tied together) | High Power, AIO | Connect to ground  |
| 11, 12             | V <sub>BUS2</sub> | Port power switch #2 output (requires both pins tied together)                          | High Power, AIO | Leave open   |
| 13                 | COMM_ILIM         | Enables SMBus or Stand-Alone mode at power-up. Hardware strap for maximum current limit | AIO             | N/A  |
| 14                 | A_DET#2           | Open-drain output for Attach Detection on V <sub>BUS2</sub> (requires Pull Up)          | OD              | Connect to ground  |
| 15                 | PWR_EN2           | Port power switch enable #2   | DI              | Connect to ground or V <sub>DD</sub> (depending on the polarity decoded via COMM_ILIM pin) |
| 16                 | ALERT#2           | Output fault ALERT for V <sub>BUS2</sub> (requires pull-up resistor)                    | OD              | Connect to ground  |
| 17                 | SMCLK             | SMCLK - SMBus clock input (requires pull-up resistor)                                   | DI              | Connect to V <sub>PULLUP</sub> (or to ground in Stand-alone mode)                          |
| 18                 | SMDATA            | SMDATA - SMBus data input/output (requires pull-up resistor)                            | DIOD            | Connect to V <sub>PULLUP</sub> (or to ground in Stand-alone mode)                          |
| 19                 | GND               | Ground  | Power           | N/A  |
| 20                 | ALERT#1           | Output fault ALERT for V <sub>BUS1</sub> (requires pull-up resistor)                    | OD              | Connect to ground  |
| 21                 | EP                | Exposed thermal pad. Must be connected to electrical ground.                            | EP              | N/A  |

#### TABLE 3-2: PIN TYPES

| Pin Type | Description  |
|----------|--|
| Power    | This pin is used to supply power or ground to the device.  |
| Hi-Power | This pin is a high-current pin.  |
| AIO      | Analog Input/Output – this pin is used as an I/O for analog signals.   |
| DI       | Digital Input – this pin is used as a digital input.   |
| DIOD     | Open-Drain Digital Input/Output – this pin is bidirectional. It is open-drain and requires a pull-up resistor. |
| OD       | Open-Drain Digital Output – used as a digital output. It is open-drain and requires a pull-up resistor.        |
| EP       | Exposed thermal pad  |

#### 4.0 TERMS AND ABBREVIATIONS

Note:

The PWR\_EN1 and PWR\_EN2 pins each have Configuration bits ("<pin name>\_S" in General Configuration 1 register (Address 11h) and General Configuration 2 register (Address 12h)) that may be used to perform the same function as the external pin state. These bits are accessed via the SMBus/l<sup>2</sup>C and are OR'd with the respective pin. This OR'd combination of pin state and register bit is referenced as the <pin name> control.

TABLE 4-1: TERMS AND ABBREVIATIONS

| Term/Abbreviation             | Description   |
|-------------------------------|---|
| Attach Detection              | An Attach Detection event occurs when the current drawn by a portable device is greater than $I_{\text{DET\_QUAL}}$ for longer than $t_{\text{DET\_QUAL}}$ .  |
| Attachment                    | The physical insertion of a portable device into a USB port that UCS2112 is controlling.  |
| CC                            | Constant Current  |
| CDM                           | Charged Device Model. JEDEC model for characterizing susceptibility of a device to damage from ESD.   |
| Current Limiting              | Determines the action that is performed when the I <sub>BUS</sub> current reaches the I <sub>LIM</sub> threshold. Trip  |
| Mode                          | opens the port power switch. Constant Current (variable slope) allows V <sub>BUS</sub> to be dropped by   |
|                               | the portable device.  |
| Disconnection                 | USB-IF term which refers to the loss of active USB communications between a USB host and a USB device.  |
| Dynamic Thermal<br>Management | The UCS2112 automatically adjusts port power switch limits and modes to lower internal power dissipation when the thermal regulation temperature value is approached.   |
| НВМ                           | Human Body Model  |
| I <sub>BUS_R2MIN</sub>        | Current limiter mode boundary   |
| I <sub>LIM</sub>              | The $I_{BUS}$ current threshold used in current limiting. In Trip mode, when $I_{LIM}$ is reached, the port power switch is opened. In Constant Current mode, when the current exceeds $I_{LIM}$ , operation continues at a reduced voltage and increased current; if $V_{BUS}$ voltage drops below $V_{BUS\_MIN}$ , the port power switch is opened. |
| OCL                           | Overcurrent limit   |
| POR                           | Power-on Reset  |
| Portable Device               | USB device attached to the USB port.  |
| Removal Detection             | A Removal Detection event occurs when the current load on the V <sub>BUS</sub> pin drops to less than   |
|                               | I <sub>REM_QUAL</sub> for longer than t <sub>REM_QUAL</sub> .   |
| Removal                       | The physical removal of a portable device from a USB port that the UCS2112 is controlling.  |
| Stand-Alone Mode              | Indicates that the communications protocol is not active and all communications between the UCS2112 and a controller are done via the external pins only (PWR_EN1 and PWR_EN2 as inputs, and ALERT1#, ALERT2#, A_DET1# and A_DET2# as outputs).   |



NOTES:

#### 5.0 GENERAL DESCRIPTION

The UCS2112 is a dual-port power switch. Two USB power ports are supported with current limits up to 3.0A continuous current (3.4A maximum) each. Selectable and programmable current limiting configurations are also available to the application. A typical block diagram is shown in Figure 5-1.

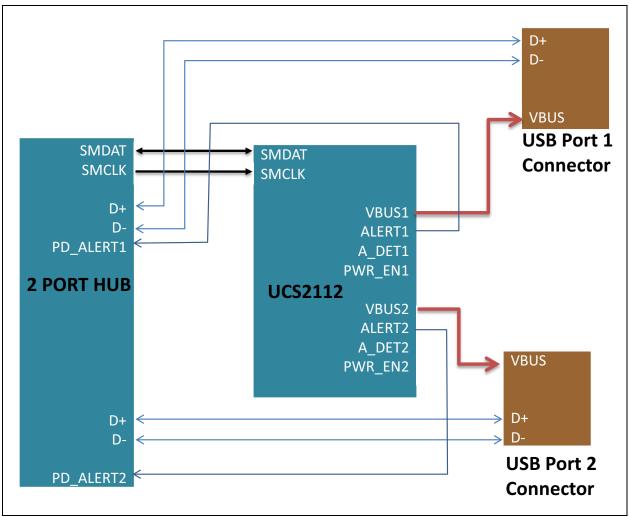


FIGURE 5-1: Typical USB Application.

#### 5.1 UCS2112 Power States

Power states are indicators of the device's current consumption in the System and the functionality of the Digital Logic. Table 5-1 details the UCS2112 power states.

TABLE 5-1: POWER STATES DESCRIPTION

| State  | Description  |
|--------|--|
| Off    | This power state is entered when the voltage at the $V_{DD}$ pin voltage is $< V_{DD\_TH}$ . In this state, the device is considered "off". The UCS2112 will not retain its digital states and register contents nor respond to SMBus/l <sup>2</sup> C communications. The port power switch and bypass switch will be off. See Section 5.1.1 "Off State Operation".   |
| Sleep  | This is the lowest power state available. While in this state, the UCS2112 will retain digital functionality and wake to respond to SMBus/I <sup>2</sup> C communications. See <b>Section 5.1.2 "Sleep State Operation"</b> .  |
| Detect | The Detect power state should not be confused with the actual Attach / Removal Detection feature. Detect power state is both channels awaiting attachment. This is a lower-current power state. In this state, the device is actively looking for a portable device to be attached. While in this state, the UCS2112 will retain the configuration and charge rationing data, but it will not monitor the bus current. SMBus/I <sup>2</sup> C communications will be fully functional. See Section 5.1.3 "Detect State Operation". |
| Error  | This power state is entered when a Fault condition exists. Error power state is one or both channels in Fault Handling. This state is updated as Priority One. The Interrupt Status registers for each channel will update the fault detected per channel. Only the channel that has detected a fault will be affected since the other channel can remain active if no fault is detected. See Section 5.1.5 "Error State Operation".   |
| Active | Active power state is one, or both channels active and sourcing current to the V <sub>BUS</sub> Port. This state is updated as Priority Two. None of the channels have detected fault. This power state provides full functionality. While in this state, operations include activation of the port power switch, current limiting, and charge rationing. See Section 5.1.4 "Active State Operation".  |

Table 5-2 shows the settings for the various power states, except Off and Error. If  $V_{DD}$  <  $V_{DD\_TH}$ , the UCS2112 is in the Off state.

TABLE 5-2: POWER STATES CONTROL SETTINGS

| Power<br>State | PWR_EN1  | PWR_EN2  | ATT_DET | Portable<br>Device<br>Attached | Behavior  |
|----------------|----------|----------|---------|--------------------------------|---|
| Sleep          | disabled | disabled | N/A     | N/A                            | All switches disabled.  |
|                |          |          |         |                                | <ul> <li>V<sub>BUS</sub> will be near ground potential.</li> </ul>  |
|                |          |          |         |                                | <ul> <li>The UCS2112 wakes to respond to SMBus communications.</li> </ul>   |
| Detect         | enabled  | disabled | enabled | No                             | <ul> <li>Automatic transition to Active state when conditions<br/>met for V<sub>BUS1</sub> (see Section 5.1.3.1 "Automatic<br/>Transition from Detect to Active").</li> </ul>                           |
|                |          |          |         |                                | <ul> <li>V<sub>BUS2</sub> pins have very low current delivery capability.</li> </ul>  |
|                | disabled | enabled  | enabled | No                             | <ul> <li>Automatic transition to Active state when conditions<br/>met for V<sub>BUS2</sub> (see Section 5.1.3.1 "Automatic<br/>Transition from Detect to Active").</li> </ul>                           |
|                |          |          |         |                                | <ul> <li>V<sub>BUS1</sub> pins have very low current delivery capability.</li> </ul>  |
|                | enabled  | enabled  | enabled | No                             | <ul> <li>Automatic transition to Active state when conditions<br/>met for both V<sub>BUS1</sub> and V<sub>BUS2</sub> (see Section 5.1.3.1<br/>"Automatic Transition from Detect to Active").</li> </ul> |

| Power<br>State | PWR_EN1  | PWR_EN2  | ATT_DET  | Portable<br>Device<br>Attached | Behavior   |  |  |
|----------------|----------|----------|----------|--------------------------------|--|--|--|
| Active         | enabled  | disabled | N/A      | Yes                            | Port power switch is on during A_DET1=1 for V <sub>BUS1</sub> .  |  |  |
|                |          |          |          |                                | <ul> <li>V<sub>BUS2</sub> pins have very low current delivery capability.</li> </ul>   |  |  |
|                | disabled | enabled  | N/A      | Yes                            | <ul> <li>Port power switch is on during A_DET2=1 for V<sub>BUS2</sub>.</li> </ul>  |  |  |
|                |          |          |          |                                | V <sub>BUS1</sub> pins have very low current delivery capability.  |  |  |
|                | enabled  | enabled  | N/A      | Yes                            | Port power switch is on during A_DET1=A_DET2=1   |  |  |
|                |          |          |          |                                | for $V_{BUS1}$ and $V_{BUS2}$ .  |  |  |
|                | enabled  | disabled | disabled | N/A                            | Forced ACTIVE Power State: Port power switch is on   |  |  |
|                |          |          |          |                                | at all times for V <sub>BUS1</sub> .   |  |  |
|                |          |          |          |                                | V <sub>BUS2</sub> pins have very low current delivery capability.  |  |  |
|                | disabled | enabled  | disabled | N/A                            | Forced ACTIVE Power State: Port power switch is on   |  |  |
|                |          |          |          |                                | at all times for V <sub>BUS2</sub> .   |  |  |
|                |          |          |          |                                | <ul> <li>V<sub>BUS1</sub> pins have very low current delivery capability.</li> </ul>   |  |  |
|                | enabled  | enabled  | disabled | N/A                            | <ul> <li>Forced ACTIVE Power State: Port power switch is on<br/>at all times for V<sub>BUS1</sub> and V<sub>BUS2</sub>.</li> </ul> |  |  |

TABLE 5-2: POWER STATES CONTROL SETTINGS (CONTINUED)

#### 5.1.1 OFF STATE OPERATION

The device will be in the Off state if  $V_{DD}$  is less than  $V_{DD\_TH}$ . When the UCS2112 is in the Off state, it will do nothing and all circuitry will be disabled. Digital register values are not stored and the device will not respond to SMBus commands.

#### 5.1.2 SLEEP STATE OPERATION

The PWR\_EN1 and PWR\_EN2 pins may be used to cause the UCS2112 to enter/exit Sleep. These pins are AND'ed for Sleep mode.

When the UCS2112 is in the Sleep state, the device will be in its lowest-power state. The bypass switch and the port power switch will be disabled. The Attach and Removal Detection feature will be disabled.  $V_{BUS1}$  and  $V_{BUS2}$  will be near ground potential. The ALERT#1 and ALERT#2 pins will not be asserted. If asserted prior to entering the Sleep state, the ALERT# pin will be released. SMBus activity is limited to single byte read or write.

The first data byte read from the UCS2112 when it is in the Sleep state will wake it; however, the data to be read will return all 0's and should be considered invalid. This is a "dummy" read byte meant to wake the UCS2112. Subsequent read or write bytes will be accepted normally. After the dummy read, the UCS2112 will be in a higher-power state (see Figure 5-2). After communication has not occurred for  $t_{\rm IDLE\ SLEEP}$ , the UCS2112 will return to Sleep.

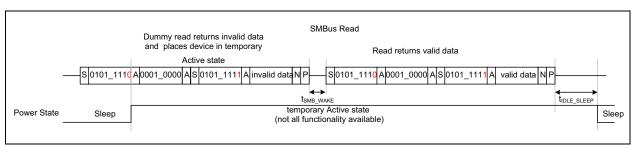


FIGURE 5-2: Wake from Sleep using SMBus Read.

#### 5.1.3 DETECT STATE OPERATION

When the UCS2112 is in the Detect state, the port power switch will be disabled. The  $V_{BUS}$  output will be connected to the  $V_{DD}$  voltage by a secondary bypass switch.

There are two methods for transitioning from the Detect state to the Active state: automatic and host-controlled.

### 5.1.3.1 Automatic Transition from Detect to Active

For the Detect state, enable PWR\_EN1 and/or PWR\_EN2, and supply  $V_{DD} \ge V_{DD\_TH}$ . When a portable device is attached and an Attach Detection event occurs, the UCS2112 will automatically transition to the Active state.

#### 5.1.3.2 State Change from Detect to Active

When conditions cause the UCS2112 to transition from the Detect state to the Active state, the following occurs:

- The Attach Detection feature will be disabled; the Removal Detection feature remains enabled.
- The bypass switch will be turned off.
- The discharge switch will be turned on briefly for <sup>t</sup>DISCHARGE.
- · The port power switch will be turned on.

#### 5.1.4 ACTIVE STATE OPERATION

Every time the UCS2112 enters the Active state, the port power switches are closed. The UCS2112 cannot be in the Active state (and therefore, the port power switch cannot be turned on) if any of the following conditions exist:

- V<sub>S</sub> < V<sub>S\_UVLO</sub>
- · PWR\_EN1 and PWR\_EN2 are disabled.

#### 5.1.5 ERROR STATE OPERATION

The UCS2112 will enter the Error state from the Active state when any of the following events are detected:

 The maximum allowable internal die temperature (T<sub>TSD</sub>) has been exceeded.

- · An overcurrent condition has been detected.
- An undervoltage condition on either V<sub>BUS</sub> pin has been detected (see Section 5.3.4 "Undervoltage Lockout on VS").
- A back-drive condition has been detected (see Section 5.3.2 "Back-voltage Detection").
- · A discharge error has been detected.
- An overvoltage condition on the V<sub>S</sub> pin.

The UCS2112 will enter the Error state from the Detect state when a back-drive condition has been detected on either port, or when the maximum allowable internal die temperature has been exceeded.

The UCS2112 will enter the Error state from the Sleep state when a back-drive condition has been detected.

When the UCS2112 enters the Error state, the port power switch and the  $V_{BUS}$  bypass switch will be disabled while the ALERT# pin is asserted (by default). They will remain off while in this power state. The UCS2112 will leave this state as determined by the fault handling selection.

With the auto-recovery fault handler, after the  $t_{CYCLE}$  time period, the UCS2112 will check that all of the error conditions have been removed.

If all of the error conditions have been removed, the UCS2112 will return to the Active state or Detect state, as applicable.

If the device is in the Error state and a Removal Detection event occurs, it will check the error conditions and then return to the power state defined.

#### 5.2 Communication

The UCS2112 can operate in SMBus mode (see Section 8.0 "System Management Bus Protocol") or Stand-alone mode. The resistor connected to the COMM\_ILIM pin determines the operating mode and the hardware-set  $I_{LIM}$  setting, as shown in Table 5-3. Unless connected to GND or  $V_{DD}$ , the resistors in Table 5-3 are external pull-down resistors.

The SMBus address is specified in Section 8.2 "SMBus Address and RD/WR Bit".

TABLE 5-3: COMMUNICATION DECODE

| COMM_ILIM Pull Down<br>Resistor (±1%) | PWR_EN1 and PWR_EN2 Polarity | I <sub>LIM</sub> (A) | Total I <sub>LIM</sub> (A)<br>(Note 1) | Communication<br>Mode |
|---------------------------------------|------------------------------|----------------------|--|-----------------------|
| GND                                   | Active-High                  | 0.53                 | 0.53 + 0.53                            | SMBus                 |
| 10 kΩ                                 | Active-High                  | 0.96                 | 0.96 + 0.96                            | SMBus                 |
| 12 kΩ                                 | Active-High                  | 1.07                 | 1.07 + 1.07                            | SMBus                 |
| 15 kΩ                                 | Active-High                  | 1.28                 | 1.28 + 1.28                            | SMBus                 |
| 18 kΩ                                 | Active-High                  | 1.6                  | 1.6 + 1.6                              | SMBus                 |

Note 1: The total maximum current depends on power dissipation characteristics of the design (see Table 1-1).

| IABLE 5-3. COMMUNION                  | ABLE 5-3. COMMUNICATION DECODE (CONTINUED) |                      |  |                    |  |  |  |  |  |
|---------------------------------------|--|----------------------|--|--------------------|--|--|--|--|--|
| COMM_ILIM Pull Down<br>Resistor (±1%) | PWR_EN1 and PWR_EN2 Polarity               | I <sub>LIM</sub> (A) | Total I <sub>LIM</sub> (A)<br>(Note 1) | Communication Mode |  |  |  |  |  |
| 22 kΩ                                 | Active-High                                | 2.13                 | 2.13 + 2.13                            | SMBus              |  |  |  |  |  |
| 27 kΩ                                 | Active-High                                | 2.67                 | 2.67 + 2.67                            | SMBus              |  |  |  |  |  |
| 33 kΩ                                 | Active-High                                | 3.2                  | 3.2 + 3.2                              | SMBus              |  |  |  |  |  |
| 47 kΩ                                 | Active-Low                                 | 0.53                 | 0.53 + 0.53                            | Stand-Alone        |  |  |  |  |  |
| 56 kΩ                                 | Active-Low                                 | 0.96                 | 0.96 + 0.96                            | Stand-Alone        |  |  |  |  |  |
| 68 kΩ                                 | Active-Low                                 | 1.07                 | 1.07 + 1.07                            | Stand-Alone        |  |  |  |  |  |
| 82 kΩ                                 | Active-Low                                 | 1.28                 | 1.28 + 1.28                            | Stand-Alone        |  |  |  |  |  |
| 100 kΩ                                | Active-Low                                 | 1.6                  | 1.6 + 1.6                              | Stand-Alone        |  |  |  |  |  |
| 120 kΩ                                | Active-Low                                 | 2.13                 | 2.13 + 2.13                            | Stand-Alone        |  |  |  |  |  |
| 150 kΩ                                | Active-Low                                 | 2.67                 | 2.67 + 2.67                            | Stand-Alone        |  |  |  |  |  |
| V <sub>DD</sub>                       | Active-Low                                 | 3.2                  | 3.2 + 3.2                              | Stand-Alone        |  |  |  |  |  |

TABLE 5-3: COMMUNICATION DECODE (CONTINUED)

Note 1: The total maximum current depends on power dissipation characteristics of the design (see Table 1-1).

#### 5.3 Supply Voltages

#### 5.3.1 V<sub>DD</sub> SUPPLY VOLTAGE

The UCS2112 requires 4.5V to 5.5V present on the  $V_{DD}$  pin for core device functionality. Core device functionality consists of maintaining register states, wake-up upon SMBus/I<sup>2</sup>C query and Attach Detection.

#### 5.3.2 BACK-VOLTAGE DETECTION

The back drive detector is functional in all power states (Sleep, Detect, and Active).

When in Sleep, the UCS2112 will enter the Error state from Sleep if a Back Drive condition was detected.

Whenever the following condition is true for either port, the port power switch will be disabled, the  $V_{BUS}$  bypass switch will be disabled and a back-voltage event will be flagged. This will cause the UCS2112 to enter the Error power state (see Section 5.1.5 "Error State Operation").

Note:

The  $V_{BUS}$  voltage exceeds the  $V_{S}$  and/or the  $V_{DD}$  pin voltage by  $V_{BV\_TH}$  and the port power switch is closed. The port power switch will be opened immediately. If the condition lasts for longer than  $t_{MASK}$ , then the UCS2112 will enter the Error state. Otherwise, the port power switch will be turned on as soon as the condition is removed.

### 5.3.3 BACK-DRIVE CURRENT PROTECTION

If a portable device is attached that is self-powered, it may drive the  $V_{BUS}$  port to its power supply voltage level; however, the UCS2112 is designed such that leakage current from the  $V_{BUS}$  pins to the  $V_{DD}$  and/or the  $V_S$  pin shall not exceed  $I_{BD\_1}$  (if the  $V_{DD}$  and/or  $V_S$  voltage is zero) or  $I_{BD\_2}$  (if the  $V_{DD}$  and/or  $V_S$  voltage exceeds  $V_{DD}$   $_{TH}$ ).

#### 5.3.4 UNDERVOLTAGE LOCKOUT ON V<sub>S</sub>

The UCS2112 requires a minimum voltage ( $V_{S\_UVLO}$ ) be present on the  $V_S$  pin for Active power state.

## 5.3.5 OVERVOLTAGE DETECTION AND LOCKOUT ON V<sub>S</sub>/V<sub>DD</sub>

The UCS2112 port power switch will be disabled if the voltage on the  $V_S$  pin exceeds a voltage ( $V_{S\ OV}$ ) for longer than the specified time ( $t_{MASK}$ ). This will cause the device to enter the Error state.

#### 5.3.6 PWR EN1 AND PWR EN2 INPUT

The PWR\_EN control affects the power state and enables the port power switch to be turned on if conditions are met (see Table 5-2). The port power switch cannot be closed if PWR\_EN is disabled. However, if PWR\_EN is enabled, the port power switch is not necessarily closed (see Section 5.1.4 "Active State Operation"). In SMBus mode, the PWR\_EN1 and PWR\_EN2 pins states will be ignored by the UCS2112 if the PIN\_IGN Configuration bit is set; otherwise, the PWR\_EN1S and PWR\_EN2S Configuration bits are checked along with the pins.

#### 5.4 Discrete Output Pins

### 5.4.1 ALERT#1 AND ALERT#2 OUTPUT PINS

The UCS2112 has two independent ALERT# out pins. ALERT#1 is tied to the status of the  $V_{BUS1}$  pin. ALERT#2 is tied to the status of the  $V_{BUS2}$  pin.

The ALERT# pin is an active-low open-drain interrupt to the host controller. The ALERT# pin is asserted when an error occurs. The ALERT# pin can also be asserted when the LOW\_CUR (portable device is pulling less current and may be finished charging) or TREG (thermal regulation temperature exceeded) bits are set and linked. Also, when charge rationing is enabled, the ALERT# pin is asserted by default when the current rationing threshold is reached (as determined by RTN\_BEH<1:0>). The ALERT# pin is released when all error conditions that may assert the ALERT# pin (such as an error condition, charge rationing, and TREG and LOW\_CUR if linked) have been removed or reset as necessary.

#### 5.4.2 BOOST# OUTPUT PIN

The UCS2112 provides a BOOST# output pin to compensate for voltage drops during high loads. The BOOST# pin is an active-low, open-drain output that would be connected to a resistor in the DC-DC Converter's feedback error voltage loop (see Figure 5-3).

The BOOST# pin is asserted when  $V_{BUS}$  Current >  $I_{BOOST}$ .  $I_{BOOST}$  typical value is 1.9A. The BOOST# is OR'ed for both  $V_{BUS1}$  and  $V_{BUS2}$  ports. When the BOOST# pin is asserted, it will remain in this state for at least  $t_{BOOST\ MAT}$  (minimum assertion time).

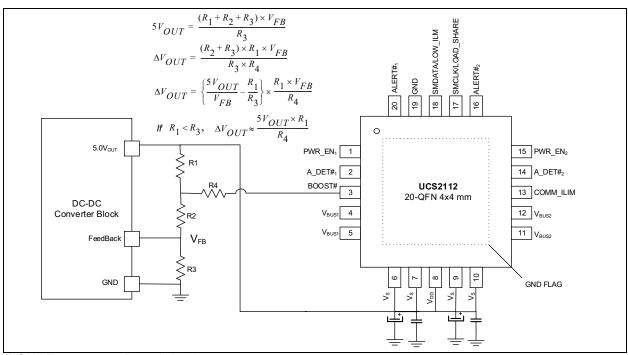


FIGURE 5-3: Boost# Pin Usage.

#### 5.5 Discrete Input Pins

#### 5.5.1 COMM ILIM INPUT

The COMM\_ILIM input determines the communications mode, as shown in Table 7-1. This is also the hardware strap for MAX Current Limit.

#### 5.5.2 SMCLK

When operated in Stand-Alone mode, this pin should be tied to ground. When the UCS2112 is configured for SMBus communications, the SMCLK is the clock input.

#### 5.5.3 SMDATA

When used in Stand-Alone, this pin should be tied to ground.

When the UCS2112 is configured for SMBus communications, the SMDATA is the data input/output.

#### 6.0 DETECT STATE

#### 6.1 Device Attach / Removal Detection

The UCS2112 can detect the attachment and removal of a portable device on the  $V_{BUS1}$  or  $V_{BUS2}$  ports.

Note:

By default, device attach / removal detection feature is disabled. It can be enabled by clearing ATT\_DISABLE bit 6 in Register 9-9.

#### 6.1.1 V<sub>BUS</sub> BYPASS SWITCH

The UCS2112 contains circuitry to provide  $V_{BUS}$  current as shown in Figure 6-1. In the Detect state,  $V_{DD}$  is the voltage source; in the Active state,  $V_{S}$  is the voltage source. The bypass switch and the port power switch are never both on at the same time.

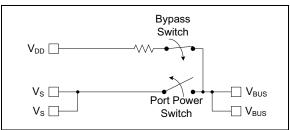


FIGURE 6-1: Bypass Switch.

While the  $V_{BUS}$  bypass switch is active, the current available to a portable device will be limited to  $I_{BUS\_BYP}$  and the Attach Detection feature will be active.

#### 6.1.2 ATTACH DETECTION

The primary Attach Detection feature is only active in the Detect power state. When active, this feature constantly monitors the current load on the  $V_{BUS1}$  or  $V_{BUS2}$  pins. If the current drawn by a portable device is greater than  $I_{DET\_QUAL}$  for longer than  $I_{DET\_QUAL}$ , an Attach Detection event occurs. This will cause the A\_DET# Status bits to be set.

Until the port power switch is enabled, the current available to a portable device will be limited to that used to detect device attachment ( $I_{DET\_QUAL}$ ). Once an Attach Detection event occurs, the UCS2112 will wait for the PWR\_EN control to be enabled (if not already). When PWR\_EN is enabled and  $V_S$  is above the threshold, the UCS2112 will activate the  $V_{BUS}$  port power switch and operate in Active state.

#### 6.1.3 REMOVAL DETECTION

The Removal Detection feature will be active in the Active and Detect power states. This feature monitors the current load on the  $V_{BUS1}$  and  $V_{BUS2}$  pins. If this load drops to less than  $I_{REM\_QUAL\_DET}$  for longer than  $I_{REM\_QUAL}$ , a Removal Detection event is flagged.

When a Removal Detection event is flagged, the following will be done:

- Disable the port power switch and the bypass switch.
- 2. Set the REM Status register bit.
- Enable an internal discharging device that will discharge the V<sub>BUS</sub> line within t<sub>DISCHARGE</sub>.
- 4. Once the  $V_{BUS}$  pin has been discharged, the device will return to the Detect state regardless of the PWR\_EN control state.



NOTES:

#### 7.0 USB PORT POWER SWITCH

To assure compliance to various charging specifications, the UCS2112 contains a USB port power switch that supports two current-limiting modes: Trip and Constant current (variable slope). The current limit ( $I_{LIM}$ ) is pin selectable (and may be updated via the register set). The switch also includes soft start circuitry and a separate short-circuit current limit.

The port power switch is on in the Active state (except when  $V_{BUS}$  is discharging).

Note: If a load that draws between 2 mA and 7 mA is connected to the port power switch, a voltage ripple between 40-90 mV<sub>PP</sub> is observed at the V<sub>BUS</sub> output. This behavior is normal and it does not affect the charging process when a portable device is connected.

#### 7.1 Current Limiting

#### 7.1.1 CURRENT LIMIT SETTING

The UCS2112 hardware set current limit,  $I_{LIM}$ , can be one of eight values. This resistor value is read once upon UCS2112 power-up. The current limit can be changed via the SMBus/ $I^2$ C after power-up; however, the programmed current limit cannot exceed the hardware set current limit. Unless connected to  $V_{DD}$ , the resistors in Table 7-1 are pull-down resistors.

At power-up, the communication mode (Stand-alone or SMBus/ $I^2$ C) and hardware current limit ( $I_{LIM}$ ) are determined via the pull-down resistor (or pull-up resistor if connected to  $V_{DD}$ ) on the COMM\_ILIM pin, as shown in Table 7-1.

### 7.1.2 SHORT-CIRCUIT OUTPUT CURRENT LIMITING

Short-circuit current limiting occurs when the output current is above the selectable current limit ( $I_{LIMx}$ ). This event will be detected and the current will immediately be limited (within  $t_{SHORT\_LIM}$  time). If the condition remains, the port power switch will flag an Error condition and enter the Error state.

#### 7.1.3 SOFT START

When the PWR\_EN control changes states to enable the port power switch, or an Attach Detection event occurs in the Detect power state and the PWR\_EN control is already enabled, the UCS2112 invokes a soft start routine for the duration of the  $V_{BUS}$  rise time ( $t_{R\_BUS}$ ). This soft start routine will limit current flow from  $V_{S}$  into  $V_{BUS}$  while it is active. This circuitry will prevent current spikes due to a step in the portable device current draw.

In the case when a portable device is attached while the PWR\_EN pin is already enabled, if the bus current exceeds  $I_{LIM}$ , the UCS2112 current limiter will respond within a specified time ( $t_{SHORT\_LIM}$ ) and will operate normally at this point. The  $C_{BUS}$  capacitor will deliver the extra current, if any, as required by the load change.

TABLE 7-1: I<sub>LIM</sub> DECODE

| COMM_ILIM<br>Pull Down<br>Resistor<br>(±1%) | PWR_EN1<br>and<br>PWR_EN2<br>Polarity | I <sub>LIM</sub> (A) | Total I <sub>LIM</sub> (A)<br>(Note 1) |
|---|---------------------------------------|----------------------|--|
| GND   | Active-High                           | 0.53                 | 0.53 + 0.53                            |
| 10 kΩ                                       | Active-High                           | 0.96                 | 0.96 + 096                             |
| 12 kΩ                                       | Active-High                           | 1.07                 | 1.07 + 1.07                            |
| 15 kΩ                                       | Active-High                           | 1.28                 | 1.28 + 1.28                            |
| 18 kΩ                                       | Active-High                           | 1.6                  | 1.6 + 1.6                              |
| 22 kΩ                                       | Active-High                           | 2.13                 | 2.13 + 2.13                            |
| 27 kΩ                                       | Active-High                           | 2.67                 | 2.67 + 2.67                            |
| 33 kΩ                                       | Active-High                           | 3.2                  | 3.2 + 3.2                              |
| 47 kΩ                                       | Active-Low                            | 0.53                 | 0.53 + 0.53                            |
| 56 kΩ                                       | Active-Low                            | 0.96                 | 0.96 + 0.96                            |
| 68 kΩ                                       | Active-Low                            | 1.07                 | 1.07 + 1.07                            |
| 82 kΩ                                       | Active-Low                            | 1.28                 | 1.28 + 1.28                            |
| 100 kΩ                                      | Active-Low                            | 1.6                  | 1.6 + 1.6                              |
| 120 kΩ                                      | Active-Low                            | 2.13                 | 2.13 + 2.13                            |
| 150 kΩ                                      | Active-Low                            | 2.67                 | 2.67 + 2.67                            |
| $V_{DD}$                                    | Active-Low                            | 3.2                  | 3.2 + 3.2                              |

**Note 1:** The total maximum current depends on power dissipation characteristics of the design (see Table 1-1).

#### 7.1.4 CURRENT LIMITING MODES

The UCS2112 current limiting has two modes: trip and constant current (variable slope). Either mode functions at all times when the port power switch is closed. When operating in the Detect power state, the current capacity at V<sub>BUS</sub> is limited to I<sub>BUS\_BYP</sub> as described in Section 6.1.1 "VBUS Bypass Switch".

#### 7.1.4.1 Trip Mode

When using trip current limiting, the UCS2112 USB port power switch functions as a low resistance switch and rapidly turns off if the current limit is exceeded. While operating using trip current limiting, the  $V_{BUS}$  output voltage will be held relatively constant (equal to the  $V_{S}$  voltage minus the  $R_{ON}\,x\,I_{BUS}$  current) for all current values up to the  $I_{LIM}.$ 

If the current drawn by a portable device exceeds  $\ensuremath{I_{\text{LIM}}},$  the following occurs:

- 1. The port power switch will be turned off (Trip action).
- 2. The UCS2112 will enter the Error state and assert the ALERT# pin.
- The fault handling circuitry will then determine subsequent actions.

Figure 7-1 shows operation of current limits in trip mode with the shaded area representing the USB 2.0 specified  $V_{BUS}$  range. Dashed lines indicate the port power switch output will go to zero (e.g., trip) when  $I_{LIM}$  is exceeded. Note that operation at all possible values of  $I_{LIM}$  are shown in Figure 7-1 for illustrative purposes only; in actual operation only one  $I_{LIM}$  can be active at any time.

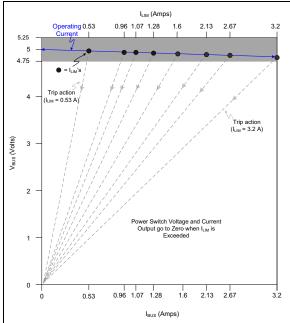


FIGURE 7-1: Current Limiting in Trip Mode.

## 7.1.4.2 Constant Current Limiting (Variable Slope)

Constant current limiting is used when the current drawn is greater than  $I_{LIM}$  (and  $I_{LIM} \leq 1.6A). In CC mode, the port power switch allows the attached portable device to reduce <math display="inline">V_{BUS}$  output voltage to less than the input  $V_S$  voltage while maintaining current delivery. The V/I slope depends on the user set  $_{ILIM}$  value. This slope is held constant for a given  $I_{LIM}$  value.

This mode is specifically provided for devices that rely on resistive means to reduce V<sub>BUS</sub> voltage for direct battery charging or to allow portable devices a means to "test" charger capacity. See Figure 7-2.

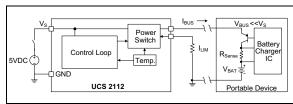


FIGURE 7-2: Constant Current Example.

Figure 7-3 shows operation of current limits while using CC mode. Unlike trip mode, once  $I_{BUS}$  current exceeds  $I_{LIM}$ , operation continues at a reduced voltage and increased current. Note that the shaded area representing the USB 2.0 specified  $V_{BUS}$  range is now restricted to an upper current limit of  $I_{BUS\_R2MIN}$ . Note that the UCS2112 will heat up along each load line as voltage decreases. If the internal temperature exceeds the  $T_{REG}$  or  $T_{TSD}$  thresholds, the port power switch will open. Also note that when the  $V_{BUS\_MIN}$ ), the port power switch will open.

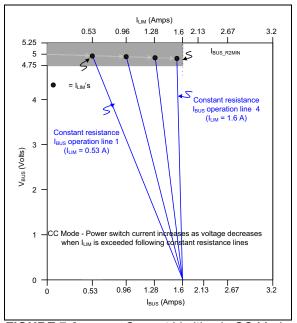


FIGURE 7-3: Current Limiting in CC Mode.

#### 7.2 USB Port Power Profiles

The UCS2112 combines the qualities of traditional USB port power switches with USB port power profiles set forth in the USB-IF BC1.2 specification. USB port power profiles consist of distinct voltage-current operation regions defined by "keep-out" and "operation" regions.

While operating in CC mode, the UCS2112 provides voltage-current output operating profiles that are specified by two keep-out regions.

If the current reaches the  $I_{BUS\_R2MIN}$  setting for longer than  $t_{MASK}$ , the UCS2112 enters the Error state and an Overcurrent event is flagged.

If the  $V_{BUS}$  voltage ever goes below the no operation lower-voltage keep-out ( $V_{BUS\_MIN}$ ) value for longer than  $t_{MASK}$ , the port power switch is disabled and a keep-out violation is flagged (by setting the MIN\_KEEP\_OUT Status bit). This will cause the device to enter the Error state.

Figure 7-4 illustrates the relationship between these USB port power profile parameters.

### 7.2.1 OPERATION WITHIN A USB PORT POWER PROFILE

An attached device may be constrained to operate within the boundaries of a USB port power profile by setting the value of  $I_{LIM}$  less than the USB port power profile  $I_{BUS\_R2MIN}$  value. In this case, the port power switch will be in Trip mode up until  $I_{LIM}$  is exceeded. At which point, the switch will transition into CC mode. If the attached device reduces the output voltage to less than  $V_{BUS\_MIN}$ , the switch will trip and terminate charging.

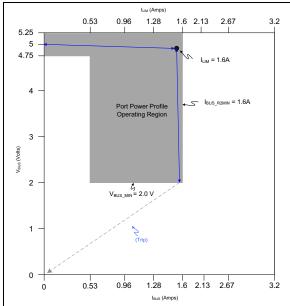


FIGURE 7-4:  $I_{LIM} < I_{BUS\_R2MIN}$  Example.

Note: The CC mode of operation is possible only up to 1.6A. As long as the value of I<sub>LIM</sub> is less than the fixed port power profile I<sub>BUS\_R2MIN</sub> value, CC mode is possible. Otherwise, the USB port power switch will operate in trip mode operation.

### 7.2.2 OPERATION OUTSIDE OF A USB PORT POWER PROFILE

An attached device may be allowed to operate outside of the boundaries of a USB port power profile by setting the value of I<sub>LIM</sub> greater than the USB port power profile I<sub>BUS\_R2MIN</sub> value. This is the default operation for all portable devices. In this case, the USB port power switch will operate in Trip mode until the bus current reaches the I<sub>LIM</sub> value. Once the I<sub>LIM</sub> value has been exceeded, the port power switch will open and terminate charging. Figure 7-5 illustrates an example of current limiting in this configuration.

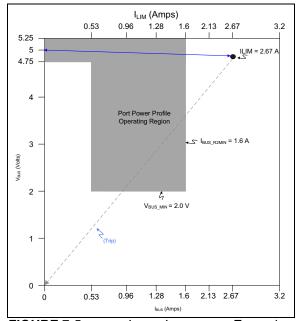


FIGURE 7-5:  $I_{LIM} > I_{BUS\_R2MIN}$  Example.

## 7.3 Thermal Management and Voltage Protection

#### 7.3.1 THERMAL MANAGEMENT

The UCS2112 utilizes two-stage internal thermal management. The first stage is Dynamic Thermal Management, and the second stage is Fixed Thermal Shutdown.

#### 7.3.1.1 Dynamic Thermal Management

For the first stage (active in both current-limiting modes), referred to as Dynamic Thermal Management, the UCS2112 automatically adjusts port power switch limits and modes to lower power dissipation when the thermal regulation temperature value is approached, as described in this section.

If the internal temperature exceeds the  $T_{REG}$  value, the port power switch is opened, the current limit ( $I_{LIM}$ ) will be lowered by one step and a timer is started ( $t_{DC\_TEMP}$ ). When this timer expires, the port power switch is closed and the internal temperature will be checked again. If it remains above the  $T_{REG}$  threshold, the UCS2112 will repeat this cycle (open port power switch and reduce the  $I_{LIM}$  setting by one step) until  $I_{LIM}$  reaches its minimum value.

If the UCS2112 is operating using Constant Current Limiting (variable slope) and the  $I_{LIM}$  setting has been reduced to its minimum set point and the temperature is still above  $T_{REG}$ , the UCS2112 will switch to operating using trip current limiting. This will be done by reducing the  $I_{BUS\_R2MIN}$  setting to 100 mA and restoring the  $I_{LIM}$  setting to the value immediately below the programmed setting (e.g., if the programmed  $I_{LIM}$  is 2.13A, the value will be set to 1.6A). If the temperature continues to remain above  $T_{REG}$ , the UCS2112 will continue this cycle (open the port power switch and reduce the  $I_{LIM}$  setting by one step).

If the UCS2112 internal temperature drops below  $T_{REG}$  -  $T_{REG\_HYST}$ , the UCS2112 will take action based on the following:

- If the Current Limit mode changed from CC mode to Trip mode, then a timer is started. When this timer expires, the UCS2112 will reset the port power switch operation to its original configuration, allowing it to operate using Constant Current Limiting (variable slope).
- If the Current Limit mode did not change from CC mode to Trip mode, or was already operating in Trip mode, the UCS2112 will reset the port power switch operation to its original configuration.

If the UCS2112 is operating using Trip Current Limiting and the  $I_{LIM}$  setting has been reduced to its minimum set point and the temperature is above  $T_{REG},$  the port power switch will be closed and the current limit will be held at its minimum setting until the temperature drops below  $T_{REG}$ - $T_{REG}$ HYST.

#### 7.3.1.2 Thermal Shutdown

The second stage of thermal management consists of a hardware implemented thermal shutdown corresponding to the maximum allowable internal die temperature ( $T_{TSD}$ ). If the internal temperature exceeds this value, the port power switches (both ports) will immediately be turned off until the temperature is below  $T_{TSD}$  -  $T_{TSD}$  HYST.

#### 7.4 V<sub>BUS</sub> Discharge

The UCS2112 will discharge  $V_{BUS}$  through an internal  $100\Omega$  resistor when at least one of the following conditions occurs:

- The PWR\_EN control is disabled (triggered on the inactive edge of the PWR\_EN control).
- A portable device Removal Detection event is flagged if the Attach/Removal Detect feature is enabled (by default it is disabled).
- The V<sub>S</sub> voltage drops below a specified threshold (V<sub>S\_UVLO</sub>) that causes the port power switch to be disabled.
- · When commanded into the Sleep power state.
- · Upon recovery from the Error state.
- When commanded via the SMBus in the Active state.
- Any time the port power switch is activated after the V<sub>BUS</sub> bypass switch has been on (i.e., whenever V<sub>BUS</sub> voltage transitions from being driven from V<sub>DD</sub> to being driven from V<sub>S</sub>, such as going from Detect to Active power state) if the Attach/Removal Detect feature is enabled (by default it is disabled).
- Any time the V<sub>BUS</sub> bypass switch is activated after the port power switch has been on (i.e., going from Active to Detect power state) if the Attach/Removal Detect feature is enabled (by default it is disabled).

When the  $V_{BUS}$  discharge circuitry is activated at the end of the  $t_{DISCHARGE}$  time, the UCS2112 will confirm that  $V_{BUS}$  was discharged. If the  $V_{BUS}$  voltage is not below the  $V_{TEST}$  level, a discharge error will be flagged (by setting the DISCH\_ERR(1/2) Status bit) and the UCS2112 will enter the Error state.

#### 7.5 Charge Rationing Interactions

When charge rationing is active, regardless of the specified behavior, the UCS2112 will function normally until the charge rationing threshold is reached. Note that charge rationing is only active when the UCS2112 is in the Active state, and it does not automatically reset when a Removal or Attach Detection event occurs. This allows charging of sequential portable devices while charge is being rationed, which means that the accumulated power given to several portable devices will still be held to the stated rationing limit.

Changing the charge rationing behavior will have no effect on the charge rationing data registers. If the behavior is changed prior to reaching the charge rationing threshold, this change will occur and be transparent to the user. When the charge rationing threshold is reached, the UCS2112 will take action as shown in Table 7-2. If the behavior is changed after the charge rationing threshold has been reached, the UCS2112 will immediately adopt the newly programmed behavior, clearing the ALERT# pin and restoring switch operation respectively (see Table 7-4).

TABLE 7-2: CHARGE RATIONING BEHAVIOR

| RTN_<br>(1 or 2) | _BEH<br>) <1:0> | Behavior                              | Actions taken   | Notes   |  |  |
|------------------|-----------------|---------------------------------------|---|---|--|--|
| 1                | 0               |                                       |   |   |  |  |
| 0                | 0               | Report                                | ALERT# pin asserted.  |   |  |  |
| 0                | 1               | Report and<br>Disconnect<br>(default) | ALERT# pin asserted.     Port power switch disconnected.  | All bus monitoring is still active.  Toggling the PWR_EN control will cause the device to change power states as defined by the registers; however, the port power switch will remain off until the rationing circuitry is reset. Furthermore, the bypass switch will not be turned on if enabled via the Attach Detection. |  |  |
| 1                | 0               | Disconnect<br>and<br>Go to Sleep      | <ol> <li>Port power switch disconnected.</li> <li>Device will enter the Sleep state.</li> </ol> | All $V_{BUS}$ and $V_{S}$ monitoring will be stopped. Toggling the PWR_EN control will have no effect on the power state until the rationing circuitry is reset.  |  |  |
| 1                | 1               | Ignore                                | Take no further action.   |   |  |  |

TABLE 7-3: CHARGE RATIONING RESET BEHAVIOR

| Behavior              | Reset Actions   |
|-----------------------|---|
| Report                | Reset the Total Accumulated Charge registers.   |
|                       | 2. Clear the RATION Status bit.   |
|                       | 3. Release the ALERT# pin.  |
| Report and Disconnect | Reset the Total Accumulated Charge registers.   |
|                       | 2. Clear the RATION Status bit.   |
|                       | 3. Release the ALERT# pin.  |
|                       | 4. Check the PWR_EN controls and enter the indicated power state if the controls changed. |
| Disconnect and        | Reset the Total Accumulated Charge registers.   |
| Go to Sleep           | 2. Clear the RATION Status bit.   |
|                       | 3. Check the PWR_EN controls and enter the indicated power state if the controls changed. |
| Ignore                | Reset the Total Accumulated Charge registers.   |
|                       | 2. Clear the RATION Status bit.   |

TABLE 7-4: EFFECTS OF CHANGING RATIONING BEHAVIOR AFTER THRESHOLD REACHED

| Previous<br>Behavior     | New Behavior                  | Actions Taken   |  |  |  |
|--------------------------|-------------------------------|---|--|--|--|
| Ignore                   | Report                        | Assert ALERT# pin.  |  |  |  |
|                          | Report and<br>Disconnect      | <ol> <li>Assert ALERT# pin.</li> <li>Open port power switch. See the Report and Disconnect (default) in<br/>Table 7-2.</li> </ol>   |  |  |  |
|                          | Disconnect and<br>Go to Sleep | <ol> <li>Open port power switch.</li> <li>Enter the Sleep state. See the Disconnect and Go to Sleep in Table 7-2.</li> </ol>  |  |  |  |
| Report                   | Ignore                        | Release ALERT# pin.   |  |  |  |
|                          | Report and<br>Disconnect      | Open port power switch. See the Report and Disconnect (default) in Table 7-2.   |  |  |  |
|                          | Disconnect and<br>Go to Sleep | <ol> <li>Release the ALERT# pin.</li> <li>Open the port power switch.</li> <li>Enter the Sleep state. See the Disconnect and Go to Sleep in Table 7-2.</li> </ol>               |  |  |  |
| Report and<br>Disconnect | Ignore                        | <ol> <li>Release the ALERT# pin.</li> <li>Check the PWR_EN controls and enter the indicated power state if the controls changed.</li> </ol>                                     |  |  |  |
|                          | Report                        | Check the PWR_EN controls and enter the indicated power state if the control changed.   |  |  |  |
|                          | Disconnect and                | Release the ALERT# pin.   |  |  |  |
|                          | Go to Sleep                   | 2. Enter the Sleep state. See the Disconnect and Go to Sleep in Table 7-2.  |  |  |  |
| Disconnect and go to     | Ignore                        | Check the PWR_EN controls and enter the indicated power state if the controls changed.  |  |  |  |
| Sleep                    | Report                        | <ol> <li>Assert the ALERT# pin.</li> <li>Check the PWR_EN controls and enter the indicated power state if the controls changed.</li> </ol>                                      |  |  |  |
|                          | Report and<br>Disconnect      | Assert the ALERT# pin.     Check the PWR_EN controls to determine the power state then enter that state except that the port power switch and bypass switch will not be closed. |  |  |  |

If the RTN\_EN control is set to '0' prior to reaching the charge rationing threshold, rationing will be disabled and the Total Accumulated Charge registers will be cleared. If the RTN\_EN control is set to '0' after the charge rationing threshold has been reached, the following additional steps occur:

- 1. RATION Status bit will be cleared.
- The ALERT# pin will be released if asserted by the rationing circuitry and no other conditions are present.
- 3. The PWR\_EN controls are checked to determine the power state.

Setting the RTN\_RST control to '1' will automatically reset the Total Accumulated Charge registers to 00\_00h. If this is done prior to reaching the charge rationing threshold, the data will continue to be accumulated restarting from 00\_00h. If this is done after the charge rationing threshold is reached, the UCS2112 will take action as shown in Table 7-3.

#### 7.6 Fault Handling Mechanism

The UCS2112 has two modes for handling faults:

- · Latch (latch-upon-fault)
- Auto-recovery (automatically attempt to restore the Active power state after a fault occurs).

If the SMBus is actively utilized, auto-recovery fault handling is the default error handler as determined by the LATCH\_SET bit. Faults include overcurrent, overvoltage (on  $V_{\text{S}}$ ), undervoltage (on  $V_{\text{BUS}}$ ), back-voltage ( $V_{\text{BUS}}$  to  $V_{\text{S}}$  or  $V_{\text{BUS}}$  to  $V_{\text{DD}}$ ), discharge error, and maximum allowable internal die temperature ( $T_{\text{TSD}}$ ) exceeded. Faults do not include keep-out violations except  $V_{\text{BUS}}$   $_{\text{MIN}}$ .

### 7.6.1 AUTO-RECOVERY FAULT HANDLING

When the LATCH\_SET bit is low, auto-recovery fault handling is used. When an error condition is detected, the UCS2112 will immediately enter the Error state and assert the ALERT# pin. Independently from the host controller, the UCS2112 will wait a preset time (t<sub>CYCLE</sub>), check error conditions (t<sub>TST</sub>), and restore Active operation if the error condition(s) no longer exist. If all other conditions that may cause the ALERT# pin to be asserted have been removed, the ALERT# pin will be released. A short-circuit auto-recovery example is provided in Figure 7-6.

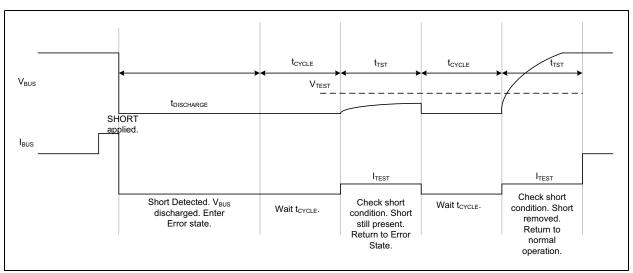


FIGURE 7-6: Error Recovery.

#### 7.6.2 LATCHED FAULT HANDLING

When the LATCH\_SET bit is high, latch fault handling is used. When an error condition is detected, the UCS2112 will enter the Error power state and assert the ALERT# (1 or 2) pin. Upon command from the host controller (by toggling the PWR\_EN (1, or 2) pin control from enabled to disabled or by clearing the ERR bit via SMBus), the UCS2112 will check error conditions once and restore Active operation if error conditions no longer exist. If an error condition still exists, the host controller is required to issue the command again to check error conditions.

If the ALERT# pin is asserted and the Interrupt Status registers (addresses 03h or 04h) are not read, the corresponding ALERT# pin remains asserted until the corresponding PWR\_EN pin is toggled.

If the ALERT# pin is asserted and the Interrupt Status registers are read, the ALERT# pin will deassert, but the UCS will remain in error state until the ERR bit is cleared via SMBus or the PWR\_EN pin is toggled.

## 8.0 SYSTEM MANAGEMENT BUS PROTOCOL

In SMBus mode, the UCS2112 communicates with a host controller, such as an Microchip PIC<sup>®</sup> microcontroller or hub, through the SMBus. The SMBus is a two-wire serial communication protocol between a computer host and its peripheral devices. A detailed timing diagram is shown in Figure 1-1. Stretching of the SMCLK signal is supported; however, the UCS2112 will not stretch the clock signal.

#### 8.1 SMBus Start Bit

The SMBus Start bit is defined as a transition of the SMBus Data line from a logic '1' state to a logic '0' state while the SMBus Clock line is in a logic '1' state.

#### 8.2 SMBus Address and RD/WR Bit

The SMBus Address Byte consists of the 7-bit client address followed by the RD/WR indicator bit. If this RD/WR bit is a logic '0', the SMBus Host is writing data to the client device. If this RD/WR bit is a logic '1', the SMBus Host is reading data from the client device.

The UCS2112 with the order code UCS2112-1-V/G4 has the SMBus address 57h - 1010 111(r/w).

Customers should contact their distributor, representatives or field application engineer (FAE) for additional SMBus addresses. Local sales offices are also available to help customers. A list of sales offices and locations is included in the back of this document.

#### 8.3 SMBus Data Bytes

All SMBus Data bytes are sent Most Significant bit first and composed of 8 bits of information.

#### 8.4 SMBus ACK and NACK Bits

The SMBus client will acknowledge all data bytes that it receives. This is done by the client device pulling the SMBus Data line low after the 8th bit of each byte that is transmitted. This applies to both the Write Byte and Block Write protocols.

The Host will NACK (not acknowledge) the last data byte to be received from the client by holding the SMBus data line high after the 8th data bit has been sent. For the Block Read protocol, the Host will ACK (acknowledge) each data byte that it receives except the last data byte.

#### 8.5 SMBus Stop Bit

The SMBus Stop bit is defined as a transition of the SMBus Data line from a logic '0' state to a logic '1' state while the SMBus clock line is in a logic '1' state. When the UCS2112 detects an SMBus Stop bit and it has been communicating with the SMBus protocol, it will reset its client interface and prepare to receive further communications.

#### 8.6 SMBus Time-out

The UCS2112 includes an SMBus time-out feature. If the clock is held at logic '0' for  $t_{TIMEOUT}$ , the device can time out and reset the SMBus interface. The SMBus interface can also reset if both the clock and data lines are held at a logic '1' for  $t_{IDLE\_RESET}$ . Communication is restored with a Start condition.

The time-out function defaults to disabled. It can be enabled by clearing the DIS\_TO bit in the General Configuration 3 register (see Register 9-9).

#### 8.7 SMBus and I<sup>2</sup>C Compliance

The major difference between SMBus and I<sup>2</sup>C devices is highlighted in this section. For complete compliance information, refer to the SMBus 2.0 specification and Application Note AN14.0 "*Microchip Dedicated Slave Devices in I*<sup>2</sup>C Systems" (DS00001853).

- UCS2112 supports I<sup>2</sup>C fast mode at 400 kHz. This covers the SMBus maximum time of 100 kHz.
- The minimum frequency for SMBus communications is 10 kHz.
- The client protocol will reset if the clock is held low longer than 30 ms. This time-out functionality is disabled by default in the UCS2112 and can be enabled by clearing the DIS\_TO bit. I<sup>2</sup>C does not have a time out.
- Except when operating in Sleep, the client protocol will reset if both the clock and the data line are logic '1' for longer than 200 μs (Idle condition). This function is disabled by default in the UCS2112 and can be enabled by clearing the DIS TO bit. I<sup>2</sup>C does not have an Idle condition.
- I<sup>2</sup>C devices do not support the Alert Response Address functionality (which is optional for SMBus).
- I<sup>2</sup>C devices support block read and write differently. I<sup>2</sup>C protocol allows for unlimited number of bytes to be sent in either direction. The SMBus protocol requires that an additional data byte indicating number of bytes to read/write is transmitted. The UCS2112 supports I<sup>2</sup>C formatting only.

#### 8.8 SMBus Protocols

The UCS2112 is SMBus 2.0-compatible and supports Send Byte, Read Byte, Block Read, Receive Byte as valid protocols as shown below. The UCS2112 also supports the I<sup>2</sup>C block read and block write protocols. The device supports Write Byte, Read Byte, and Block Read/Block Write. All of the below protocols use the convention in Table 8-1.

TABLE 8-1: SMBUS PROTOCOL

| Data Sent to Device | Data Sent to the Host |  |  |  |
|---------------------|-----------------------|--|--|--|
| Data sent           | Data sent             |  |  |  |

#### 8.9 SMBus Write Byte

The Write Byte is used to write one byte of data to a specific register as shown in Table 8-2.

TABLE 8-2: WRITE BYTE PROTOCOL

| START | Slave<br>Address | WR | ACK | Reg. Addr. | ACK | Register Data | ACK | STOP  |
|-------|------------------|----|-----|------------|-----|---------------|-----|-------|
| 1 → 0 | YYYY_YYY         | 0  | 0   | XXh        | 0   | XXh           | 0   | 0 → 1 |

#### 8.10 SMBus Read Byte

The Read Byte protocol is used to read one byte of data from the registers as shown in Table 8-3.

TABLE 8-3: READ BYTE PROTOCOL

| START | Slave Address | WR | ACK | Register Address | ACK  |       |
|-------|---------------|----|-----|------------------|------|-------|
| 1 → 0 | YYYY_YYY      | 0  | 0   | XXh              | 0    |       |
| START | Slave Address | RD | ACK | Register Data    | NACK | STOP  |
| 1 → 0 | YYYY_YYY      | 1  | 0   | XXh              | 1    | 0 → 1 |

#### 8.11 Block Write

The Block Write is used to write multiple data bytes to a group of contiguous registers, as shown in Table 8-4. It is an extension of the Write Byte Protocol.

Note: The Block Write and Block Read protocols require that the Address Pointer be automatically incremented. For a write command, the Address Pointer will be automatically incremented when the ACK is sent to the host. There are no over or under bound limit checking and the Address Pointer will wrap around from FFh to 00h if necessary.

TABLE 8-4: BLOCK WRITE PROTOCOL

| START | Slave Address | WR | ACK | Register<br>Address | ACK | Repeat N Times |     | STOP  |
|-------|---------------|----|-----|---------------------|-----|----------------|-----|-------|
| SIAKI |               |    |     |                     |     | Register Data  | ACK | 0101  |
| 1 → 0 | YYYY_YYY      | 0  | 0   | XXh                 | 0   | XXh            | 0   | 0 → 1 |

#### 8.12 Block Read

The Block Read is used to read multiple data bytes from a group of contiguous registers, as shown in Table 8-5. It is an extension of the Read Byte Protocol.

TABLE 8-5: BLOCK READ PROTOCOL

| START | Slave Address | WR | ACK | Register<br>Address | ACK |               |      |       |
|-------|---------------|----|-----|---------------------|-----|---------------|------|-------|
| 1 → 0 | YYYY_YYY      | 0  | 0   | XXh                 | 0   |               |      |       |
| START | Slave Address | RD | ACK | Repeat N Times      |     | Degister Dete | NACK | STOP  |
| SIAKI |               |    |     | Register Data       | ACK | Register Data | NACK | 3105  |
| 1 → 0 | YYYY_YYY      | 1  | 0   | XXh                 | 0   | XXh           | 1    | 0 → 1 |

#### 8.13 SMBus Send Byte

The Send Byte protocol is used to set the internal address register pointer to the correct address location. No data is transferred during the Send Byte protocol as shown in Table 8-6.

Note 1: The SMBus Send Byte command is expected to be followed by the SMBus Receive Byte command. When two SMbus Send Byte commands are sent in a row, the first command receives an ACK and will be processed by the UCS2112, but the second command receives a NACK, and will be ignored.

#### TABLE 8-6: SEND BYTE PROTOCOL

| START | Slave Address | WR | ACK | Register Address | ACK | STOP  |
|-------|---------------|----|-----|------------------|-----|-------|
| 1 → 0 | YYYY_YYY      | 0  | 0   | XXh              | 0   | 0 → 1 |

#### 8.14 SMBus Receive Byte

The Receive Byte protocol is used to read data from a register when the internal register Address Pointer is known to be at the right location (e.g., set via Send Byte). This is used for consecutive reads of the same register as shown in Table 8-7.

TABLE 8-7: RECEIVE BYTE PROTOCOL

| START | Slav | ve Address | RD | ACK | Register Data | NACK | STOP  |
|-------|------|------------|----|-----|---------------|------|-------|
| 1 → 0 | Y    | YYY_YYY    | 1  | 0   | XXh           | 1    | 0 → 1 |

#### 8.14.1 STAND-ALONE OPERATING MODE

Stand-alone mode allows the UCS2112 to operate without active SMBus/l $^2$ C communications. Stand-alone mode can be enabled by connecting a pull-down resistor greater or equal to 47 k $\Omega$  on the COMM\_ILIM pin as shown in Table 5-3.The SMCLK pin should be tied to ground in this mode.

### 9.0 REGISTER DESCRIPTION

The registers shown in Table 9-1 are accessible through the SMBus or I<sup>2</sup>C. An entry of '—' indicates that the bit is not used. Writing to these bits will have no effect and reading these bits will return '0'. Writing to a reserved bit may cause unexpected results and reading from a reserved bit will return either '1' or '0' as indicated in the bit description. While in the Sleep state, the UCS2112 will retain configuration and charge rationing data as indicated in the text. If a register does not indicate that data will be retained in the Sleep power state, this information will be lost when the UCS2112 enters the Sleep power state.

TABLE 9-1: REGISTER SET IN HEXADECIMAL ORDER

| Register<br>Address | Register Name                                       | R/W      | Function   | Default<br>Value | Page<br>No. |
|---------------------|---|----------|--|------------------|-------------|
| 00h                 | Port 1 Current Measurement                          | R        | Stores the current measurement for port 1                              | 00h              | 38          |
| 01h                 | Port 2 Current Measurement                          | R        | Stores the current measurement for port 2                              | 00h              | 38          |
| 02h                 | V <sub>BUS</sub> Port Status                        | R        | Indicates Load Share V <sub>BUS</sub> Port and general status          | 00h              | 39          |
| 03h                 | Interrupt Status1                                   | See Text | Indicates why ALERT# pin asserted for port 1                           | 00h              | 40          |
| 04h                 | Interrupt Status2                                   | See Text | Indicates why ALERT# pin asserted for port 2                           | 00h              | 42          |
| 0Fh                 | General Status1                                     | R/R-C    | Indicates General Status for port 1                                    | 00h              | 44          |
| 10h                 | General Status2                                     | R/R-C    | Indicates General Status for port 2                                    | 00h              | 45          |
| 11h                 | General Configuration1                              | R/W      | Controls basic functionality for port 1                                | 06h              | 46          |
| 12h                 | General Configuration2                              | R/W      | Controls basic functionality for port 2                                | 02h              | 47          |
| 13h                 | General Configuration3                              | R/W      | Controls other functionality   | 60h              | 48          |
| 14h                 | Current Limit                                       | R/W      | Controls/Displays MAX Current Limit per port                           | 00h              | 49          |
| 15h                 | Auto-Recovery Configuration                         | R/W      | Controls the auto-recovery functionality                               | 2Ah              | 50          |
| 16h                 | Port 1 Total Accumulated<br>Charge High Byte        | R        | Stores the total accumulated charge delivered high byte, Port 1        | 00h              | 51          |
| 17h                 | Port 1 Total Accumulated<br>Charge Middle High Byte | R        | Stores the total accumulated charge delivered middle high byte, Port 1 | 00h              | 51          |
| 18h                 | Port 1 Total Accumulated<br>Charge Middle Low Byte  | R        | Stores the total accumulated charge delivered middle low byte, Port 1  | 00h              | 51          |
| 19h                 | Port 1 Total Accumulated<br>Charge Low Byte         | R        | Stores the total accumulated charge delivered low byte, Port 1         | 00h              | 51          |
| 1Ah                 | Port 2 Total Accumulated<br>Charge High Byte        | R        | Stores the total accumulated charge delivered high byte, Port 2        | 00h              | 52          |
| 1Bh                 | Port 2 Total Accumulated<br>Charge Middle High Byte | R        | Stores the total accumulated charge delivered middle high byte, Port 2 | 00h              | 52          |
| 1Ch                 | Port 2 Total Accumulated<br>Charge Middle Low Byte  | R        | Stores the total accumulated charge delivered middle low byte, Port 2  | 00h              | 52          |
| 1Dh                 | Port 2 Total Accumulated<br>Charge Low Byte         | R        | Stores the total accumulated charge delivered low byte, Port 2         | 00h              | 52          |
| 1Eh                 | Port 1 Charge Rationing<br>Threshold High Byte      | R/W      | Sets the maximum allowed charge that will be delivered to Port 1       | FFh              | 53          |
| 1Fh                 | Port 1 Charge Rationing<br>Threshold Low Byte       | R/W      | Sets the maximum allowed charge that will be delivered to Port 1       | FFh              | 53          |
| 20h                 | Port 2 Charge Rationing<br>Threshold High Byte      | R/W      | Sets the maximum allowed charge that will be delivered to Port 2       | FFh              | 53          |

TABLE 9-1: REGISTER SET IN HEXADECIMAL ORDER (CONTINUED)

| Register<br>Address | Register Name                                 | R/W | Function  | Default<br>Value | Page<br>No. |
|---------------------|---|-----|---|------------------|-------------|
| 21h                 | Port 2 Charge Rationing<br>Threshold Low Byte | R/W | Sets the maximum allowed charge that will be delivered to Port 2        | FFh              | 53          |
| 22h                 | Ration Configuration                          | R/W | Controls Charge Ration Functionality                                    | 11h              | 54          |
| 23h                 | Port 1 Current Limit Behavior                 | R/W | Controls the Current Limiting Behavior (CC<br>Mode Region 2) for Port 1 | 96h              | 55          |
| 24h                 | Port 2 Current Limit Behavior                 | R/W | Controls the Current Limiting Behavior (CC Mode Region 2) for Port 2    | 96h              | 55          |
| FDh                 | Product ID                                    | R   | Stores a fixed value that identifies each product                       | E1h              | 56          |
| FEh                 | Manufacturer ID                               | R   | Stores a fixed value that identifies Microchip                          | 5Dh              | 56          |
| FFh                 | Revision                                      | R   | Stores a fixed value that represents the revision number                | 81h              | 56          |

# 9.1 Current Measurement Register

The Current Measurement register stores the measured current value delivered to the portable device (I<sub>BUS</sub>). This value is updated continuously while the device is in the Active power state.

# REGISTER 9-1: PORTS 1 AND 2 CURRENT MEASUREMENT REGISTERS (ADDRESSES 00H, 01H)

| R-0        | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0   |
|------------|-----|-----|-----|-----|-----|-----|-------|
| CM(x)<7:0> |     |     |     |     |     |     |       |
| bit 7      |     |     |     |     |     |     | bit 0 |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit |                    |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7:0 **CM(x)<7:0>:** Port X Current Measurement, where x = 1 or 2 (address 00h for Port 1 and address 01h for Port 2)  $^{(1)}$   $^{(2)}$ .
- Note 1: The bit weights are in mA,1 LSB = 13.3 mA (maximum value is 255 LSB corresponding to 3.4A).
  - **2:** This data will be cleared when the device enters the Sleep or Detect states. This data will also be cleared whenever the port power switch is turned off (or any time that V<sub>BUS</sub> is discharged).

### 9.2 Status Registers

The Status registers store bits that indicate error conditions as well as Attach Detection and Removal Detection.

### REGISTER 9-2: V<sub>BUS</sub> PORT STATUS REGISTER (ADDRESS 02H)

| R-0        | R-0        | R-0      | R-0      | U-0 | U-0 | R-0       | R-0       |
|------------|------------|----------|----------|-----|-----|-----------|-----------|
| ALERT2_PIN | ALERT1_PIN | CC_MODE2 | CC_MODE1 | _   | _   | ADET2_PIN | ADET1_PIN |
| bit 7      |            |          |          |     |     |           | bit 0     |

| Legend:           |                  |                        |                  |
|-------------------|------------------|------------------------|------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit  |                  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared x | = Bit is unknown |

bit 7 ALERT2\_PIN: Reflects the status of the ALERT#2 pin. This bit is set and cleared as the ALERT#2 pin changes states.

1 = ALERT#2 Pin asserted (logic low)

0 = ALERT#2 Pin not asserted

bit 6 ALERT1\_PIN: Reflects the status of the ALERT#1 pin. This bit is set and cleared as the ALERT#1 pin changes states.

1 = ALERT#1 Pin asserted (logic low)

0 = ALERT#1 Pin not asserted

bit 5 CC\_MODE2: Port2 Constant Current Mode State

1 = Port 2 in Constant Current mode

0 = Port 2 operating normally

bit 4 CC\_MODE1: Port1 Constant Current Mode State

1 = Port 1 in Constant Current mode

0 = Port 1 operating normally

bit 3-2 Unimplemented

bit 1 **ADET2:\_PIN** Reflects the status of the A\_DET#2 pin. When set, indicates that the A\_DET#2 pin is asserted low. This bit is set and cleared as the A\_DET#2 pin changes states.

1 = A\_DET#2 pin is asserted (logic low)

0 = A\_DET#2 pin is not asserted

bit 0 **ADET1\_PIN:** Reflects the status of the A\_DET#1 pin. When set, indicates that the A\_DET#1 pin is asserted low. This bit is set and cleared as the A\_DET#1 pin changes states.

1 = A DET#1 pin is asserted (logic low)

0 = A\_DET#1 pin is not asserted

#### REGISTER 9-3: INTERRUPT STATUS 1 REGISTER (ADDRESS 03H)

| R/W-0    | R/C-0      | R/C-0 | R/C-0     | R/C-0 | R/C-0   | R/C-0   | R/C-0   |
|----------|------------|-------|-----------|-------|---------|---------|---------|
| ERR1 (1) | DISCH_ERR1 | RESET | KEEP_OUT1 | TSD   | OV_VOLT | BACK_V1 | OV_LIM1 |
| bit 7    |            |       |           |       | •       |         | bit 0   |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit | C = Clear on Read  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

bit 7 **ERR1:** Error Port 1 - Indicates that an error was detected on the V<sub>BUS1</sub> pin and the device entered the Error state. Writing this bit to '0' will clear the Error state and allows the device to be returned to the Active state. When written to '0', all error conditions are checked. If all error conditions have been removed, the UCS2112 returns to the Active state. This bit is set automatically by the UCS2112 when the Error state is entered. If any other bit is set in the Interrupt Status register (03h), the device will not leave the Error state.

This bit is cleared automatically by the UCS2112 if the auto-recovery fault handling functionality is active and no error conditions are detected. Likewise, this bit is cleared when the PWR\_EN1 control is disabled (Note 1).

- 1 = Port 1 in Error State.
- 0 = Port 1 in Active State (no errors detected).
- bit 6 **DISCH\_ERR1:** Discharge Error Port 1 indicates the device was unable to discharge Port1. This bit will be cleared when read if the error condition has been removed or if the ERR bit is cleared. This bit will cause the ALERT#1 pin to be asserted and the device to enter the Error state.
  - 1 = UCS2112 was unable to discharge  $V_{BUS1}$ .
  - $0 = No V_{BUS1}$  discharge error.
- bit 5 **RESET:** Indicates that the UCS2112 has just been reset and should be re-programmed. This bit will be set at power-up. This bit is cleared when read or when the PWR\_EN control is toggled. The ALERT# pins are not asserted when this bit is set. This data is retained in the Sleep state.
  - 1 = UCS2112 has just been reset.
  - 0 = Reset did not occur.
- bit 4 **KEEP\_OUT1:** Port 1 Minimum Keep-out region Indicates that the V-I output on the V<sub>BUS1</sub> pin has dropped below V<sub>BUS\_MIN.</sub> This bit will be cleared when read if the error condition has been removed or if the ERR1 bit is cleared. This bit will cause the ALERT#1 pin to be asserted and the device to enter the Error state.
  - 1 = V<sub>BUS1</sub> < V<sub>BUS MIN</sub>
  - $0 = V_{BUS1} > V_{BUS\ MIN}$
- bit 3 **TSD:** Thermal Shutdown Indicates that the internal temperature has exceeded T<sub>TSD</sub> threshold and the device has entered the Error state. This bit will be cleared when read if the error condition has been removed or if the ERR1 bit is cleared. This bit will cause the ALERT#1and ALERT#2 pins to be asserted and the device to enter the Error state.
  - 1 = Thermal Shutdown Temperature reached.
  - 0 = Internal temperature < T<sub>TSD</sub>
- bit 2  $\text{OV\_VOLT: } V_S$  Overvoltage Indicates that the  $V_S$  voltage has exceeded the  $V_{S\_OV}$  threshold, and the device has entered the Error state. This bit will be cleared when read if the error condition has been removed or if the ERR1 bit is cleared. This bit will cause the ALERT#1 and ALERT#2 pins to be asserted and the device to enter the Error state.
  - $1 = V_S > V_{S OV}$
  - $0 = V_S < V_{SOV}$

#### REGISTER 9-3: INTERRUPT STATUS 1 REGISTER (ADDRESS 03H) (CONTINUED)

- bit 1 **BACK\_V1:** Back-Bias Voltage Port 1 Indicates that the V<sub>BUS1</sub> voltage has exceeded the V<sub>S</sub> or V<sub>DD</sub> voltages by more than 150 mV. This bit will be cleared when read if the error condition has been removed or if the ERR1 bit is cleared. This bit will cause the ALERT#1 pin to be asserted and the device to enter the Error state.
  - 1 =  $V_{BUS1} > V_S$ , or  $V_{BUS1} > V_{DD}$  by more than 150 mV.
  - $_{0}$  =  $V_{RIIS1}$  voltage has not exceeded the  $V_{S}$  and  $V_{DD}$  voltages by more than 150 mV.
- bit 0 **OV\_LIM1:** Overcurrent Limit Port 1 Indicates that the I<sub>BUS</sub> current has exceeded both the I<sub>LIM</sub> threshold and the I<sub>BUS\_R2MIN</sub> threshold settings for V<sub>BUS1</sub>. This bit will be cleared when read if the error condition has been removed or if the ERR1 bit is cleared. This bit will cause the ALERT#1 pin to be asserted and the device to enter the Error state.
  - 1 = Current Limit for Port 1 exceeded
  - 0 = Current Limit for Port 1 not exceeded
- **Note 1:** Note that the ERR1 bit does not necessarily reflect the ALERT#1 pin status. The ALERT#1 pin may be cleared or asserted without the ERR1 bit changing states.

#### REGISTER 9-4: INTERRUPT STATUS 2 REGISTER (ADDRESS 04H)

| R/W-0    | R/C-0      | R-0    | R/C-0     | R/C-0 | U-0 | R/C-0   | R/C-0   |
|----------|------------|--------|-----------|-------|-----|---------|---------|
| ERR2 (1) | DISCH_ERR2 | VS_LOW | KEEP_OUT2 | TREG  | _   | BACK_V2 | OV_LIM2 |
| bit 7    |            |        |           |       |     |         | bit 0   |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit | C = Clear on Read  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7 ERR2: Error Port 2 Indicates that an error was detected on the V<sub>BUS1</sub> pin and the device entered the Error state. Writing this bit to a '0' will clear the Error state and allows the device to be returned to the Active state. When written to '0', all error conditions are checked. If all error conditions have been removed, the UCS2112 returns to the Active state. This bit is set automatically by the UCS2112 when the Error state is entered. If any other bit is set in the Interrupt Status register (04h), the device will not leave the Error state. This bit is cleared automatically by the UCS2112 if the auto-recovery fault handling functionality is active and no error conditions are detected. Likewise, this bit is cleared when the PWR EN2 control is disabled (Note 1).
  - 1 = Port 2 in Error State.
  - 0 = Port 2 in Active State (no errors detected).
- bit 6 **DISCH\_ERR2:** Discharge Error Port 2 indicates the device was unable to discharge Port2. This bit will be cleared when read if the error condition has been removed or if the ERR bit is cleared. This bit will cause the ALERT#2 pin to be asserted and the device to enter the Error state.
  - 1 = Device was unable to discharge  $V_{BUS2}$ .
  - $0 = No V_{BUS2}$  discharge error.
- bit 5  $VS\_LOW$ : Indicates that the  $V_S$  voltage has fallen below the  $V_{S\_UVLO}$  threshold and both  $V_{BUS1}$  and  $V_{BUS2}$  port power switches are held off. This bit is cleared automatically when the  $V_S$  voltage is above the  $V_S$  UVLO threshold.
  - 1 = V<sub>S</sub> voltage has fallen below the V<sub>S UVLO</sub>.
  - $0 = V_S$  voltage is above  $V_{S\_UVLO}$ .
- bit 4 **KEEP\_OUT2:** Port 2 Minimum Keep-out region Indicates that the V-I output on the V<sub>BUS2</sub> pin has dropped below V<sub>BUS\_MIN</sub>. This bit will be cleared when read if the error condition has been removed or if the ERR2 bit is cleared. This bit will cause the ALERT#2 pin to be asserted and the device to enter the Error state.
  - 1 = V<sub>BUS2</sub> < V<sub>BUS MIN</sub>
  - $0 = V_{BUS2} > V_{BUS\_MIN}$
- bit 3 **TREG:** Thermal Regulation Indicates that the internal temperature has exceeded T<sub>REG</sub> and that the current limit has been reduced. This bit is cleared when read and will not cause the ALERT#1 and ALERT#2 pins to be asserted unless the ALERT LINK bit is set.
  - 1 = Internal temperature > T<sub>REG</sub>
  - 0 = Internal temperature < T<sub>REG</sub>
- bit 2 Unimplemented: Read as '0'
- bit 1 **BACK\_V2:** Back-Bias Voltage Port 2 Indicates that the V<sub>BUS2</sub> voltage has exceeded the V<sub>S</sub> or V<sub>DD</sub> voltages by more than 150 mV. This bit will be cleared when read if the error condition has been removed or if the ERR2 bit is cleared. This bit will cause the ALERT#2 pin to be asserted and the device to enter the Error state.
  - 1 =  $V_{BUS2} > V_S$ , or  $V_{BUS2} > V_{DD}$  by more than 150 mV.
  - $_{0}$  =  $V_{BUS2}$  voltage has not exceeded the  $V_{S}$  and  $V_{DD}$  voltages by more than 150 mV.

# REGISTER 9-4: INTERRUPT STATUS 2 REGISTER (ADDRESS 04H) (CONTINUED)

- bit 0 **OV\_LIM2:** Overcurrent Limit Port 2 Indicates that the I<sub>BUS</sub> current has exceeded both the I<sub>LIM</sub> threshold and the I<sub>BUS\_R2MIN</sub> threshold settings for V<sub>BUS2</sub>. This bit will be cleared when read if the error condition has been removed or if the ERR2 bit is cleared. This bit will cause the ALERT#2 pin to be asserted and the device to enter the Error state.
  - 1 = Current Limit for Port 2 exceeded
  - 0 = Current Limit for Port 2 not exceeded.
- **Note 1:** Note that the ERR2 bit does not necessarily reflect the ALERT#2 pin status. The ALERT#2 pin may be cleared or asserted without the ERR2 bit changing states.

#### REGISTER 9-5: GENERAL STATUS 1 REGISTER (ADDRESS 0FH)

| R/C-0   | U-x | U-x | R-0      | R-0         | R/C-0    | R/C-0 | R-0   |
|---------|-----|-----|----------|-------------|----------|-------|-------|
| RATION1 | _   | _   | CC_MODE1 | PWR_EN1_CON | LOW_CUR1 | REM1  | ADET1 |
| bit 7   |     |     |          |             |          |       | bit 0 |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit | C = Clear on Read  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7 RATION1: Indicates the state of Port 1 Rationing. This bit is cleared when read, or cleared automatically when the RTN RST1 bit is set or the RTN EN1 bit is cleared.
  - 1 = Port 1 has delivered the programmed mAh of current
  - 0 = Port 1 has not delivered the programmed mAh of current
- bit 6-5 Unimplemented
- bit 4 **CC\_MODE1:** Indicates whether Port 1 has entered CC mode.
  - 1 = Port 1 is in CC mode
  - 0 = Port 1 not in CC mode
- bit 3 **PWR\_EN1\_CON:** Reflects the PWR\_EN control state. This bit is set and cleared automatically with the logic expression: (PWR\_EN1 pin OR PWR\_EN1S).
  - 1 = Port 1 Power Enable is set
  - 0 = Port 1 Power Enable is clear
- bit 2 **LOW\_CUR1:** Indicates if the portable device charge current is below the 13.3 mA threshold on the V<sub>BUS1</sub> and may have finished charging. This bit is cleared when read and will cause the ALERT#1 pin to be asserted if the ALERT LINK1 bit is set.
  - 1 = Port 1 charging current less than threshold
  - 0 = Port 1 charging current above threshold
- bit 1 **REM1:** Removal Detection Port1 Indicates if a Removal Detection event has occurred and there is no longer a portable device present on the V<sub>BUS1</sub> pin. This bit is cleared when read and will not cause the ALERT#1 pin to be asserted.
  - 1 = Removal Detection occurred
  - 0 = No Removal Detection
- bit 0 **ADET1:** Attach Detection Port1 Indicates that an Attach Detection event has occurred on the V<sub>BUS1</sub> pins and there is a new portable device present. Asserts the A\_DET#1 pin. This bit is set and cleared as the A\_DET#1 pin changes.
  - 1 = Attach Detection event has occurred. A\_DET#1 pin asserted
  - 0 = No Attach Detection event

#### REGISTER 9-6: GENERAL STATUS 2 REGISTER (ADDRESS 10H)

| R/C-0   | U-x | U-x | R-0      | R-0         | R/C-0    | R/C-0 | R-0   |
|---------|-----|-----|----------|-------------|----------|-------|-------|
| RATION2 | _   | _   | CC_MODE2 | PWR_EN2_CON | LOW_CUR2 | REM2  | ADET2 |
| bit 7   |     |     |          |             |          |       | bit 0 |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit | C = Clear on Read  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7 RATION2: Indicates the state of Port 2 Rationing. This bit is cleared when read, or cleared automatically when the RTN RST2 bit is set or the RTN EN2 bit is cleared.
  - 1 = Port 2 has delivered the programmed mAh of current
  - 0 = Port 2 has not delivered the programmed mAh of current
- bit 6-5 Unimplemented
- bit 4 **CC\_MODE2:** Indicates whether Port 2 has entered CC mode.
  - 1 = Port 2 is in CC mode
  - 0 = Port 2 not in CC mode
- bit 3 **PWR\_EN2\_CON:** Reflects the PWR\_EN control state. This bit is set and cleared automatically with the logic expression: (PWR\_EN2 pin OR. PWR\_EN2S).
  - 1 = Port 2 Power Enable is set
  - 0 = Port 2 Power Enable is clear
- bit 2 **LOW\_CUR2:** Indicates if the portable device charge current is below the 13.3 mA threshold on the V<sub>BUS2</sub> and may have finished charging. This bit is cleared when read and will cause the ALERT#2 pin to be asserted if the ALERT LINK2 bit is set.
  - 1 = Port 2 charging current less than threshold
  - 0 = Port 2 charging current above threshold
- bit 1 **REM2:** Removal Detection Port2 Indicates if a Removal Detection event has occurred and there is no longer a portable device present on the V<sub>BUS1</sub> pin. This bit is cleared when read and will not cause the ALERT#2 pin to be asserted.
  - 1 = Removal Detection occurred
  - 0 = No Removal Detection
- bit 0 **ADET2:** Attach Detection Port2 indicates that an Attach Detection event has occurred on the V<sub>BUS2</sub> pins and there is a new portable device present. Asserts the A\_DET#2 pin. This bit is set and cleared as the A\_DET#2 pin changes.
  - 1 = Attach Detection event has occurred. A\_DET#2 pin asserted
  - 0 = No Attach Detection event

#### 9.3 Configuration Registers

The Configuration registers control basic device functionality. The contents of these registers are retained in Sleep.

#### REGISTER 9-7: GENERAL CONFIGURATION 1 REGISTER (ADDRESS 11H)

| R/W-0       | R/W-0 R/W-0 |        | R/W-0    | R/W-0   | R/W-1     | R/W-1  | R/W-0   |
|-------------|-------------|--------|----------|---------|-----------|--------|---------|
| ALERT1_MASK | ALERT1_LINK | DSCHG1 | PWR_EN1S | DISCHG_ | TIME<1:0> | ATT_TH | H1<1:0> |
| bit 7       |             |        |          |         |           |        | bit 0   |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit | C = Clear on Read  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7 ALERT1\_MASK: Mask errors for all interrupts in Register 9-3 except OV\_LIM1 and TSD.
  - 1 = The ALERT#1 pin will only assert if a OV\_LIM1 or TSD is detected.
  - 0 = The ALERT#1 pin will be asserted if an error condition or indicator event is detected.
- bit 6 ALERT1\_LINK: Links the ALERT#1 pin to be asserted when the LOW\_CUR1 bit is set.
  - 1 = The ALERT#1 pin will be asserted if the LOW\_CUR1 indicator bit is set.
  - 0 = The ALERT#1 pin will not be asserted if the LOW CUR1 indicator bit is set.
- bit 5 **DSCHG1:** Forces the V<sub>BUS1</sub> to be reset and discharged when the UCS2112 is in the Active state. Writing this bit to a logic '1' will cause the port power switch to be opened and the discharge circuitry to activate and discharge V<sub>BUS</sub>. Actual discharge time is controlled by DISCHG\_TIME<1:0>. This bit is self-clearing.
  - $1 = V_{BUS1}$  discharge initiated.
  - 0 = Port 1 not in discharge
- bit 4 **PWR\_EN1S:** Power Enable Port 1 override This bit is OR'ed with the PWR\_EN1 pin. Thus, if the polarity is set to active-high, either the PWR\_EN1 pin or this bit must be '1' to enable the port power switch
- bit 3-2 **DISCHG\_TIME<1:0>:** Discharge time Port 1 sets t<sub>DISCHARGE</sub>. The discharge time value is the same for both ports.
  - 00 = 100 ms
  - 01 = 200 ms
  - 10 = 300 ms
  - 11 = 400 ms
- bit 1-0 **ATT\_TH1<1:0>:** Attach Detection Threshold Port 1 determines the current draw needed to determine an Attach event has occurred. It also controls the Removal Detection current level (Note 1).
  - 00 = 200 μA Attach/100 μA Removal
  - 01 = 400 μA Attach/300 μA Removal
  - 10 = 800 μA Attach/700 μA Removal
  - 11 = 1000 μA Attach/900 μA Removal
- **Note 1:** The removal threshold is different when operating in the Active power state versus when operating in the Detect power state.

#### REGISTER 9-8: GENERAL CONFIGURATION 2 REGISTER (ADDRESS 12H)

| R/W-0       | R/W-0       | R/W-0  | R/W-0    | U-0 | U-0 | R/W-1  | R/W-0   |
|-------------|-------------|--------|----------|-----|-----|--------|---------|
| ALERT2_MASK | ALERT2_LINK | DSCHG2 | PWR_EN2S | -   | _   | ATT_TI | H2<1:0> |
| bit 7       |             |        |          |     |     |        | bit 0   |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit | C = Clear on Read  |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7 ALERT2 MASK: Mask errors for all interrupts in Register 9-4 except OV LIM2 and TSD.
  - 1 = The ALERT#2 pin will only assert if a OV LIM2 or TSD is detected.
  - 0 = The ALERT#2 pin will be asserted if an error condition or indicator event is detected.
- bit 6 ALERT2\_LINK: Links the ALERT#2 pin to be asserted when the LOW CUR2 or TREG bits are set.
  - 1 = The ALERT#2 pin will be asserted if the LOW CUR2 or TREG indicator bit is set.
  - 0 = The ALERT#2 pin will not be asserted if the LOW\_CUR2 or TREG indicator bit is set.
- bit 5 **DSCHG2:** Forces the V<sub>BUS2</sub> to be reset and discharged when the UCS2112 is in the Active state. Writing this bit to a logic '1' will cause the port power switch to be opened and the discharge circuitry to activate to discharge V<sub>BUS</sub>. Actual discharge time is controlled by DISCHG\_TIME<1:0>. This bit is self-clearing.
  - $1 = V_{BUS2}$  discharge initiated.
  - 0 = Port 2 not in discharge
- bit 4 **PWR\_EN2S:** Power Enable Port 2 override This bit is OR'ed with the PWR\_EN2 pin. Thus, if the polarity is set to active-high, either the PWR\_EN2 pin or this bit must be '1' to enable the port power switch.
- bit 3-2 Unimplemented
- bit 1-0 **ATT\_TH2<1:0>:** Attach Detection Threshold Port 2 determines the current draw needed to determine an Attach event has occurred. It also controls the Removal Detection current level (Note 1).
  - 00 = 200 μA Attach/100 μA Removal
  - 01 = 400 μA Attach/300 μA Removal
  - 10 = 800 µA Attach/700 µA Removal
  - 11 = 1000 μA Attach/900 μA Removal
- **Note 1:** The removal threshold is different when operating in the Active power state versus when operating in the Detect power state.

#### REGISTER 9-9: GENERAL CONFIGURATION 3 REGISTER (ADDRESS 13H)

| R/W-0   | R/W-1   | R/W-1  | R-0     | R-0                    | R/W-0 | U-0 | U-0   |
|---------|---------|--------|---------|------------------------|-------|-----|-------|
| PIN_IGN | ATT_DIS | DIS_TO | PWR_STA | TE<1:0> <sup>(1)</sup> | BOOST | _   | _     |
| bit 7   |         |        |         |                        |       |     | bit 0 |

#### Legend:

R = Readable bit W = Writable bit U = Unimplemented bit C = Clear on Read-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 7 **PIN\_IGN:** Ignores the PWR\_EN1 and PWR\_EN2 pin states when determining the power state. This bit is retained in Sleep.
  - 1 = PWR EN1 and PWR EN2 pin states are ignored.
  - 0 = Power state is determined by the OR'd combination of the PWR\_EN1 and PWR\_EN2 pins states and the corresponding PWR\_EN1S and PWR\_EN2S bit states.
- bit 6 **ATT\_DIS:** Attach Detect Disable Disables the Attach and Removal Detection feature and affects the power state (see Table 5-2). Setting this bit to 1 forces Active state provided the PWR\_EN 1/2 control is enabled.
  - 1 = Attach/Removal Detection disabled.
  - 0 = Attach/Removal Detection enabled.
- bit 5 **DIS\_TO:** Disable Time Out Disables the SMBus time out feature.
  - 1 = Time out disabled
  - 0 = Time out enabled
- bit 4-3 PWR\_STATE<1:0>: Current Power State These bits indicate the current power state. See Note 1
  - 00 = **SLEEP**
  - 01 = DETECT
  - 10 = ACTIVE
  - 11 = ERROR
- bit 2 **BOOST:** Indicates that the I<sub>BUS</sub> current is higher than I<sub>BOOST</sub> on V<sub>BUS1</sub> or V<sub>BUS2</sub> (bit is OR'ed).
  - 1 =  $I_{BUS}$  has exceeded  $I_{BOOST}$  on either or both ports
  - $0 = I_{BUS}$  is less than  $I_{BOOST}$  on either port individually
- bit 1-0 Unimplemented
- **Note 1:** Accessing the SMBus/I<sup>2</sup>C causes the UCS2112 to leave the Sleep state. As a result, the PWR\_STATE<1:0> bits will never read as 00b.

# 9.4 Current Limit Register

The Current Limit register controls the I<sub>LIM</sub> used by the port power switch. The default setting is based on the resistor on the COMM\_ILIM pin and this value cannot be changed to be higher than hardware set value. The contents of this register are retained in Sleep.

#### REGISTER 9-10: CURRENT LIMIT REGISTER (ADDRESS 14H)

| U-0   | U-0 | R/W-0 | R/W-0           | R/W-0 | R/W-0 | R/W-0       | R/W-0 |
|-------|-----|-------|-----------------|-------|-------|-------------|-------|
| _     | _   | IL    | ILIM_PORT2<2:0> |       |       | M_PORT1<2:0 | )>    |
| bit 7 |     | •     |                 |       |       |             | bit 0 |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit |                    |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

bit 7-6 Unimplemented: Read as '0' bit 5-3 ILIM\_PORT2<2:0>: Sets the I<sub>LIM</sub> value for port 2. 000 = 0.53A001 = 0.96A010 **= 1.07A** 011 **= 1.28A** 100 **= 1.6A** 101 **= 2.13A** 110 = 2.67A111 = 3.2Abit 2-0 **ILIM\_SW<2:0>:** Sets the I<sub>LIM</sub> value for port 1. 000 = 0.53A001 = 0.96A010 = 1.07A011 **= 1.28A** 100 **= 1.6A** 101 **= 2.13A** 110 = 2.67A 111 = 3.2A

#### 9.5 Auto-Recovery Register

The contents of this register are retained in Sleep.

The Auto-Recovery Configuration register sets the parameters used when the auto-recovery fault handling algorithm is invoked. Once the auto-recovery fault handling algorithm has checked the overtemperature and back-drive conditions, it will set the  $I_{LIM}$  value to  $I_{TEST}$  and then turn on the port power switch and start the  $t_{TST}$  timer. If, after the timer has expired, the  $V_{BUS}$  voltage is less than  $V_{TEST}$ , then it is assumed that a short-circuit condition is present and the Error state is restarted for auto recovery.

#### REGISTER 9-11: AUTO RECOVERY CONFIGURATION REGISTER (ADDRESS 15H)

| R/W-0  | R/W-0       | R/W-1 | R/W-0 | R/W-1 | R/W-0 | R/W-1  | R/W-0        |  |
|--------|-------------|-------|-------|-------|-------|--------|--------------|--|
| LATCHS | TCYCLE<2:0> |       |       | TTST  | <1:0> | VTST_S | VTST_SW<1:0> |  |
| bit 7  |             |       |       |       |       |        | bit 0        |  |

| Legend:           |                  |                       |                    |
|-------------------|------------------|-----------------------|--------------------|
| R = Readable bit  | W = Writable bit | U = Unimplemented bit |                    |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared  | x = Bit is unknown |

- bit 7 **LATCHS:** Latch Set Controls the fault-handling routine that is used in the case that an error is detected.
  - 1 = Error state will be latched. In order for the UCS2112 to return to normal Active state, the ERR bit must be cleared by the user.
  - 0 = The UCS2112 will automatically retry when an error condition is detected.
- bit 6-4 **TCYCLE<2:0>:** Defines the delay (t<sub>CYCLE</sub>) after the Error state is entered before the auto-recovery fault handling algorithm is started as shown below.

```
000 = 15 ms
```

011 = 30 ms

100 **= 35 ms** 

101 = 40 ms

110 **= 45 ms** 

111 = 50 ms

bit 3-2 **TTST<1:0>:** Retry Duration timer – Sets the t<sub>TST</sub> as shown below.

00 = 10 ms

01 = **15 ms** 

10 = 20 ms

11 = 25 ms

bit 1-0 **VTST\_SW:** Short-circuit Voltage Threshold V<sub>TEST</sub> voltage threshold that must be crossed during retries to declare the short removed.

00 = 250 mV

01 = 500 mV

10 = 750 mV

11 = 1000 mV

<sup>001 = 20</sup> ms

<sup>010</sup> **= 25 ms** 

## 9.6 Total Accumulated Charge Registers

The Total Accumulated Charge registers store the total accumulated charge delivered from the  $V_S$  source to a portable device. The bit weighting of the registers is given in mA-hrs. The register value is reset to  $00\_00\mathrm{h}$  only when the RTN\_RST bit is set or if the RTN\_EN bit is cleared (see Register 9-16). This value will be retained when the device transitions out of the Active state and resumes accumulation if the device returns to the Active state and charge rationing is still enabled.

These registers are updated every one (1) second while the UCS2112 is in the Active power state. Every time the value is updated, it is compared against the target value in the Charge Rationing Threshold registers. This data is retained in the Sleep state.

REGISTER 9-12: PORT1 TOTAL ACCUMULATED CHARGE REGISTERS (ADDRESS 16H, 17H, 18H, 19H)

| R-0         | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0    |
|-------------|-----|-----|-----|-----|-----|-----|--------|
| TAC1<25:18> |     |     |     |     |     |     |        |
| bit 31      |     |     |     |     |     |     | bit 24 |

| R-0         | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0    |  |  |
|-------------|-----|-----|-----|-----|-----|-----|--------|--|--|
| TAC1<17:10> |     |     |     |     |     |     |        |  |  |
| bit 23      |     |     |     |     |     |     | bit 16 |  |  |

| R-0       | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0   |  |  |
|-----------|-----|-----|-----|-----|-----|-----|-------|--|--|
| TAC1<9:2> |     |     |     |     |     |     |       |  |  |
| bit 15    |     |     |     |     |     |     | bit 8 |  |  |

| R-0       | R-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0   |
|-----------|-----|-----|-----|-----|-----|-----|-------|
| TAC1<1:0> |     | _   | _   | _   | _   | _   | _     |
| bit 7     |     |     |     |     |     |     | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

bit 31-6 TAC1<25:0>: Total Accumulated Charge Port 1 – Each LSB of this 26-bit value equals 0.00367 mAh.

bit 5-0 **Unimplemented:** Read as '0'

# REGISTER 9-13: PORT2 TOTAL ACCUMULATED CHARGE REGISTER (ADDRESS 1AH,1BH,1CH,1DH)

| R-0         | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0    |  |  |
|-------------|-----|-----|-----|-----|-----|-----|--------|--|--|
| TAC2<25:18> |     |     |     |     |     |     |        |  |  |
| bit 31      |     |     |     |     |     |     | bit 24 |  |  |

| R-0         | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0    |  |  |
|-------------|-----|-----|-----|-----|-----|-----|--------|--|--|
| TAC2<17:10> |     |     |     |     |     |     |        |  |  |
| bit 23      |     |     |     |     |     |     | bit 16 |  |  |

| R-0       | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0   |  |  |
|-----------|-----|-----|-----|-----|-----|-----|-------|--|--|
| TAC2<9:2> |     |     |     |     |     |     |       |  |  |
| bit 15    |     |     |     |     |     |     | bit 8 |  |  |

| R-0       | R-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0   |
|-----------|-----|-----|-----|-----|-----|-----|-------|
| TAC2<1:0> |     | _   | _   | _   | _   | _   | _     |
| bit 7     |     |     |     |     |     |     | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-6 **TAC2<25:0>:** Total Accumulated Charge Port 2 – Each LSB of this 26-bit value equals 0.00367 mAh.

bit 5-0 **Unimplemented:** Read as '0'

## 9.7 Charge Rationing Threshold Registers

The Charge Rationing Threshold registers set the maximum allowed charge that will be delivered to a portable device. Every time the Total Accumulated Charge registers are updated, the value is checked against this limit. If the value meets or exceeds this limit, the RATION1/RATION2 bit is set and action taken according to the RTN\_BEH1<1:0> and RTN\_BEH2<1:0> bits in Register 9-16: Ration Configuration Register (Address 22h).

### REGISTER 9-14: PORT 1 CHARGE RATIONING THRESHOLD REGISTERS (ADDRESS 1EH,1FH)

| R/W-1     | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |  |  |
|-----------|-------|-------|-------|-------|-------|-------|-------|--|--|
| CT1<15:8> |       |       |       |       |       |       |       |  |  |
| bit 15    |       |       |       |       |       |       | bit 8 |  |  |

| R/W-1    | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |  |
|----------|-------|-------|-------|-------|-------|-------|-------|--|
| CT1<7:0> |       |       |       |       |       |       |       |  |
| bit 7    |       |       |       |       |       |       | bit 0 |  |

 Legend:
 R = Readable bit
 W = Writable bit
 U = Unimplemented bit

 -n = Value at POR
 '1' = Bit is set
 '0' = Bit is cleared
 x = Bit is unknown

bit 15-0 **CT1<15:0>:** Charge Rationing Threshold Port 1 – Each LSB of this 16-bit value equals 3.76 mAh.

#### REGISTER 9-15: PORT 2 CHARGE RATIONING THRESHOLD REGISTERS (ADDRESS 20H, 21H)

| R/W-1  | R/W-1     | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |  |  |  |
|--------|-----------|-------|-------|-------|-------|-------|-------|--|--|--|
|        | CT2<15:8> |       |       |       |       |       |       |  |  |  |
| bit 15 |           |       |       |       |       |       | bit 8 |  |  |  |

| R/W-1    | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |  |  |
|----------|-------|-------|-------|-------|-------|-------|-------|--|--|
| CT2<7:0> |       |       |       |       |       |       |       |  |  |
| bit 7    |       |       |       |       |       |       | bit 0 |  |  |

 Legend:

 R = Readable bit
 W = Writable bit
 U = Unimplemented bit

 -n = Value at POR
 '1' = Bit is set
 '0' = Bit is cleared
 x = Bit is unknown

bit 15-0 CT2: Charge Rationing Threshold Port 2 – Each LSB of this 16-bit value equals 3.76 mAh.

#### REGISTER 9-16: RATION CONFIGURATION REGISTER (ADDRESS 22H)

| R/W-0   | R/W-0    | R/W-0 | R/W-1    | R/W-0   | R/W-0    | R/W-0  | R/W-1    |
|---------|----------|-------|----------|---------|----------|--------|----------|
| RTN_EN2 | RTN_RST2 | RTN_B | EH2<1:0> | RTN_EN1 | RTN_RST1 | RTN_BE | EH1<1:0> |
| bit 7   |          |       |          |         |          |        | bit 0    |

 Legend:
 W = Writable bit
 U = Unimplemented bit

 -n = Value at POR
 '1' = Bit is set
 '0' = Bit is cleared
 x = Bit is unknown

- bit 7 **RTN\_EN2:** Charge Ration Enable Port 2 Enables Charge Rationing for Port 2.
  - 1 = Charge Rationing enabled
  - 0 = Charge Rationing disabled. The Total Accumulated Charge registers for port 2 will be cleared to 00\_00h and current data will no longer be accumulated. If the Total Accumulated Charge registers have already reached the Charge Rationing Threshold, the applied response will be removed as if the charge rationing had been reset. This will also clear the RATION2 Status bit (if set).
- bit 6 RTN\_RST2: Port 2 Ration Reset Resets the charge rationing functionality for port 2.
  - 1 = Total Accumulated Charge registers are reset to 00\_00h. In addition, when this bit is set, the RATION2 Status bit will be cleared and, if there are no other errors or active indicators, the ALERT#2 pin will be released.
  - 0 = Normal operation. This bit must be cleared to enable charge rationing.
- bit 5-4 **RTN\_BEH2<1:0>:** Ration Behavior Control bits Controls how the UCS2112 responds when the Ration Threshold has been exceeded (as shown in Table 7-2).
  - 00 = Report
  - 01 = Report and Disconnect
  - 10 = Disconnect and SLEEP
  - 11 = Ignore
- bit 3 **RTN\_EN1:** Charge Ration Enable Port 1 Enables Charge Rationing for Port 1.
  - 1 = Charge Rationing enabled
  - 0 = Charge Rationing disabled. The Total Accumulated Charge registers for port 1 will be cleared to 00\_00h and current data will no longer be accumulated. If the Total Accumulated Charge registers have already reached the Charge Rationing Threshold, the applied response will be removed as if the charge rationing had been reset. This will also clear the RATION1 Status bit (if set).
- bit 2 RTN\_RST1: Port 1 Ration Reset Resets the charge rationing functionality for port 1.
  - 1 = Total Accumulated Charge registers are reset to 00\_00h. In addition, when this bit is set, the RATION1 Status bit will be cleared and, if there are no other errors or active indicators, the ALERT#1 pin will be released.
  - 0 = Normal operation. This bit must be cleared to enable charge rationing.
- bit 1-0 **RTN\_BEH1<1:0>:** Ration Behavior Control bits Controls how the UCS2112 responds when the Ration Threshold has been exceeded (as shown in Table 7-2).
  - 00 = Report
  - 01 = Report and Disconnect
  - 10 = Disconnect and SLEEP
  - 11 = Ignore

## 9.8 Current Limit Behavior Registers

The Current Limit Behavior register stores the values used by the applied current limiting mode (trip or CC). The contents of this register are not retained in Sleep.

#### REGISTER 9-17: PORT 1 CURRENT LIMIT BEHAVIOR REGISTER (ADDRESS 23H)

| R/W-1    | R/W-0      | U-0 | R/W-1 | R/W-0         | R/W-1 | R/W-1    | R/W-0    |
|----------|------------|-----|-------|---------------|-------|----------|----------|
| SEL_VBUS | 1_MIN<1:0> | _   | SE    | L_R2_IMIN1<2: | :0>   | Reserved | Reserved |
| bit 7    |            |     |       |               |       |          | bit 0    |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-6 **SEL\_VBUS1\_MIN<1:0>:** Define the V<sub>BUS\_MIN</sub> voltage for port 1 as follows:

00 = 1.50V

01 = 1.75V

10 = 2.0V

11 = 2.25V

bit 5 Unimplemented

bit 4-2 SEL\_R2\_IMIN1<2:0>: Defines the I<sub>BUS R2MIN</sub> current.

000 = 100 mA

001 **= 530 mA** 

010 = 960 mA

011 = 1280 mA

100 = 1600 mA

101 = 2130 mA

bit 1-0 Reserved: Do not change.

#### REGISTER 9-18: PORT 2 CURRENT LIMIT BEHAVIOR REGISTER (ADDRESS 24H)

| R/W-1      | R/W-0    | U-0 | R/W-1 | R/W-0         | R/W-1 | R/W-1    | R/W-0    |
|------------|----------|-----|-------|---------------|-------|----------|----------|
| SEL_VBUS2_ | MIN<1:0> | _   | SE    | L_R2_IMIN2<2: | 0>    | Reserved | Reserved |
| bit 7      |          |     |       |               |       |          | bit 0    |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-6 SEL\_VBUS2\_MIN<1:0>: Define the V<sub>BUS MIN</sub> voltage for port 2 as follows:

00 = 1.50V

01 = 1.75V

10 **= 2.0V** 

11 = 2.25V

bit 5 Unimplemented

bit 4-2 SEL\_R2\_IMIN2<2:0>: Defines the I<sub>BUS\_R2MIN</sub> current.

000 = 100 mA

001 **= 530 mA** 

010 = 960 mA

011 = 1280 mA

100 = 1600 mA

101 **= 2130 mA** 

bit 1-0 **Reserved**: Do not change.

## 9.9 Product ID Register

The Product ID register stores a unique 8-bit value that identifies the UCS device family.

#### REGISTER 9-19: PRODUCT ID REGISTER (ADDRESS FDH)

| R-1   | R-1 | R-1 | R-0   | R-0  | R-0 | R-0 | R-1   |
|-------|-----|-----|-------|------|-----|-----|-------|
|       |     |     | PID<7 | 7:0> |     |     |       |
| bit 7 |     |     |       |      |     |     | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-0 PID<7:0>: Product ID for the UCS2112.

### 9.10 Manufacturer ID Register

The Manufacturer ID register stores a unique 8-bit value that identifies Microchip Technology Inc.

## REGISTER 9-20: MANUFACTURER ID REGISTER (ADDRESS FEH)

| R-0   | R-1 | R-0 | R-1  | R-1  | R-1   | R-0 | R-1 |
|-------|-----|-----|------|------|-------|-----|-----|
|       |     |     | MID< | 7:0> |       |     |     |
| bit 7 |     |     |      |      | bit 0 |     |     |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-0 MID<7:0>: Manufacturer ID for Microchip.

#### 9.11 Revision Register

The Revision register stores an 8-bit value that represents the part revision.

#### REGISTER 9-21: REVISION REGISTER (ADDRESS FFH)

| R-1   | R-0 | R-0 | R-0  | R-0  | R-0 | R-0 | R-1   |
|-------|-----|-----|------|------|-----|-----|-------|
|       |     |     | REV< | 7:0> |     |     |       |
| bit 7 |     |     |      |      |     |     | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

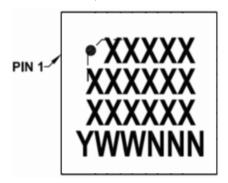
bit 7-0 **REV<7:0>:** Part Revision.

|   | $\sim$ | <br>Ο. |
|---|--------|--------|
| N |        | <br>຺. |
|   |        |        |

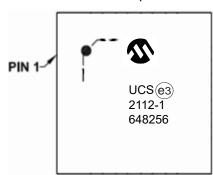
#### 10.0 PACKAGING INFORMATION

# 10.1 Package Marking Information

4x4 mm QFN, 20-lead



Example



Legend: XX...X Customer-specific information

Y Year code (last digit of calendar year)
YY Year code (last 2 digits of calendar year)
WW Week code (week of January 1 is week '01')

NNN Alphanumeric traceability code

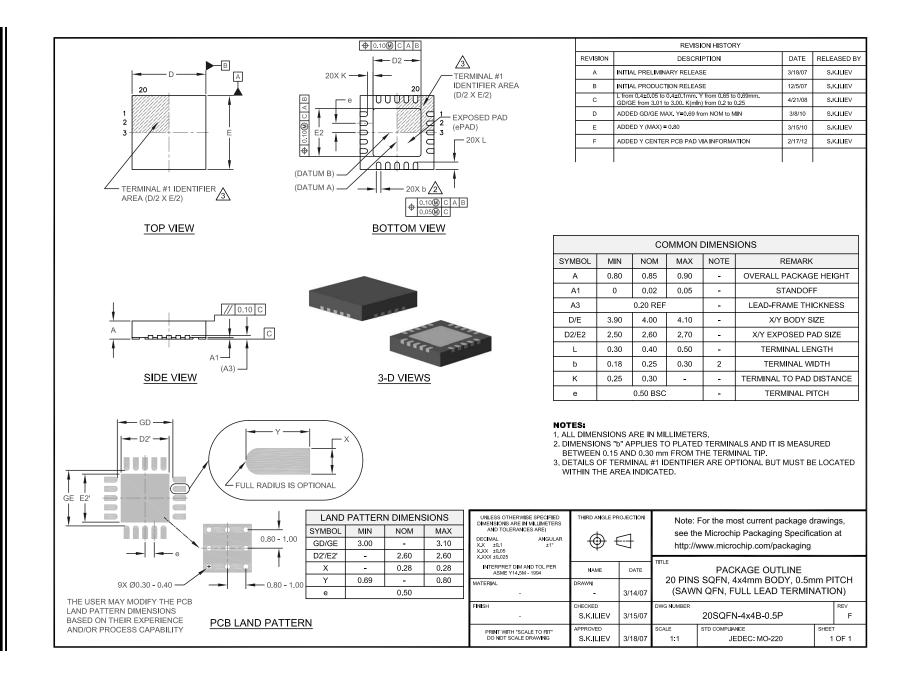
e3 Pb-free JEDEC® designator for Matte Tin (Sn)

This package is Pb-free. The Pb-free JEDEC designator (e3)

can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.







NOTES:

#### APPENDIX A: REVISION HISTORY

#### **Revision D (January 2021)**

The following is the list of modifications:

- Added information about the automotive qualification status of the device in the Features section.
- Updated the Product Identification System section with an automotive qualified device.

### **Revision C (February 2017)**

The following is the list of modifications:

- Added minimum and maximum values for the ILIM7 parameter in Table 1-2: Electrical Specifications.
- Added "Operating Junction Temperature" parameter in Table 1-3: Temperature Specifications.
- Added a note in Section 8.13, SMBus Send Byte detailing the behavior of the UCS2112 when two commands are sent in a row.
- Added maximum value for the VDD\_TH\_HYST parameter and maximum value for the R<sub>ON\_PSW</sub> parameter in Table 1-2: Electrical Specifications.
- Updated Figure 2-8.
- · Minor typographical corrections

### **Revision B (October 2015)**

 Updated Features to indicate EN/IEC 60950-1 (CB) certification.

## **Revision A (August 2015)**

· Original release of this document



NOTES:

# PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

| PART NO.                 | [X] <sup>(1)</sup> -X -X /XX XXX   | Examples:   |
|--------------------------|--|---|
| Device Tape              | and Reel Version Temperature Package Qualification ption   | a) UCS2112-1-V/G4: SMBus Address 57h<br>Various Temperature<br>20-pin 4x4 QFN Package   |
| Device:                  | UCS2112: USB Dual-Port Power Switch and Current Monitor  | b) UCS2112T-2-V/G4VAO: Tape and Reel<br>SMBus Address 56h<br>Various Temperature<br>20-pin 4x4 QFN Package<br>AEC-Q100 Automotive                 |
| Tape and Reel<br>Option: | Blank = Tube<br>T = Tape and Reel  | Qualified   |
| Version:                 | 1 = SMBus address 57h 2 = SMBus address 56h  |   |
| Temperature Range:       | V = -40°C to +105°C (Various)  |   |
| Package:                 | G4 = Plastic Quad Flat No Lead Package - 4x4 mm Body with 0.40 mm Contact Length, Saw Singulated, QFN, 20-lead | Note 1: Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes               |
| Qualification:           | Blank = Standard Qualification<br>VAO = AEC-Q100 Automotive Qualification                                      | and is not printed on the device package.<br>Check with your Microchip Sales Office for<br>package availability with the Tape and<br>Reel option. |

# **UCS2112**

NOTES:

#### Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specifications contained in their particular Microchip Data Sheet.
- · Microchip believes that its family of products is secure when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods being used in attempts to breach the code protection features of the Microchip devices. We believe that these methods require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Attempts to breach these code protection features, most likely, cannot be accomplished without violating Microchip's intellectual property rights.
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