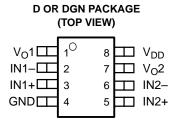




### 150-mW STEREO AUDIO POWER AMPLIFIER

#### **FEATURES**

- 150-mW Stereo Output
- · Wide Range of Supply Voltages
  - Fully Specified for 3.3-V and 5-V Operation
  - Operational From 2.5 V to 5.5 V
- Thermal and Short-Circuit Protection
- Surface-Mount Packaging
  - PowerPAD™ MSOP
  - SOIC
- Standard Operational Amplifier Pinout

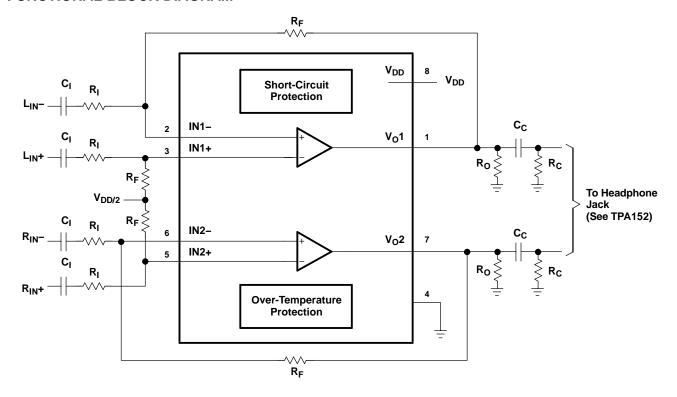


#### **DESCRIPTION**

The TPA112 is a stereo audio power amplifier packaged in an 8-pin PowerPAD<sup>TM</sup> MSOP package capable of delivering 150 mW of continuous RMS power per channel into 8- $\Omega$  loads. Amplifier gain is externally configured by means of two resistors per input channel and does not require external compensation for settings of 1 to 10.

THD+N when driving an 8- $\Omega$  load from 5 V is 0.1% at 1 kHz, and less than 2% across the audio band of 20 Hz to 20 kHz. For 32- $\Omega$  loads, the THD+N is reduced to less than 0.06% at 1 kHz, and is less than 1% across the audio band of 20 Hz to 20 kHz. For 10-k $\Omega$  loads, the THD+N performance is 0.01% at 1 kHz, and less than 0.02% across the audio band of 20 Hz to 20 kHz.

#### **FUNCTIONAL BLOCK DIAGRAM**



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PowerPAD is a trademark of Texas Instruments.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### **AVAILABLE OPTIONS**

	PACKAGED D	EVICES	MSOP
T <sub>A</sub>	SMALL OUTLINE <sup>(1)</sup> (D)	MSOP <sup>(1)</sup> (DGN)	SYMBOLIZATION
-40°C to 85°C	TPA112D	TPA112DGN	TI AAD

 The D and DGN packages are available in left-ended tape and reel only (e.g., TPA112DR, TPA112DGNR).

#### **Terminal Functions**

TERM	TERMINAL		DESCRIPTION	
NAME	NO.	1/0	DESCRIPTION	
GND	4	ı	GND is the ground connection.	
IN1-	2	ı	IN1- is the inverting input for channel 1.	
IN1+	3	I	IN1+ is the noninverting input for channel 1.	
IN2-	6	ı	IN2- is the inverting input for channel 2.	
IN2+	5	I	IN2+ is the noninverting input for channel 2.	
V <sub>DD</sub>	8	ı	V <sub>DD</sub> is the supply voltage terminal.	
V <sub>O</sub> 1	1	0	1 is the audio output for channel 1.	
V <sub>O</sub> 2	7	0	V <sub>O</sub> 2 is the audio output for channel 2.	

#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)(1)

		UNIT
$V_{DD}$	Supply voltage	6 V
V <sub>I</sub>	Differential input voltage	-0.3 V to V <sub>DD</sub> + 0.3 V
I <sub>I</sub>	Input current	±2.5 μA
Io	Output current	±250 mA
	Continuous total power dissipation	Internally Ilimited
TJ	Operating junction temperature range	–40°C to 150°C
T <sub>stg</sub>	Storage temperature range	−65°C to 150°C
	Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### **DISSIPATION RATING TABLE**

	PACKAGE	$T_A \le 25^{\circ}C$ POWER RATING	DERATING FACTOR ABOVE T <sub>A</sub> = 25°C	T <sub>A</sub> = 70°C POWER RATING	T <sub>A</sub> = 85°C POWER RATING
	D	725 mW	5.8 mW/°C	464 mW	377 mW
L	DGN	2.14 W <sup>(1)</sup>	17.1 mW/°C	1.37 W	1.11 W

(1) See the Texas Instruments document, PowerPAD Thermally Enhanced Package Application Report (SLMA002), for more information on the PowerPAD package. The thermal data was measured on a PCB layout based on the information in the section entitled Texas Instruments Recommended Board for PowerPAD, of that document.



#### **RECOMMENDED OPERATING CONDITIONS**

		MIN	MAX	UNIT
$V_{DD}$	Supply voltage	2.5	5.5	V
T <sub>A</sub>	Operating free-air temperature	-40	85	°C

#### DC ELECTRICAL CHARACTERISTICS

at  $T_A = 25^{\circ}C$ ,  $V_{DD} = 3.3 \text{ V}$ 

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Voo	Output offset voltage				10	mV
PSRR	Power supply rejection ratio	V <sub>DD</sub> = 3.2 V to 3.4 V		83		dB
I <sub>DD(q)</sub>	Supply current			1.5	3	mA
Z <sub>I</sub>	Input impedance			> 1		ΜΩ

#### **AC OPERATING CHARACTERISTICS**

 $V_{DD}$  = 3.3 V,  $T_A$  = 25°C,  $R_L$  = 8  $\Omega$ 

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%	70 <sup>(1)</sup>	mW
THD+N	Total harmonic distortion + noise	P <sub>O</sub> = 70 mW, 20 Hz–20 kHz	2%	
B <sub>OM</sub>	Maximum output power BW	G = 10, THD < 5%	> 20	kHz
	Phase margin	Open loop	58°	
S <sub>VRR</sub>	Supply ripple rejection	f = 1 kHz	68	dB
	Channel/channel output separation	f = 1 kHz	86	dB
SNR	Signal-to-noise ratio	P <sub>O</sub> = 100 mW	100	dB
V <sub>n</sub>	Noise output voltage		9.5	μV(rms)

<sup>(1)</sup> Measured at 1 kHz

#### DC ELECTRICAL CHARACTERISTICS

at  $T_A = 25^{\circ}C$ ,  $V_{DD} = 5 \text{ V}$ 

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Voo	Output offset voltage				10	mV
PSRR	Power supply rejection ratio	V <sub>DD</sub> = 4.9 V to 5.1 V		76		dB
$I_{DD(q)}$	Supply current			1.5	3	mA
Z <sub>I</sub>	Input impedance			> 1		МΩ

#### **AC OPERATING CHARACTERISTICS**

 $V_{DD} = 5 \text{ V}, T_A = 25^{\circ}\text{C}, R_L = 8 \Omega$ 

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%	70 <sup>(1)</sup>	mW
THD+N	Total harmonic distortion + noise	$P_O = 150 \text{ mW}, 20 \text{ Hz}-20 \text{ kHz}$	2%	
B <sub>OM</sub>	Maximum output power BW	G = 10, THD < 5%	> 20	kHz
	Phase margin	Open loop	56°	
S <sub>VRR</sub>	Supply ripple rejection	f = 1 kHz	68	dB
	Channel/channel output separation	f = 1 kHz	86	dB
SNR	Signal-to-noise ratio	P <sub>O</sub> = 150 mW	100	dB
V <sub>n</sub>	Noise output voltage		9.5	μV(rms)

<sup>(1)</sup> Measured at 1 kHz



#### **AC OPERATING CHARACTERISTICS**

 $V_{DD}$  = 3.3 V,  $T_A$  = 25°C,  $R_L$  = 32  $\Omega$ 

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%	40(1)	mW
THD+N	Total harmonic distortion + noise	P <sub>O</sub> = 30 mW, 20 Hz–20 kHz	0.5%	
B <sub>OM</sub>	Maximum output power BW	G = 10, THD < 2%	> 20	kHz
	Phase margin	Open loop	58°	
S <sub>VRR</sub>	Supply ripple rejection	f = 1 kHz	68	dB
	Channel/channel output separation	f = 1 kHz	86	dB
SNR	Signal-to-noise ratio	P <sub>O</sub> = 100 mW	100	dB
V <sub>n</sub>	Noise output voltage		9.5	μV(rms)

<sup>(1)</sup> Measured at 1 kHz

#### **AC OPERATING CHARACTERISTICS**

 $V_{DD}$  = 5 V,  $T_A$  = 25°C,  $R_L$  = 32  $\Omega$ 

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%	40 <sup>(1)</sup>	mW
THD+N	Total harmonic distortion + noise	P <sub>O</sub> = 60 mW, 20 Hz–20 kHz	0.4%	
B <sub>OM</sub>	Maximum output power BW	G = 10, THD < 2%	> 20	kHz
	Phase margin	Open loop	56°	
S <sub>VRR</sub>	Supply ripple rejection	f = 1 kHz	68	dB
	Channel/channel output separation	f = 1 kHz	86	dB
SNR	Signal-to-noise ratio	P <sub>O</sub> = 150 mW	100	dB
V <sub>n</sub>	Noise output voltage		9.5	μV(rms)

<sup>(1)</sup> Measured at 1 kHz

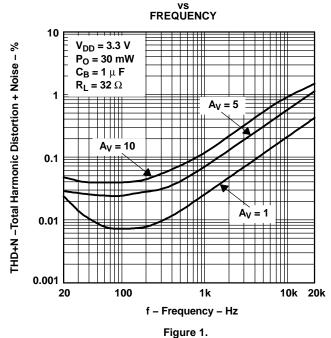


#### **TYPICAL CHARACTERISTICS**

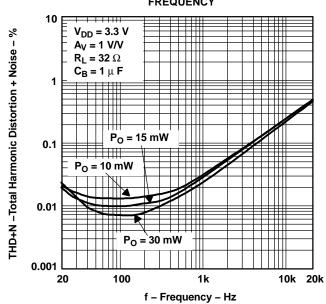
#### **Table of Graphs**

			FIGURE
THD+N	Total harmonic distortion plus noise	vs Frequency	1, 2, 4, 5, 7, 8, 10, 11, 13, 14, 16, 17, 34, 36
		vs Output power	3, 6, 9, 12, 15, 18
PSSR	Power supply rejection ratio	vs Frequency	19, 20
V <sub>n</sub>	Output noise voltage	vs Frequency	21, 22
	Crosstalk	vs Frequency	23-26, 37, 38
	Mute attenuation	vs Frequency	27, 28
	Open-loop gain	vs Frequency	29, 30
	Phase margin	vs Frequency	29, 30
	Phase	vs Frequency	39-44
	Output power	vs Load resistance	31, 32
I <sub>CC</sub>	Supply current	vs Supply voltage	33
SNR	Signal-to-noise ratio	vs Voltage gain	35
	Closed-loop gain	vs Frequency	39-44
	Power dissipation/amplifier	vs Output power	45, 46

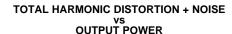
## TOTAL HARMONIC DISTORTION + NOISE vs

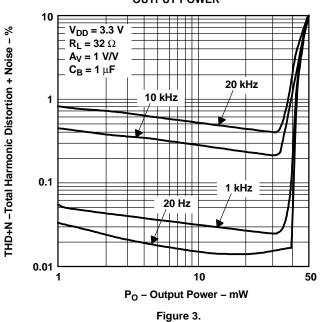


### TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

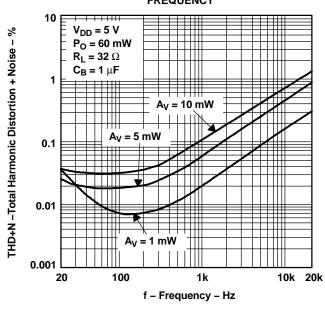






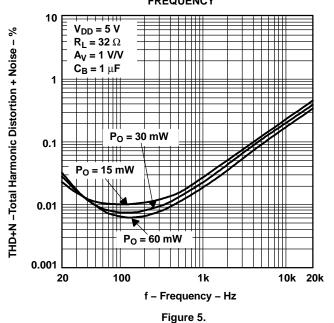


### TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY



#### Figure 4.

# TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY



### TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

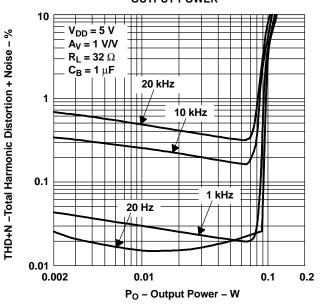
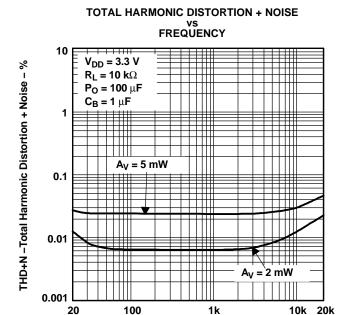


Figure 6.

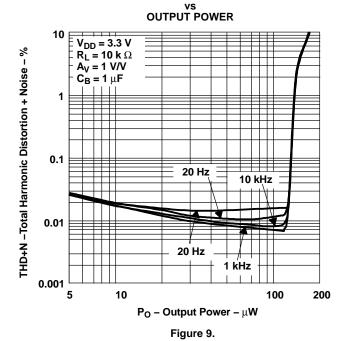




## TOTAL HARMONIC DISTORTION + NOISE

f - Frequency - Hz

Figure 7.



### TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

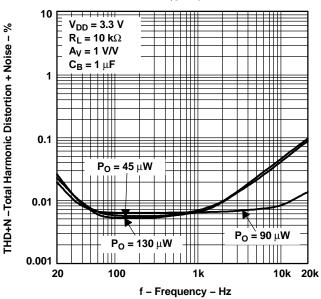


Figure 8.

# TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

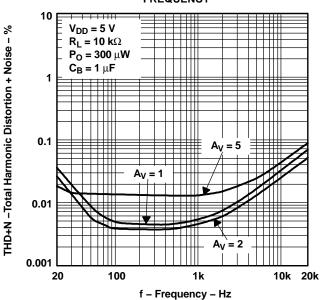


Figure 10.





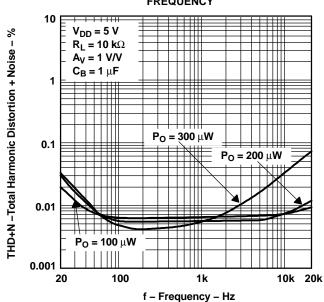


Figure 11.

# TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

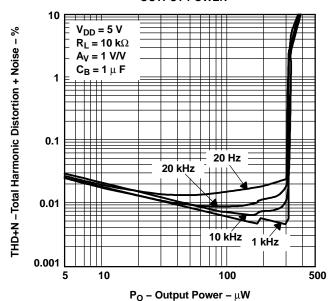


Figure 12.

# TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

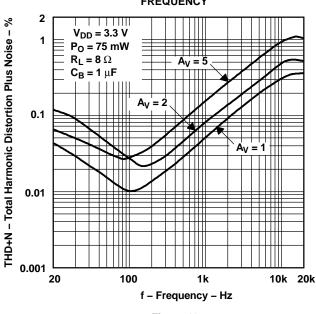


Figure 13.

# TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

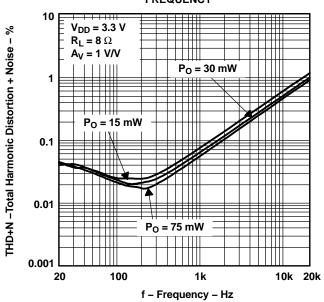
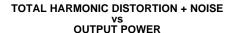
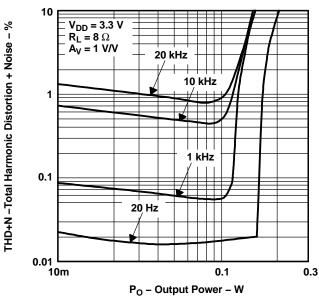


Figure 14.







## Figure 15.

### TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

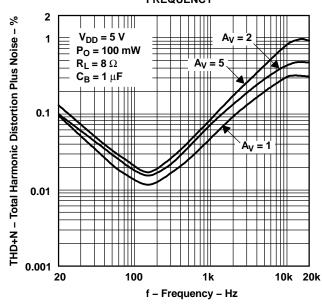
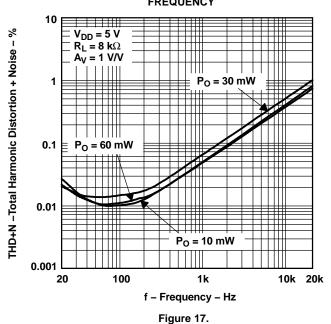


Figure 16.

# TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY



# TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

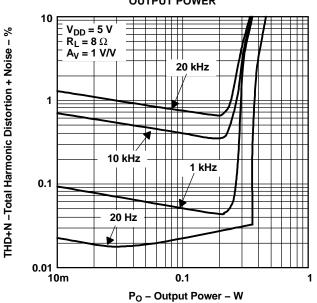
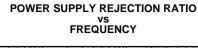


Figure 18.





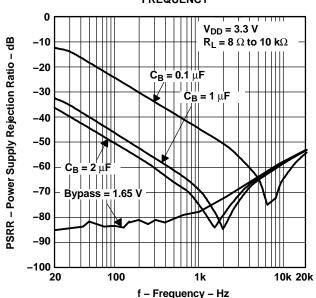


Figure 19.

# POWER SUPPLY REJECTION RATIO vs FREQUENCY

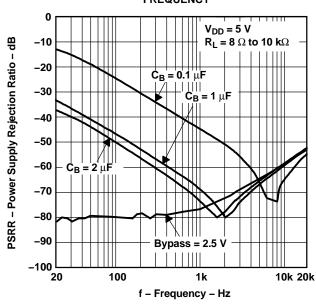


Figure 20.

# OUTPUT NOISE VOLTAGE vs FREQUENCY

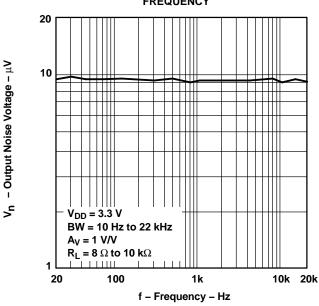


Figure 21.

# OUTPUT NOISE VOLTAGE VS FREQUENCY

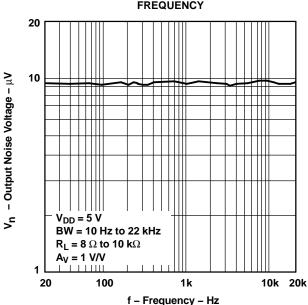
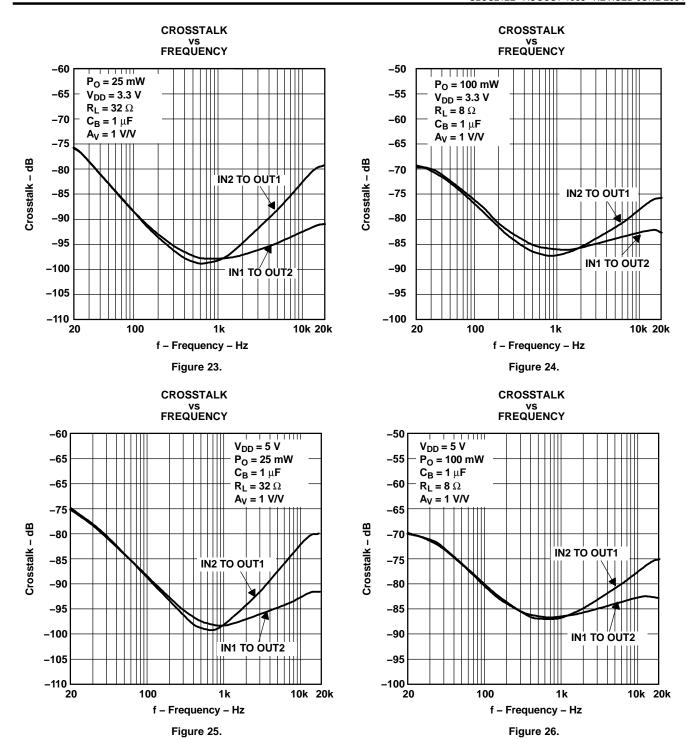
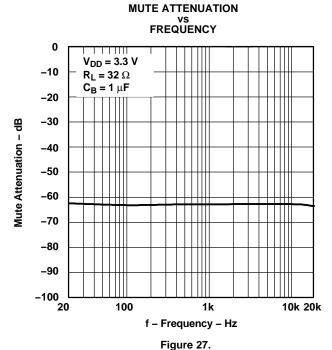


Figure 22.







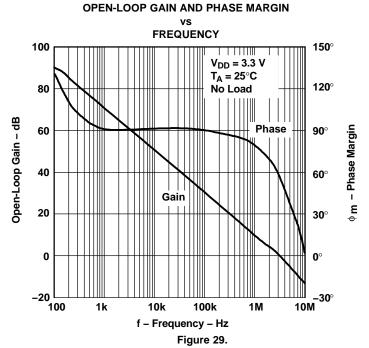


#### vs FREQUENCY 0 V<sub>DD</sub> = 5 V -10 $C_B = 1 \mu F$ $R_L = 32 \Omega$ -20 Mute Attenuation - dB -30 -40 -50 -60 -70 -80 -90 -100 └ 20 100 1k 10k 20k

f – Frequency – Hz Figure 28.

**MUTE ATTENUATION** 

igure 27.





#### **OPEN-LOOP GAIN AND PHASE MARGIN**

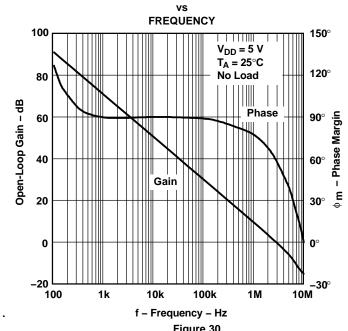
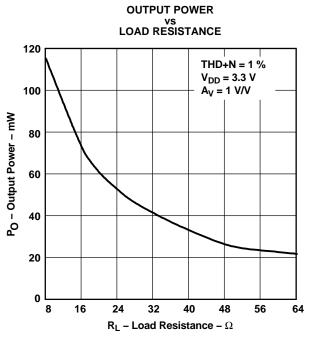
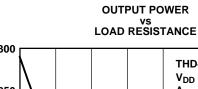


Figure 30.



#### Figure 31.



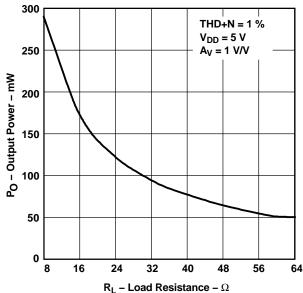
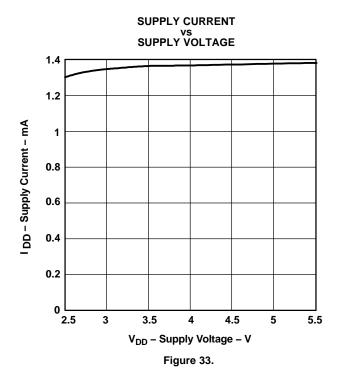
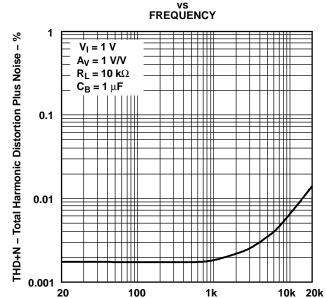


Figure 32.







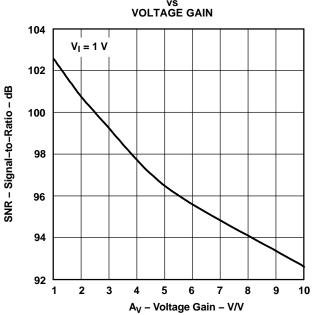
**TOTAL HARMONIC DISTORTION + NOISE** 

### SIGNAL-TO-NOISE RATIO vs VOLTAGE GAIN 104

**TOTAL HARMONIC DISTORTION + NOISE** vs FREQUENCY

Figure 34.

f - Frequency - Hz



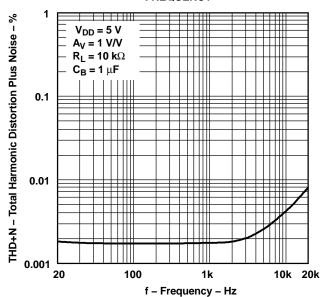
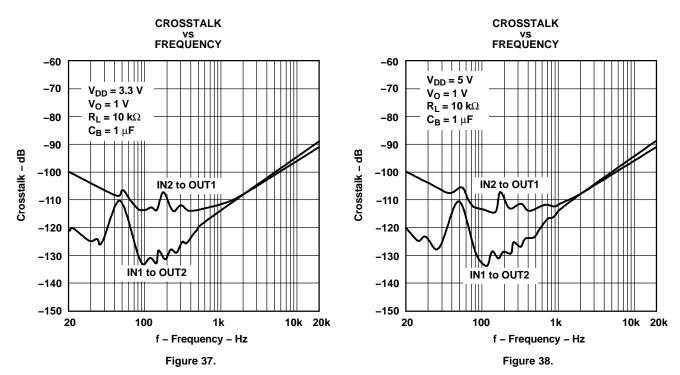
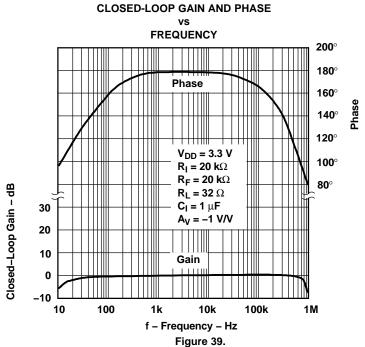


Figure 35.

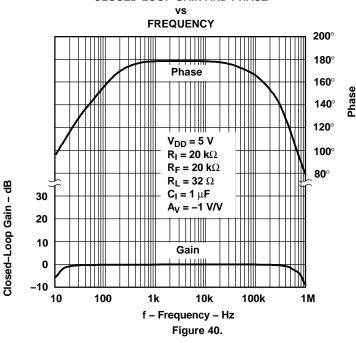




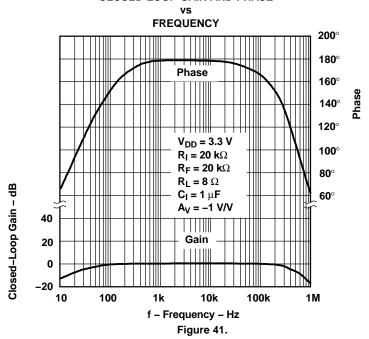




#### **CLOSED-LOOP GAIN AND PHASE**

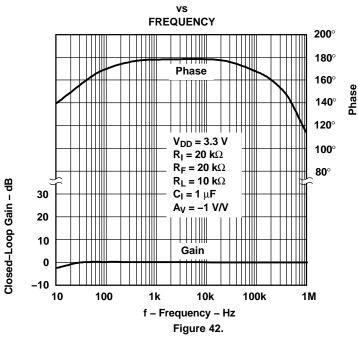


#### **CLOSED-LOOP GAIN AND PHASE**

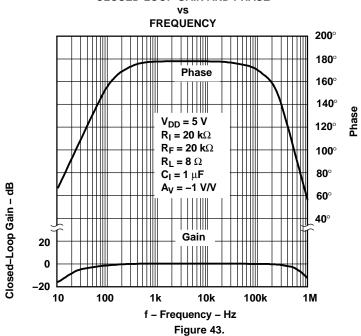




#### **CLOSED-LOOP GAIN AND PHASE**



#### **CLOSED-LOOP GAIN AND PHASE**

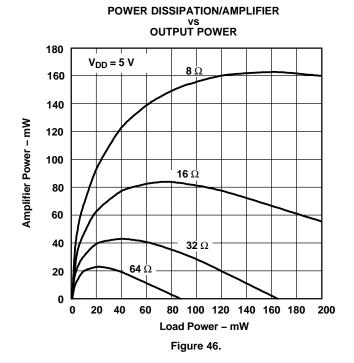




#### **CLOSED-LOOP GAIN AND PHASE** vs **FREQUENCY 200**° 180° Phase 160° 140° Closed-Loop Gain - dB 120° $V_{DD} = 5 V$ $R_I = 20 \text{ k}\Omega$ 100° $R_F = 20 \text{ k}\Omega$ $R_L$ = 10 $k\Omega$ 80° $C_I = 1 \mu F$ 30 $A_V = -1 \text{ V/V}$ 20 10 Gain 0 -10 10 100 1k 10k 100k 1M f - Frequency - Hz

Figure 44.

#### POWER DISSIPATION/AMPLIFIER vs OUTPUT POWER 80 $V_{DD} = 3.3 V$ 8 Ω 70 60 Amplifier Power - mW 50 40 16 Ω 30 $32^{\prime}\Omega$ 20 **64** Ω 10 0 20 40 80 100 120 140 160 180 0 60 200 Load Power - mW Figure 45.





#### **APPLICATION INFORMATION**

#### GAIN SETTING RESISTORS, R<sub>F</sub> and R<sub>I</sub>

The gain for the TPA112 is set by resistors  $R_F$  and  $R_I$  according to Equation 1.

$$Gain = -\left(\frac{R_F}{R_I}\right) \tag{1}$$

Given that the TPA112 is an MOS amplifier, the input impedance is high. Consequently, input leakage currents are not generally a concern, although noise in the circuit increases as the value of  $R_F$  increases. In addition, a certain range of  $R_F$  values is required for proper start-up operation of the amplifier. Taken together, it is recommended that the effective impedance seen by the inverting node of the amplifier be set between 5 k $\Omega$  and 20 k $\Omega$ . The effective impedance is calculated in Equation 2.

Effective Impedance = 
$$\frac{R_F R_I}{R_F + R_I}$$
 (2)

As an example, consider an input resistance of 20 k $\Omega$  and a feedback resistor of 20 k $\Omega$ . The gain of the amplifier would be -1 and the effective impedance at the inverting terminal would be 10 k $\Omega$ , which is within the recommended range.

For high-performance applications, metal film resistors are recommended because they tend to have lower noise levels than carbon resistors. For values of  $R_F$  above 50  $k\Omega$ , the amplifier tends to become unstable due to a pole formed from  $R_F$  and the inherent input capacitance of the MOS input structure. For this reason, a small compensation capacitor of approximately 5 pF should be placed in parallel with  $R_F$ . In effect, this creates a low-pass filter network with the cutoff frequency defined in Equation 3.

$$f_{co(lowpass)} = \frac{1}{2\pi R_F C_F}$$
 (3)

For example, if  $R_F$  is 100 k $\Omega$  and  $C_F$  is 5 pF then  $f_{co(lowpass)}$  is 318 kHz, which is well outside the audio range.

#### INPUT CAPACITOR, C.

In the typical application, input capacitor  $C_I$  is required to allow the amplifier to bias the input signal to the proper dc level for optimum operation. In this case,  $C_I$  and  $R_I$  form a high-pass filter with the corner frequency determined in Equation 4.

$$f_{co(highpass)} = \frac{1}{2\pi R_I C_I}$$
 (4)

The value of  $C_l$  is important to consider, as it directly affects the bass (low-frequency) performance of the circuit. Consider the example where  $R_l$  is 20 k $\Omega$  and the specification calls for a flat bass response down to 20 Hz. Equation 4 is reconfigured as Equation 5.

$$C_{I} = \frac{1}{2\pi R_{I} f_{co(highpass)}}$$
 (5)

In this example,  $C_l$  is 0.4  $\mu F$ , so one would likely choose a value in the range of 0.47  $\mu F$  to 1  $\mu F$ . A further consideration for this capacitor is the leakage path from the input source through the input network  $(R_l, C_l)$  and the feedback resistor  $(R_F)$  to the load. This leakage current creates a dc offset voltage at the input to the amplifier that reduces useful headroom, especially in high-gain applications (> 10). For this reason a low-leakage tantalum or ceramic capacitor is the best choice. When polarized capacitors are used, the positive side of the capacitor should face the amplifier input in most applications, as the dc level there is held at  $V_{DD}/2$ , which is likely higher that the source dc level. It is important to confirm the capacitor polarity in the application.



#### **APPLICATION INFORMATION (continued)**

### POWER SUPPLY DECOUPLING, Cs

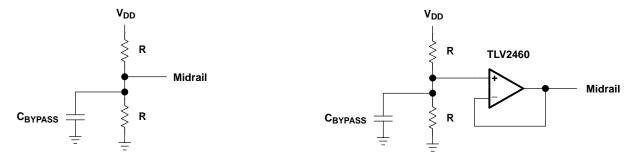
The TPA112 is a high-performance CMOS audio amplifier that requires adequate power supply decoupling to ensure that the output total harmonic distortion (THD) is as low as possible. Power supply decoupling also prevents oscillations for long lead lengths between the amplifier and the speaker. The optimum decoupling is achieved by using two capacitors of different types that target different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series-resistance (ESR) ceramic capacitor; typically, 0.1  $\mu$ F, placed as close as possible to the device  $V_{DD}$  lead, works best. For filtering lower frequency noise signals, a larger aluminum electrolytic capacitor of 10  $\mu$ F or greater placed near the power amplifier is recommended.

#### **MIDRAIL VOLTAGE**

The TPA112 is a single-supply amplifier; so, it must be properly biased to accommodate audio signals. Normally, the amplifier is biased at  $V_{DD}/2$ , but it can actually be biased at any voltage between  $V_{DD}$  and ground. However, biasing the amplifier at a point other than  $V_{DD}/2$  reduces the amplifier's maximum output swing. In some applications where the circuitry driving the TPA112 has a different midrail voltage, it might make sense to use the same midrail voltage for the TPA112, and possibly eliminate the use of the dc-blocking capacitors.

The two concerns with the midrail voltage source are the amount of noise present and its output impedance. Any noise present on the midrail voltage source that is not present on the audio input signal will be input to the amplifier, and passed to the output (and increased by the gain of the circuit). Common-mode noise is cancelled out by the differential configuration of the circuit.

The output impedance of the circuit used to generate the midrail voltage needs to be low enough so as not to be influenced by the audio signal path. A common method of generating the midrail voltage is to form a voltage divider from the supply to ground, with a bypass capacitor from the common node to ground. This capacitor improves the PSRR of the circuit. However, this circuit has a limited range of output impedances; so, to achieve low output impedances, the voltage generated by the voltage divider is fed into a unity-gain amplifier to lower the output impedance of the circuit.



- a) Midrail Voltage Generator Using a Simple Resistor-Divider
- Buffered Midrail Voltage Generator to Provide Low Output Impedance

Figure 47. Midrail Voltage Generator

If a voltage step is applied to a speaker, it causes a noise pop. To reduce popping, the midrail voltage should rise at a subsonic rate. That is, a rate less than the rise time of a 20-Hz waveform. If the voltage rises faster than that, there is the possibility of a pop from the speaker.

Pop can also be heard in the speaker if the midrail voltage rises faster than the charge of either the input coupling capacitor or the output coupling capacitor. If midrail rises first, the charging of the input and output capacitors is heard in the speaker. To keep this noise as low as possible, the relationship shown in Equation 6 should be maintained.



#### **APPLICATION INFORMATION (continued)**

$$\frac{1}{\left(C_{B} \times R_{SOURCE}\right)} \le \frac{1}{\left(C_{I}R_{I}\right)} \ll \frac{1}{R_{L}C_{C}}$$
(6)

Where  $C_{BYPASS}$  is the value of the bypass capacitor, and  $R_{SOURCE}$  is the equivalent source impedance of the voltage divider (the parallel combination of the two resistors). For example, if the voltage divider is constructed using two 20-k $\Omega$  resistors, then  $R_{SOURCE}$  is 10 k $\Omega$ .

#### MIDRAIL BYPASS CAPACITOR, CB

The midrail bypass capacitor  $C_B$  serves several important functions. During start-up,  $C_B$  determines the rate at which the amplifier starts up. This helps to push the start-up pop noise into the subaudible range (so slow it can not be heard). The second function is to reduce noise produced by the power supply caused by coupling into the output drive signal. This noise is from the midrail generation circuit internal to the amplifier. The capacitor is fed from the resistor divider with equivalent resistance of  $R_{SOURCE}$ . To keep the start-up pop as low as possible, the relationship shown in Equation 7 should be maintained.

$$\frac{1}{\left(C_{B} \times R_{SOURCE}\right)} \le \frac{1}{\left(C_{I}R_{I}\right)} \tag{7}$$

As an example, consider a circuit where  $C_B$  is 1  $\mu F$ ,  $R_{SOURCE}$  = 160  $k\Omega$ ,  $C_I$  is 1  $\mu F$ , and  $R_I$  is 20  $k\Omega$ . Inserting these values into the Equation 8 results in:

$$6.25 \le 50 \tag{8}$$

which satisfies the rule. Recommended values for bypass capacitor  $C_B$  are 0.1  $\mu F$  to 1  $\mu F$ , ceramic or tantalum low-ESR, for the best THD and noise performance.

#### **OUTPUT COUPLING CAPACITOR, Cc**

In the typical single-supply, single-ended (SE) configuration, an output coupling capacitor ( $C_C$ ) is required to block the dc bias at the output of the amplifier, thus preventing dc currents in the load. As with the input coupling capacitor, the output coupling capacitor and impedance of the load form a high-pass filter governed by Equation 9.

$$f_{(out high)} = \frac{1}{2\pi R_L C_C}$$
(9)

The main disadvantage, from a performance standpoint, is that the typically small load impedances drive the low-frequency corner higher. Large values of  $C_C$  are required to pass low frequencies into the load. Consider the example where a  $C_C$  of 68  $\mu F$  is chosen and loads vary from 32  $\Omega$  to 47  $k\Omega$ . Table 1 summarizes the frequency response characteristics of each configuration.

Table 1. Common Load Impedances vs Low Frequency
Output Characteristics in SE Mode

R <sub>L</sub>	c <sub>c</sub>	LOWEST FREQUENCY
32 Ω	68 μF	73 Hz
10,000 Ω	68 μF	0.23 Hz
47,000 Ω	68 μF	0.05 Hz

As Table 1 indicates, headphone response is adequate and drive into line level inputs (a home stereo for example) is good.

The output coupling capacitor required in single-supply, SE mode also places additional constraints on the selection of other components in the amplifier circuit. With the rules described earlier still valid, add the following relationship:

#### • Output Pulldown Resistor, R<sub>C</sub> + R<sub>O</sub>

 Placing a 100-Ω resistor, R<sub>C</sub>, from the output side of the coupling capacitor to ground ensures the coupling capacitor, C<sub>C</sub>, is charged before a plug is inserted into the jack. Without this resistor, the coupling capacitor would charge rapidly upon insertion of a plug, leading to an audible pop in the headphones.



– Placing a 20-k $\Omega$  resistor, R<sub>O</sub>, from the output of the IC to ground ensures that the coupling capacitor fully discharges at power down. If the supply is rapidly cycled without this capacitor, a small pop may be audible in 10-k $\Omega$  loads.

#### Using Low-ESR Capacitors

- Low-ESR capacitors are recommended throughout this application. A real capacitor can be modeled simply as a resistor in series with an ideal capacitor. The voltage drop across this resistor minimizes the beneficial effects of the capacitor in the circuit. The lower the equivalent value of this resistance, the more the real capacitor behaves like an ideal capacitor.

#### **5-V VERSUS 3.3-V OPERATION**

The TPA112 is designed for operation over a supply range of 2.5 V to 5.5 V. This data sheet provides full specifications for 5-V and 3.3-V operation because these are considered to be the two most common standard voltages. There are no special considerations for 3.3-V versus 5-V operation as far as supply bypassing, gain setting, or stability. The most important consideration is that of output power. Each amplifier in the TPA112 can produce a maximum voltage swing of  $V_{DD}-1$  V. This means, for 3.3-V operation, clipping starts to occur when  $V_{O(PP)}=2.3$  V, as opposed to  $V_{O(PP)}=4$  V for 5-V operation. The reduced voltage swing subsequently reduces maximum output power into the load before distortion begins to become significant.



#### PACKAGE OPTION ADDENDUM

10-Dec-2020

#### PACKAGING INFORMATION

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Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
TPA112D	ACTIVE	SOIC	D	8	75	RoHS & Green	NIPDAU	Level-1-260C-UNLIM		TPA112	Samples
TPA112DR	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM		TPA112	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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10-Dec-2020

### **PACKAGE MATERIALS INFORMATION**

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#### TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPA112DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

www.ti.com 5-Jan-2022



#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPA112DR	SOIC	D	8	2500	350.0	350.0	43.0

### PACKAGE MATERIALS INFORMATION

www.ti.com 5-Jan-2022

#### **TUBE**



#### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
TPA112D	D	SOIC	8	75	505.46	6.76	3810	4



SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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